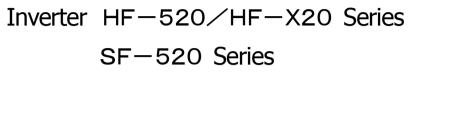
Sumitomo Drive Technologies



Engineering Tool for PC SDWP001 Operating Manual



Sumitomo Heavy Industries, Ltd.

Manual No. DM2308E-1

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Safety Symbols and Markings

The following conventions are used to indicate and classify safety precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

Important

Indicates a property damage message.

Safety Notes and Instructions

Below is a list of important wiring instructions that must be followed carefully for safety and proper performance:

Cautionary Notes on Wiring

ANote
Use the proper cable when connecting the drive and SDWP001.
Close and restart SDWP001 if the cable is inserted during a session of SDWP001.
Using any other type of cable will void the warranty for the drive and software.

Notes on Use

ANote

Close and restart SDWP001 if the power to the drive is turned off and then turned on. Failing to do so will void the warrantee for the drive and software.

Manual Overview

This manual has been written for those using SDWP001. Information covered in this manual includes:

- · An overview of all functions used in SDWP001
- Instructions for installing and uninstalling SDWP001.

Related Manuals

Detailed technical documentation is available on Sumitomo drives and various drive options. Refer to this other documentation as needed.

Make sure that you have a proper understanding of all product specifications and restrictions when using this product.

Notes on Data Communications

Important

SDWP001 is not for use with any other communication-related devices not specified in this manual. Do not make any modifications to the drive, operator, software, or MEMOBUS/Modbus data. Use of any other communication devices will involve data that does not agree or comply with SDWP001 programming, and may not operate properly.

About this Software

Notes on Usage

- This software is for installation to a single computer only. Authorization is required for use on another computer
- · It is strictly forbidden to copy the software for any purpose other than as backup
- · It is strictly forbidden to reverse compile or reverse engineer this software
- · It is strictly forbidden to loan, exchange, or trade this software to a third party
- Sumitomo Heavy Industries, Ltd. possesses all rights of copyright protection related to this software.

Operating System and Trademarks

- · Windows 7 registered trade marks of Microsoft Incorporated.
- · Adobe Reader is a registered trademark of Adobe Systems Incorporated.
- Pentium is a registered trademark of Intel Corporation.
- Ethernet is a registered trademark of Xerox Corporation.
- · InstallShield is a registered trademark of InstallShield Software Corporation.
- · Registered trademarks used in this manual do no appear with TM and ®.

1 System Overview

This section provides an overview of SDWP001 and various features of the software

<Applicable Inverter>

HF-520 (Standard Series)	0.2~7.5 kW
HF-X20 (Flame-Proof [d2G4] Series)	0.2~3.7 kW
SF-520 (Standard Series)	0.1~2.2 kW

<Applicable PC communications cable>

Model : WV103 (RS-232C interface) ···· Cable Length 3m When connecting with a USB port of the PC, please prepare a USB to RS-232C change cable

1.1 SDWP001 Overview and Functions

SDWP001 is the powerful engineering tool designed for advanced application setup and for performing maintenance tasks on the Sumitomo drive (Inverter).

The advanced functionality of SDWP001 assists all users with powering up the drive, test running the application, or performing maintenance.

Main functions:

- · Editing parameters while taking advantage of useful help information
- Displaying drive operation status (I/O signals, internal status information, etc.) as well as product information
- · Troubleshooting features, including possible causes for problems and other help options
- Test running the drive and application (both manual and pattern operation)
- Oscilloscope function.

NOTE: Some SDWP001 functions may not be applicable for the specific drive model being used. Such functions will not be available when displayed in the menu toolbars.

There are following way to connect the drive to SDWP001.

Normal Connection (Drive Only)

Connects the drive directly to SDWP001 using an RS-232C communications cable. To connect a different drive, unplug the communications cable from the drive that is currently connected and connect it to the other drive.

1.2 System Environment

System requirements for running SDWP001 are listed in the table below:

nnatible PCs			
PC/AT DOS/V compatible PCs			
*Sumitomo will not provide support when using NEC PC9821 series computers.			
higher (1.6 G	Hz recommended)		
00 MB recom	mended at time of installation)		
XGA monitor (at least 1024 × 768 set for small fonts)			
it) or higher			
se OS			
OS compatible with 32-bit and 64-bit memory			
•Windows 7			
The operation can not be guaranteed in other OS.			
Sumitomo provides a RS-232C communications cable. (Option)			
odel	Cable Model		
	Modular Connector Type		
	WV103(Cable Length 3m)		
•SI-232/JC-H option card required if using SF-520.			
When connecting with a USB port of the PC, please use a USB to RS-232C change			
cable.			
Environment in which the Internet can connect (for installation only)			
ader 6.0			
aying Help inf	formation		
	higher (1.6 G 00 MB recom ast 1024 × 76 it) or higher se OS n 32-bit and 6 not be guara s a RS-232C odel on card requir with a USB po ich the Interna		

- NOTE: To install and uninstall SDWP001, the user must be logged in with administrator rights.
- NOTE: Windows 7 user should take note of the following: Multiple users cannot log in simultaneously; only one user is allowed at a time.
- NOTE: Some security and virus software may interfere with SDWP001 and keep it from starting properly.

1.3 Installing SDWP001

Executing the SDWP001 installation program will install the software. All files needed to install the software are included on the download file. For proper software installation, be sure that all other programs have been closed.

NOTE: To install SDWP001, the user must be logged in with administrator rights.

Follow the instructions below to install SDWP001:

- 1) Download the file from our web site ' http://cyclo.shi.co.jp/'.
- 2) From Windows® Explorer, open the folder then double-click on "SETUP.EXE".
- The Language selection dialog box will appear. Select the appropriate language (Japanese or English).

hoose 9	ietup Languag	e			>
ETI	Select the lar	nguage for th	his installation from	n the choices be	low.
E.	(A)				
	English (United	States)		×	
	1	ОК	Cancel	1	

4) Click "OK" and SDWP001 will prepare the InstallShield Wizard and then launch the InstallShield Wizard for SDWP001.

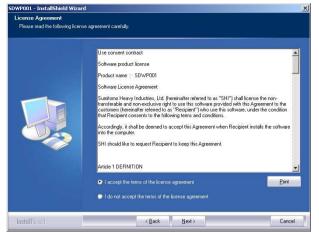
InstallShield Wizard	
	Preparing to Install
0	SDWP001 Setup is preparing the InstallShield Wizard, which will guide you through the program setup process. Please wait.
States and states	Preparing to Install
	_
Conservation of the	
	Cancel

Click the button marked, "Next" to begin installation.



5) America software license agreement.

You must accept the terms to proceed with the installation. Click "Next" to continue.

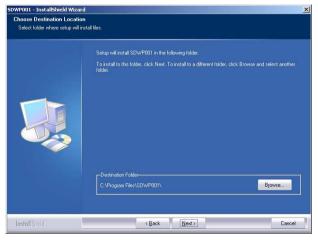


6) Enter the user information into the required fields.

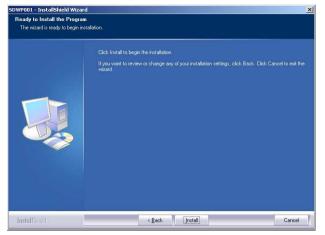
The User Name and company information are required for installation, registration, and use of the software. Click "Next" after the data has been entered.

User Name: Jac Company Name: Sumdomd Instal this application for: Anyone who uses this computer (all user) Drivy for me (gec)	Sustomer Information Please enter your information	
		Tiso Company Name: Sumtomol Install this application foc. ♥ Anyone who uses this computer (all users)

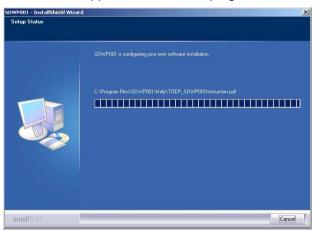
 SDWP001 asks for the software installation path. The default path will appear as: C: Program Files¥Sumitomo¥SDWP001¥. Click "Next".



8) Once SDWP001 is ready to be installed, a message will appear to indicate that installation preparations are complete. Click "Install" to install the software.



9) The required files will be installed and copied to the designated directory. A window will appear to indicate the progress of installation.



10) A message will appear to indicate that installation is complete. Click "Finish" to close the window.



NOTE: A message may appear indicating that the PC requires restart for proper SDWP001 installation. Follow the instructions and restart the computer.

1.4 Uninstalling SDWP001

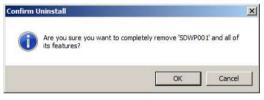
NOTE: Administrator privileges are required to uninstall SDWP001. Log in as the administrator to uninstall SDWP001.

Follow the procedure below to uninstall SDWP001:

- 1) Open the Start menu in the Windows Task Bar.
- 2) Click "Control Panel" and open the Control Panel folder.
- 3) Double-click on the "Program and Features" icon to open the following window:

Control Panel Home View installed updates Turn Windows features on or		r change a program program, select it from the list and then cl	ick Uninstall <mark>,</mark> Cl	nange, or Repair	G
off	Organize 🔻 Ur	install			
	Name	Publisher	Installed On	Size	Version
	SDWP001	Sumitomo Heavy Industries, Ltd.	12/3/2015	100 MB	1.00

4) Select SDWP001 and click "Remove". The following message will appear:



 Click "OK" to execute the uninstall shield. When the program has been uninstalled, the following message will appear:

5DWP001 - InstallShield Wizard	
	Uninstall Complete InstalSheld W.card has finished unristaling SDWP001,
InstallShield	< Back Cancel

6) Click "Finish".

2 Starting SDWP001

Follow the directions below to start using SDWP001:

2.1 Starting the Program

There are three ways to start a session of SDWP001:

- · from the Start menu
- from a shortcut
- by double-clicking on a Project file.

	SDWP001 HF-520 / HF-X20 Series SF-520 Series
Sumitomo Drive Technologies	

2.1.1 Starting from the Start Menu

Follow these instructions to open SDWP001 from the Start menu:

- 1) Open the Start menu in the Windows task bar.
- 2) Go to the Programming menu and open the Programming folder.
- 3) Open the folder marked "Sumitomo Inverter".
- 4) Select "SDWP001".

2.1.2 Starting from a Shortcut

Double-click on the shortcut marked "SDWP001".

2.1.3 Double-clicking on a Project File

SDWP001 can be opened by double-clicking on a Project file.

- 1) Open up Windows Explorer
- 2) Double-click on a Project file icon.

NOTE: A Project file saved to the desktop can also be used to open a session of SDWP001 by double-clicking on that icon.

2.2 Connecting the Drive and PC via the Com Port

When SDWP001 is first opened, the start up window shown below will appear on the computer monitor.

SDWP001			
Elle View Connect Help			
	🖆 🔁 🗓 🗉 🖾 🕍 😵 🕻	P 💿 I 🔹 🖸 📰 🗺 🚺 📕	
	1 2 = 1 2 = 0		
			1
Function Tree + # ×	Connect	×	All Monitor + 4 ×
Drive			Category All - II
- I Parameter Edit		×	Parameter NU. Name
Direct Parameter edit Monitor			
맞h All Monitor	Connect	Cancel	
User monitor	. house and the second se		
Status Monitor	communication interface	<u> </u>	
Movement Monitor	COM		
Visual Monitor			
-== 🔂 Test Run	Connect Setting Port		
🖓 Manual Run	Port	COM1 💌	
Trouble Shooting	Media	Single C Search	
	Address	001	
	Protocol Setting	•	
			User monitor 문All Monitor
(D) Ready			CAP NUM SCRL //

The first window to appear asks if the user would like to connect to a drive or open up a Project file.

Connect	×	Connect	<u>></u>
Connect	Open Project File	Connect	Open Project File
COM	*	COM	e *
		7	
Connect Setting	· · · · · · · · · · · · · · · · · · ·	Connect Setting	14
Port	COM1 V	Port	COM1
Port Media	COM1 💌		COM1 💌
		Port	
Media	Single C Search	Port Media	Single C Search
Media Address	Single C Search	Port Media Address	Single C Search
Media Address	Single C Search	Port Media Address Protocol Settino.	Single C Search 001 ▼
Media Address	Single C Search	Port Media Address Protocol Settino BPS Selection	Single C Search O01 Search 9600bps

Connect: PC connects to the drive to edit parameters and perform test run. Open Project File: Drive does not necessarily need to be connected to edit a project file. To connect a drive, SDWP001 requires that certain data be entered for the "Connect Setting" and "Protocol Setting". 1) Specify the Connect Setting

Port

Selects the com port for drive connection. SDWP001 will list the com ports available for the PC being used. This display will vary by PC.

Media

Selects the media for setting the com address: Search or Single. If you know the com address, enter it here. If not, select "Search" and SDWP001 will automatically search for the address.

Address

Sets the com address for drive parameter settings. This setting will be grayed out when "Search" has been selected for the media.

 Selecting the Protocol Setting Sets the communication speed for drive and PC.

BPS Selection 9600bps

Parity Selection None

Data Length 8 bit

Stop bit

1 bit

3) Select "Connect"

SDWP001 will attempt to connect to the drive. If select "Search", data of the connected drive will appear when the connection is completed.

If select "Single", SDWP001 main screen will appear when the connection is completed.

2.3 Connecting the Drive and PC

When the "Media" connection setting discussed in the previous section is set for search detection, SDWP001 will automatically search all serial ports for any connections.

If SDWP001 detects that drive is connected, the following window will appear, showing the models and addresses of all drives that are connected.

Address	Inverter	
1	HF-520 (AF Motor)	
2 3	HF-520 (AF Motor)	
3	HF-520 (AF Motor)	
4	HF-520 (AF Motor)	
5	HF-520 (AF Motor)	
6	HF-520 (AF Motor)	
-	··	
		1 22

Use the window above to select which drive the current session of SDWP001 will focus on and click "OK". Clicking on "Cancel" will cause the following window to appear:

	ł		
	Connect	Open Project File	
communi COM	cation interface		
STORAGE AND A STORAGE			
COM		COM1	
COM		COM1 © Single C Search	

If SDWP001 is unable to communicate with the drive, the window above will not appear and the following message will be displayed instead:



Regardless of whether the drive is connected to the PC, this message may appear if SDWP001 is unable to properly communicate with the drive.

If the drive selection screen fails to appear, check the items listed in the table below:

Check	Comments
Is the power supply on?	Check the power supply.
Is there a loose connection	Make sure the com cable and the connector are properly
somewhere?	fastened to the correct ports.
Is the correct com port selected?	The com cable should be connected to the same port specified
is the correct corrigin point selected?	in the Connect window.
	RS-232C
Is the com address correct?	Make sure the com address that is set and the one you are
	trying to connect to are the same.
	Notebook PCs may not supply enough power to the RS-232C
Is the RS-232C port enabled?	port. Check the setting for the power supplied to the C port.
	Refer to the PC user's manual for information on setting the
	power supply.
	PC batteries may not supply the type of power needed for
Is the PC operating from a battery?	communications.
	Try switching to an AC power supply.
Is the wiring correct?	Check for correct wiring using the instructions that came with
	the com cable and the instruction manual for the drive.
	 Try shortening the length of the com cable
Is the com cable the proper length?	Use a twisted pair shielded line
	Check the length of the com cable (RS-232C: 3 m max).

If SDWP001 still has difficulty connecting to the drive after verifying all of the items listed above, check the following:

Are the communication-related parameters in the drive set for use with SDWP001?

Remember that any changes to communication-related parameters in the drive require that power be cycled in the drive for those new setting changes to take effect.
 Proper cycling of power means that LED indicators on the operator must completely extinguish before the power supply back on.

2.4 Managing Project Files

Data handled by SDWP001 is organized into a Project. Users can assign names to a Project.

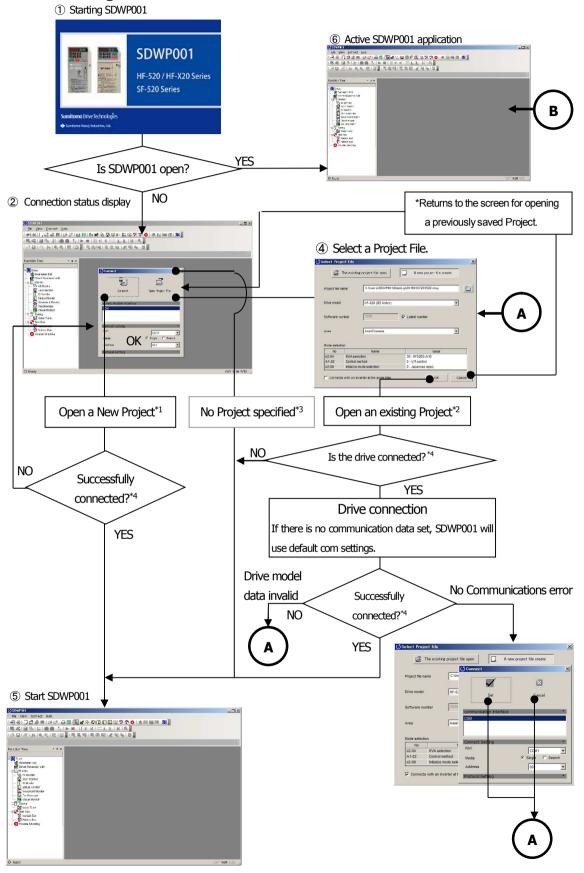
A Project stores all connection data, drive functions, and data that have been edited into a single file to facilitate data tracking and portability.

The flowcharts in the next section outline starting SDWP001, creating a Project, and quitting the program.

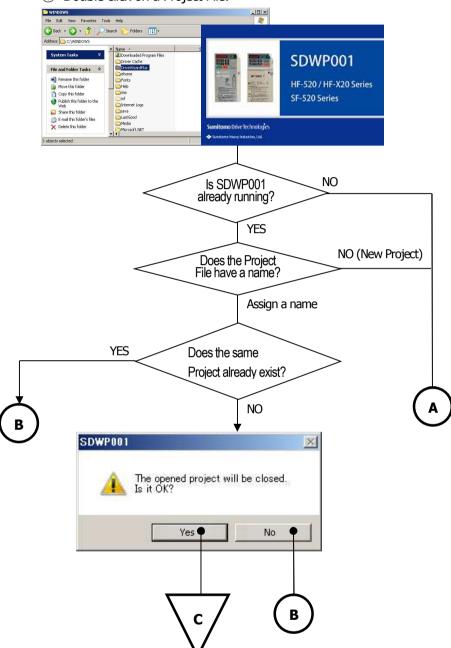
*1	New Project :	SDWP001 creates a new Project file and automatically assigns default values to all parameters. The Project must be given a name when it is saved.
*2	Pre-existing Project :	The user selects a Project that was saved earlier.
*3	No Project :	 No Project file is opened. No data will be displayed and no parameters can be edited. No child windows (such as the Parameter Edit window, etc.) will be displayed. If any docking windows are open, they will not display any data or drive model information. Software functions will become enabled once a Project is opened or once SDWP001 connects to the drive.

*4 Once a Project has been opened, double check that the drive model information is correct.

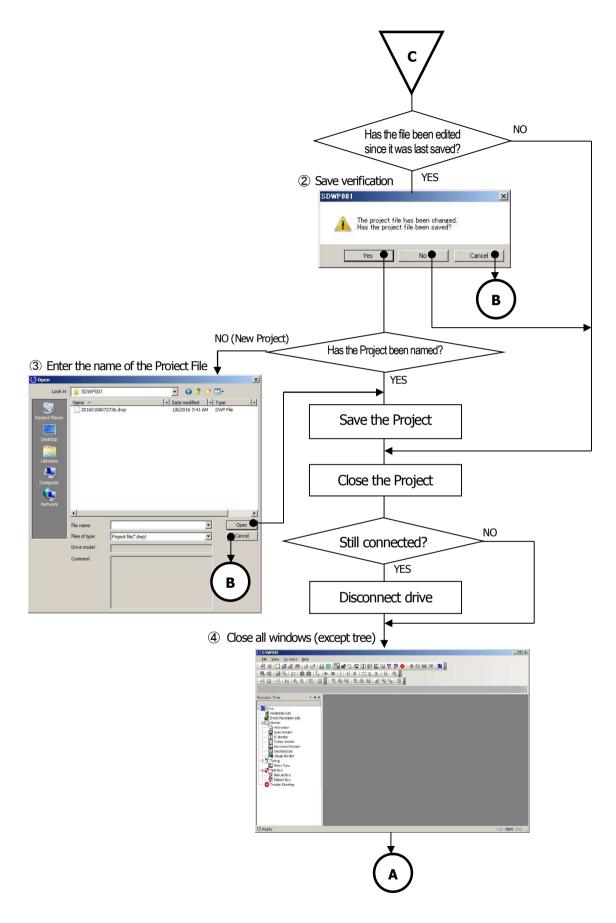
2.4.1 Starting SDWP001



2.4.2 Double-clicking on a Project File from Windows Explorer

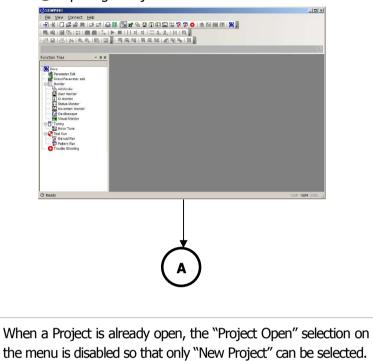


1 Double click on a Project File.



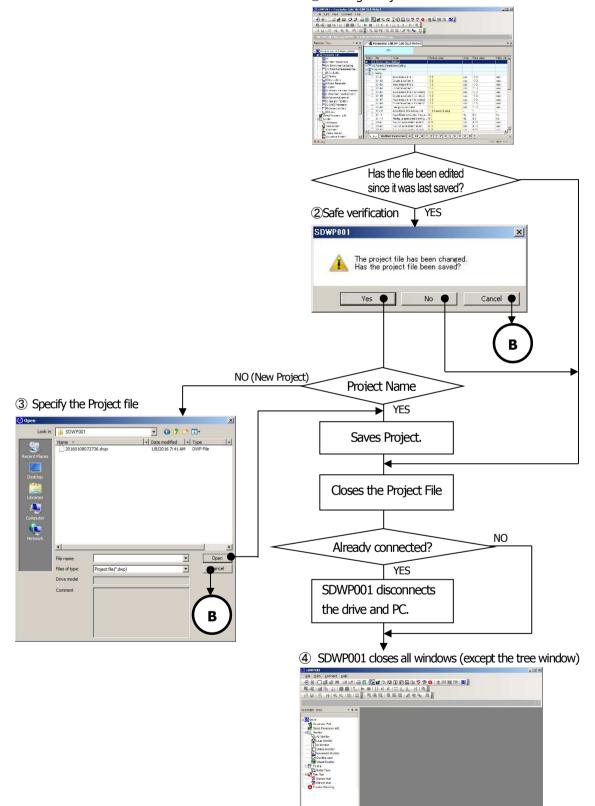
2.4.3 Opening a Project File

① Opening a Project File

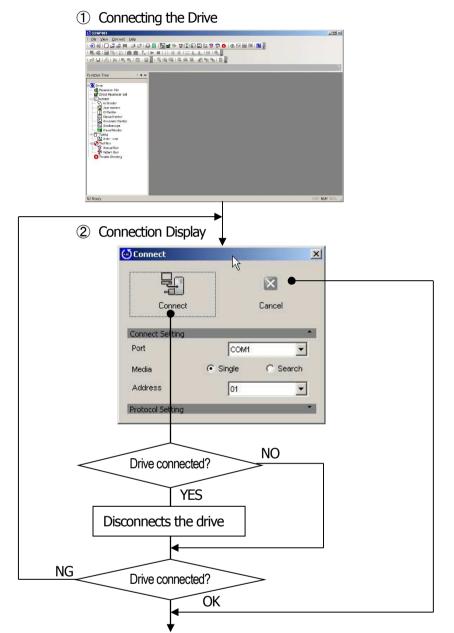


2.4.4 Closing a Project File

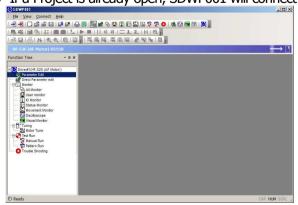




2.4.5 Connecting the Drive to the PC

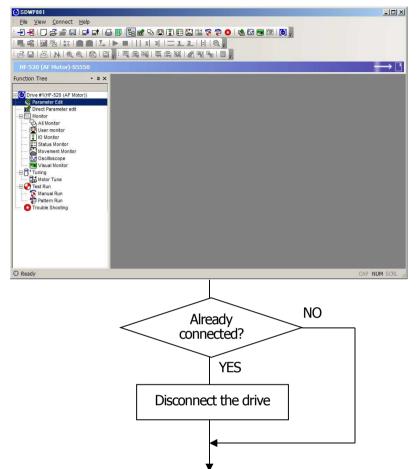


3 If a Project is already open, SDWP001 will connect with the file open.

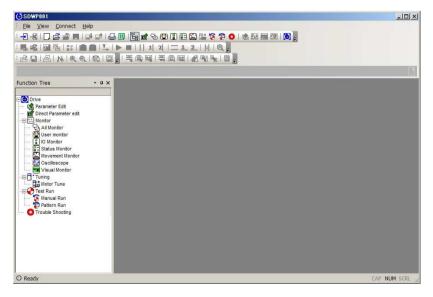


2.4.6 Disconnecting the Drive

① Disconnecting the drive

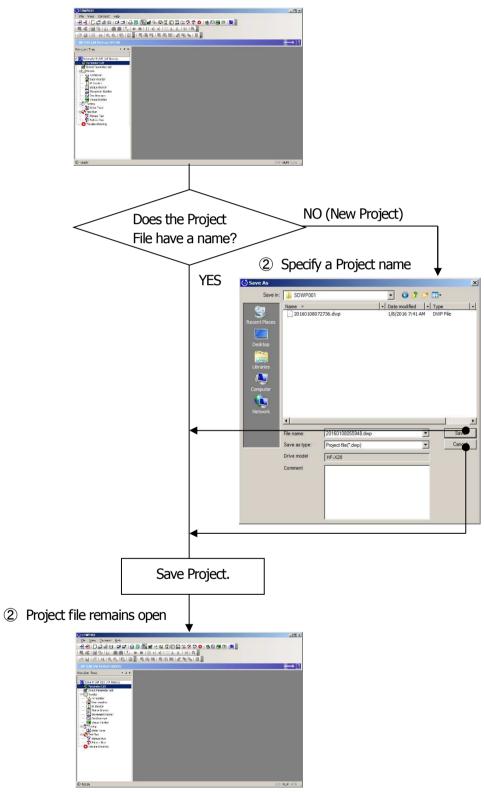


② If a Project File is open, SDWP001 will disconnect the drive and leave the file open.



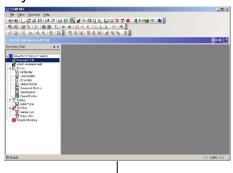
2.4.7 Saving a Project File

① Saving a Project File



2.4.8 Save Project File AS

① Saving a Project

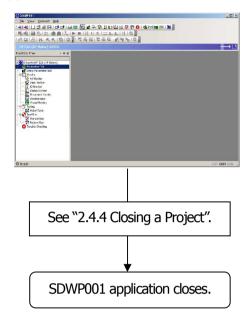


② Enter the Project file name

@ R:20

	🔁 Save As					×
	Save in:	SDWP001		-	G 🔊 😕 🛙	
		Name A			modified + 1	
	1 (St. 1977)	2016010807	2736.dwp			WP File
	Recent Places					
	Desktop					
	Ceskup					
	1000					
	Libraries					
	Computer					
	 (a) 					
	Network					
	network	-				
		<u>•</u>	Sec			
		File name:	20160108055948.	dwp	-	Save
		Save as type:	Project file(*.dwp)		-	Cancel
		Drive model	HF-X20			
			111-020			
		Comment				
			1			
						,
				<u> </u>	C 'I	
		Sav	ves the I	Project	: file	
						-
				┫		
_						
3 Returns	s to the	open P	roiect			
		openti				
	SDWP101					포토 포
	: She Yew Com : 관리 네 니 그 : :	E 🖬 🖬 🖬 🖬 🖥 🖹		27 O 38 Ed 10 Ed	120	
	風感園園		1 2 = 조 2 특징 특히토 선원적	e.		
	HE-520 (AF Mot	or)-55550	-9 28 04 04 14 18 19 19	91 444 🛐		> [!]
	Function Tree	- = ×				
	E Drivertiger 120	(AF fileter))				
	B Direc Paramet	ter ect				
	Ve Al Nonter	e. 👘				
	- Statue Vorm	for /arsha				
	Visual Monit	с Ц1				
	Hitsh Ra					
	Cree First 20 Cree Howstone 40 Cree Ho					

2.4.9 Quitting the Application



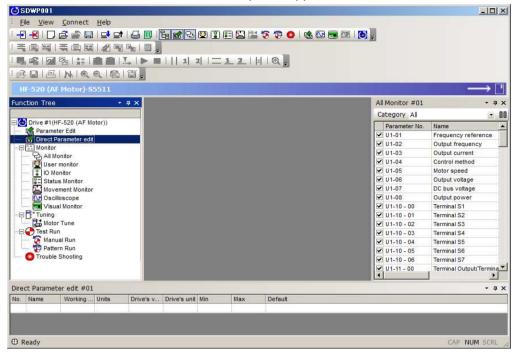
2.4.10 Managing Project Files with the Menu

	Situation	Project alr	eady open	Project not y	et opened
Menu		Drive	Not	Drive	Not
		Connected	Connected	Connected	Connected
2.4.2	Creating a New Project	×	×	0	0
2.4.3	Opening a Project File	×	×	0	0
2.4.4	Closing a Project	0	0	×	×
2.4.5	Connecting to the Drive	×	0	×	0
2.4.6	Disconnecting the Drive	0	×	0	×
2.4.7	Saving a Project	0	0	×	×
2.4.8	Saving a Project As	0	0	0	×
2.4.9	Quit	0	0	0	0

O: Selection possible, ×: Selection not possible.

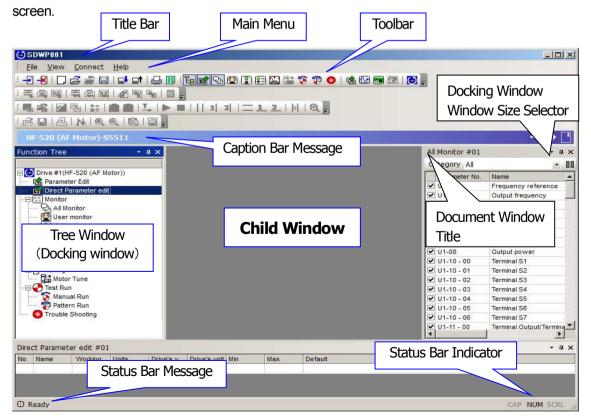
3 SDWP001 Main Screen

The main screen when SDWP001 is first opened appears below.



3.1 Screen Construction

The illustration below indicates the various windows, tabs, and toolbars that appear in the main



3.1.1 Title Bar

The title bar in SDWP001 shows all active child windows.

SDWP001				
ł	<u>F</u> ile	<u>V</u> iew	<u>Connect</u>	<u>H</u> elp

When no child windows are displayed

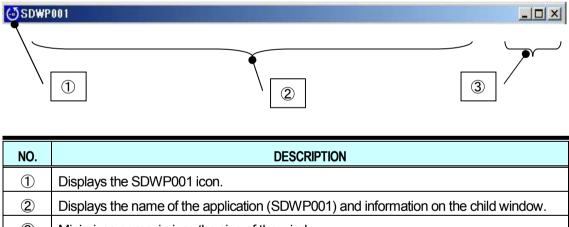
SDWP001 - Parameter Edit #01 Elle Edit View Connect Help

When the Parameter Display Screen is open as a child window

C	🔄 SDWP001 - Oscilloscope #01					
	Eile	Edit	View	Connect	Monitor	Help

When the Oscilloscope Display is open as a child window

The title bar appears below:



③ Minimizes or maximizes the size of the window.

3.1.2 Main Menu

Options available in the Main Menu in SDWP001 appear below.

<u>(1) Menu</u>

MENU	DESCRIPTION
	For reading and writing data from a Project, displaying drive information, as well as
File (<u>F</u>)	importing and exporting files.
	This menu becomes available when using the Parameter Edit and Oscilloscope
Edit (<u>E</u>)*1	windows.
	*This menu is not available when not using a corresponding child window.
View (<u>V</u>)	Determines which function windows are displayed or not displayed.
Connection (C)	For connecting and disconnecting the drive.
Manitar (NA)*1	For starting and stopping to trace drive performance with the Oscilloscope.
Monitor (<u>M</u>)*1	*This menu is available only when using the Oscilloscope function.
Tools $(\underline{T})^{*1}$	Opens the tools related to the current task.
Help (<u>H</u>)	Displays Help information, including the manual, drive data, and software version data.

*1: For a more detailed description of Menu items, see the description for each function that follows.

<u>(2) File Menu</u>

SUBMENU	DESCRIPTION
Create New Project (N)	Creates a new Project.
Open Project (<u>O</u>)	Open a Project that was saved earlier.
Save Project (S)	Saves the current Project.
Save Project As (<u>A</u>)	Saves the current Project under a new or different name
Close Droject (L)	Closes the current Project.
Close Project (<u>L</u>)	Closing a Project will disconnect the drive if connected.
Drive Data (<u>T</u>)	Displays data from the drive when the drive is connected.
Import (<u>I</u>)	Imports items as selected in the active window.
Export (E)	Exports items selected in the active window.
Export (<u>E</u>)	CSV format, etc., you can choose the format of the saved file.
Print Settings (P)	Changes settings for print out.
Environment estur ()()	For various program environment settings (how data is saved, use of
Environment setup (\underline{V})	filters, etc.).
(Project History)	Displays a list of the five most recently opened Projects.
Quit (<u>X)</u>	Close the current session of SDWP001

(3) Display Menu

SUBMENU	SELECTION	DESCRIPTION
Function Tree	0	Displays the Function Tree.
Direct Parameter Edit	0	Opens the Direct Parameter Edit window.
All Monitors	0	Displays all monitors.
User Monitor	0	Displays user monitors only.
I/O Monitor	0	Displays the input and output monitors.
Status Monitor	0	Displays the Status Monitor.
Operation Monitor	0	Displays the Operation Monitor.
Manual Operation	0	Displays the window for performing Manual Run.
		*This function cannot be used when connected to an upper controller.
Pattern Operation	0	Displays the window for performing Pattern Run.
		*This function cannot be used when connected to an upper controller.
Troubleshooting	0	Shows the Troubleshooting window.
Results List	0	Displays the results after comparing parameters.
Drive Replacement	0	Displays the function for replacing the drive with a different model.
Conversion Results	0	Displays the results after performing a Parameter Conversion.
		*Unused menu
Visual Monitor	-	Displays the Visual Monitors.
		*Exclusive functions for the HF-520 and HF-X20 series
Parameter Edit	-	Opens the window for editing parameters.
Oscilloscope	-	Displays the Oscilloscope window.
Toolbar (<u>T</u>)	_	Displays or hides the toolbar.
Standard (<u>S</u>)	0	Displays or hides the standard toolbar.
Parameter Edit (<u>E)</u>	0	Displays or hides the toolbar for editing parameters.
Oscilloscope (<u>O</u>)	0	Displays or hides the Oscilloscope toolbar.
Customize (<u>C</u>)	—	Opens the window for customizing the menu and toolbar.
Language ^{*2}	-	For selecting which language to display.
<u>E</u> nglish	_	Displays English only.
		English is not displayed when English has been selected.
Japanese	_	Displays Japanese language settings.
		Japanese is not displayed when Japanese has been selected.

*2: Changing the Language Selection requires restarting SDWP001.

(4) Connect Menu

SUBMENU	DESCRIPTION
Connect Inverter (C)	Connects the drive to the PC.
	*If already connected, this selection will read, "Reconnect (R)".
Disconnect Inverter	Disconnects the drive that is currently connected.
	*This selection is only available when a drive is connected.

<u>(5) Help Menu</u>

SUBMENU DESCRIPTION	
SDWP001 Manual (M)	Opens the instruction manual for SDWP001.
Version Data (A)	Displays the version of SDWP001 currently installed.

(6) Edit Menu (Parameter Edit)

Submenu	Description	
Write selected parameters (S)	Writes the value for the selected parameters to the drive.	
Write group (G)	Writes the setting values for the entire group of parameters selected to the drive.	
Select All Parameters (<u>A</u>)	Writes the setting values for all parameters to the drive.	
Read selected parameters (<u>E</u>)	Read the parameters selected from the drive that is connected.	
Read Group (<u>R</u>)	Reads the specified group of parameters from the drive.	
Read All Parameters (L)	Reads all parameters from the drive.	
Drive initialized (<u>I</u>)	Initializes the drive.	
Drive Compare (<u>C</u>)	Compares parameters settings in the current Project with parameter settings stored in the drive that is connected. This option is disabled when no drive is connected.	
File Compare (<u>F</u>)…	Compares the parameter settings in the current Project with another Project or parameter file.	
Comment Edit (<u>D</u>)	Opens the Comment Edit window.	

3.1.3 Toolbars

A list of toolbars in SDWP001 appears below.

Standard Toolbar

ICON	FUNCTION
-	Connects to the drive.
×	Disconnects the drive.
	Creates a new Project.
đ	Opens an existing Project.
í	Closes the Project currently open.
	Saves the Project.
	Imports the data selected.
⊒1	Exports the data selected.
4	Prints the current document.
	Opens the Environment setup window.
Ea	Displays the Function Tree window.
	Displays the Direct Edit window.
5	Displays the All Monitor function.
	Displays the User monitor.
	Displays the I/O Monitor function window.
8	Shows the Status Monitor.
*	Shows the Operation Monitor.
3	Shows the Manual Run window.
1	Shows the Pattern Run window.
0	Displays information for Trouble-Shooting.
\$	Displays the Parameter Edit window.
Ν	Displays the Oscilloscope.
	Shows the Visual Monitor window.
Ð	Shows software version information.

Parameter Edit Toolbar

Parameter Edit	• ×
x x x x x x x	ŋ 📃

ICON	FUNCTION	
×^	Saves the selected parameter to the drive.	
	Saves an entire group of parameters to the drive.	
	Saves all parameters to the drive.	
\$K	Reads the selected parameter.	
-	Reads a group of parameters from the drive.	
	Reads all parameters from the drive.	
2	Initializes the drive.	
1	Compares settings in the drive.	
5	Compares a file.	
	Opens the Comment Edit window.	

Oscilloscope Toolbar

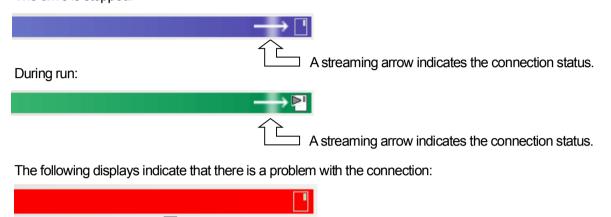


ICON	FUNCTION	
	Saves the data that was collected.	
r 🔁	Reads data that was collected.	
25	Switches the background color and the waveform color.	
	Copies an image of the waveform.	
×÷	Displays the calculations toolbar.	
Ô	Takes a snapshot of the data selected.	
2	Erases the snapshot data.	
1.	Displays the Trigger Conditions Setting dialog box.	
	Starts monitoring drive performance.	
	Stops monitoring drive performance.	
	Switches to the vertical cursor display.	
1	Sets the V1 vertical cursor.	
2	Sets the V2 vertical cursor.	
	Switches to the horizontal cursor display.	
1	Sets the H1 horizontal cursor.	
2	Sets the H2 horizontal cursor.	
	Moves the cursor.	
•	Enlarges the waveform display.	

3.1.4 Caption Bar

The Caption bar shows the connection status with the drive. When the drive and PC are not connected:

The following displays appear when the drive and PC are connected: When properly connected, the Caption bar will display: The drive is stopped:



The inverter has timed out. Please check the comm. connection.

3.1.5 Tree Window

All functions in SDWP001 can be executed from the Function Tree window.

Drive #1(HF-520 (AF Motor)) E Systematic Edit E ALL E AlL A1:Environmental Setting E A2:Favorite Parameters Setting B:Application E :Cruning D:Instructions E :Motor Parameter	Displays information regarding the Project that is currently open. Drive data also appears when connected to the drive. If no drive is connected, then the display will show data for the drive the Project has been assigned to.
E:Option H:Terminal Function Selection E:Protection Function Selection N:Special Adjustment O:Operator Relation O:DWEZ Parameter	
R:Connection Data	Displays the Function menu.
E S:Group E S:Group	Displays the Function menu. Functions are listed by category. By double clicking on an item in the tree, a function window that corresponds to that menu item will appear.
E S:Group Monitor All Monitor Wuser monitor	Functions are listed by category. By double clicking on an item in the tree, a function window that corresponds to that menu

Right-clicking on the nodes in the display screen will cause a context menu to appear. Most menus read "Open (\underline{O})" while others offer more functions.

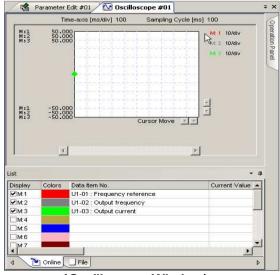
No.	ltem	Menu	Operation Description
1 Root		Inverter information (\underline{T})	Displays data read from the drive.
		Connect Inverter (<u>C</u>)	Connects the drive and PC.
		Disconnect Inverter (D)	Disconnects the drive from the PC.
2	Parameter Edit	Open (<u>O</u>)	Opens the Parameter Edit window.
2		User Parameter (<u>U</u>)	Opens the User Parameter setting window.
3	Direct Parameter Edit	Open (<u>O</u>)	Opens the Direct Parameter Edit window.
4	Monitor	_	_
5	All Monitors	Open (<u>O</u>)	Opens a window displaying all monitors.
6	User Monitor	Open (<u>O</u>)	Opens the User Monitor window.
0		Monitor item setting (<u>M</u>)	Opens the Monitor Item Setting Dialog
7	I/O Monitor	Open (<u>O</u>)	Opens the I/O Monitor window.
8	Status Monitor	Open (<u>O</u>)	Opens the Status Monitor window.
9	9 Movement Monitor	Open (<u>O</u>)	Opens the Movement Monitor window.
9		Monitor item setting (<u>M</u>)	Opens the Monitor Item Setting toolbar.
10	Oscilloscope	Open (<u>O</u>)	Opens the Oscilloscope screen.
11	Visual Monitor	Open (<u>O</u>)	Opens the Visual Monitor screen.
12	Trial Run	_	—
13	Manual Operation	Open (<u>O</u>)	Opens the Manual Run window.
14	Pattern Operation	Open (<u>O</u>)	Opens the Pattern Run window.
15	Troubleshooting	Open (<u>O</u>)	Opens the Troubleshooting window.

3.1.6 Child Window

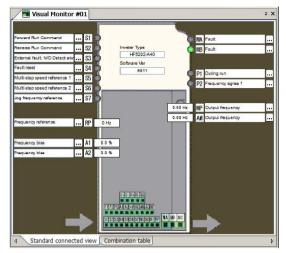
The Parameter Edit screen, Oscilloscope, and Visual Monitor functions are displayed in child windows as shown below.



<Parameter Edit Window>



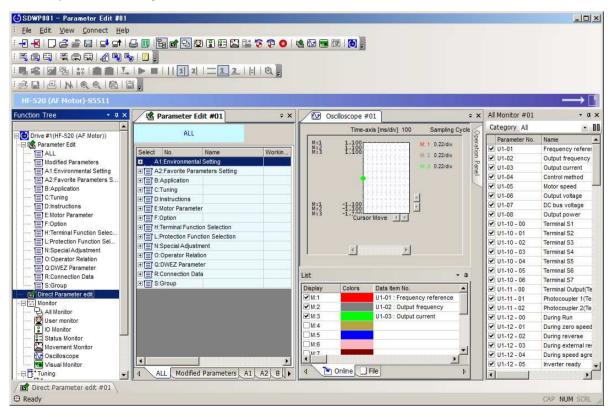
<Oscilloscope Window>



<Visual Monitor Window>

You can switch between displays by clicking on the tabs in the child window, including the Parameter Display window, Oscilloscope, and Visual Monitor functions.

You can also change the screen layout so that the various windows are stacked horizontally or vertically.

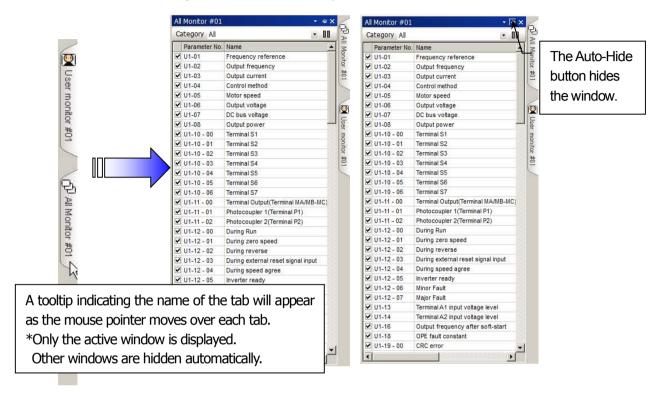


<Example of screen layout>

3.1.7 Docking Windows and Floating Windows

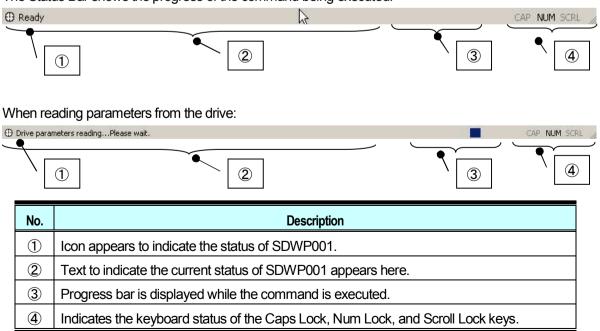
Monitor, Manual Run, Pattern Run, and Troubleshooting functions are displayed as docking windows. These windows can be separated from one another to become floating windows.

When windows are docked together, other windows may be hidden with the auto-hide function.



3.1.8 Status Bar

The Status Bar shows the progress of the command being executed.



4 Editing Drive Data

4.1 Drive Model Data Display

You can display information on the connected drive by selecting "File (<u>F</u>)" in the Main Menu \rightarrow "Inverter information (<u>T</u>)...", or by right-clicking on the Function Tree "Drive (number)" and selecting "Inverter information (<u>T</u>)..." in the menu.

NOTE: No data is displayed if the drive is not online.

Inveter Type:	HF5202-A40	
Initialize mode:	Japanese spec	
Capacity:	200V Class 0.4kW	
Software Ver.;	5511	
Control Type:	V/f control	

4.2 Parameter Edit

There are two ways to edit parameters:

- Parameter Edit window
- Direct Edit window

4.2.1 Parameter Edit Window

The Parameter Edit window lets you change and edit parameter settings.

4.2.1.1 Online Parameter Edit Screen

Double-clicking on "Parameter Edit" in the Function Tree makes the Parameter Edit window appear.

* Parameter "Q", "R" is a reservation area. DWEZ is not usable.

Select	No.	Name	Working value	Units	Drive's val.
	1:Environmenta			T I	
EEA	2:Favorite Para	ameters Setting		1.0	
±≡ в	Application				
	:Tuning				
	Instructions				
the second second	Motor Paramet	er			
E F					
	Terminal Funct				
	Protection Fun				
	Special Adjust				
	Operator Rela				
	:DWEZ Parame				-
	Connection Da	ita			
E E S	:Group				

Pop-Up Menu in Parameter List

Right-clicking on the Parameter List will display a pop-up menu. The selection available will vary depending on the tabs that are currently active.

When all parameter tabs are active:

Add Direct Parameter edit
Check all
Remove All Checks
Open All Tree
Close All Tree
Help
Environmental setup...

Jr.

Add Direct Parameter edit

Lets you add parameters selected in the parameter list to the Direct Parameter Edit window. For instructions on the Direct Parameter Edit function, see 4.2.2.

Check All

Selects all parameters, including those not displayed in the active tab.

Remove All Checks

Clears any checks for any parameters that have been selected.

Open All Tree

Opens all trees.

Close All Tree

5

Closes all tree branches for all parameter tabs.

Environmental setup

Displays the Environment Setting window.

When other tabs are currently active:

Add Direct Parameter edit
<u>C</u> heck all
<u>R</u> emove All Checks
Open All Tree
Close All Tree
Help
Environmental setun

Adding to the Direct Parameter Edit Window

Adds the parameters selected from the parameter list to the Direct Parameter Edit window. For instructions on the Direct Parameter Edit function, see 4.1.2.

Check All

Select all parameters, including those not displayed in the active tab.

Remove All Checks

Deselects all parameters that were selected.

Environmental setup

Displays the Environment Settings window.

Pop-up menu appearing from the column head in the Parameter List

Right-clicking on the column head in the Parameter List will display the following pop-up menu:

4	Name
~	Unit
4	Drive's value
~	Drive's unit
~	Min
~	Max
~	Default

Columns

Columns can be displayed or hidden. Columns "Selection", "No.", and "Working Value" can not be moved.

Pop-Up Menu in an Active Tab

Right-clicking on a tab window will display the following pop-up menu:

Group <u>t</u> ab display •	•	Shortening display
 A1:Environmental Setting 		Detailed display
A2:Favorite Parameters Setting	-	
B:Application		
C:Tuning		
D:Instructions		
E:Motor Parameter	-	
F:Option		
H:Terminal Function Selection		
L:Protection Function Selection		
N:Special Adjustment		
O:Operator Relation		
Q:DWEZ Parameter		
R:Connection Data		
S:Group		

Shortening display

Displays only the parameter group names.

Detailed display

Displays the details for each parameter group.

Group tab display

Switches between displaying and not displaying tabs.

NOTE: The tabs for "All Parameters" and "Modified Parameters" cannot be switched. NOTE: Parameter "Q", "R" is a reservation area. DWEZ is not usable.

Move Column

Move columns by dragging and dropping. The "Select" column cannot be moved.

	LiProtect	ion Function Selection								
Select	No.	Name	Working value	Units	Drive's value	Drive's unit	Min	Max	Default	
	L1-01	Motor protection selection	1 : General-purpose metor pr	-	1	-	0	6	1	Г
	L1-02	Motor protection time constant	1.0	min	1.0	min	0.1	5.0	1.0	
]	L1-03	MOL thermistor input	3 : Operation continued	-3	3	-	0	3	3	-
	L1-04	MOL filter time	1 : Coast to stop	-233	1	1	0	2	1	
]	L1-05	MOL reserved 1	0.20	sec	0.20	sec	0.00	10.00	0.20	
1	L1-08	Motor OL Level1	1.60	A	1.60	A	0.00	2.40	1.60	
	L1-13	Electronic thermal continues	1 : Continue Electronic thermal	-23	1	-	0	1	1	
]	L1-22	Leakage Current Filter Time C	0.0	sec	0.0	sec	0.0	60.0	0.0	
]	L1-23	Leakage Current Filter Time C	0.0	sec	0.0	sec	0.0	60.0	0.0	
]	L2-01	Momentary power loss detec	0 : Disabled	-0	0	-	0	2	0	
]	L2-02	Momentary power loss rideth	0.1	sec	0.1	sec	0.0	25.5	0.1	
	L2-03	Min. baseblock time	0.2	sec	0.2	sec	0.1	5.0	0.2	
	L2-04	Voltage recovery time	0.3	sec	0.3	sec	0.0	5.0	0.3	E



	LiProtect	ion Function Selection								
Select (No.	Working value	Name	Units	Drive's value	Drive's unit	Min	Max	Default	
	L1-21	1 : General-purpose motor pr	Motor protection selection	2	1	1 -	0	6	1	ſ
-	L1-02	1.0	Motor protection time constant	min	1.0	nin	0.1	5.0	1.0	7
	L1-03	3 : Operation continued	MOL thermistor input	-	3	-	0	3	3	-
	L1-04	1 : Coast to stop	MOL filter time	-	1	-	0	2	1	
	L1-05	0.20	MOL reserved 1	sec	0.20	sec	0.00	10.00	0.20	
	L1-08	1.60	Motor OL Level1	A	1.60	A	0.00	2.40	1.60	
1	L1-13	1 : Continue Electronic thermal	Electronic thermal continues		1	-	0	1	1	
]	L1-22	0.0	Leakage Current Filter Time C	sec	0.0	sec	0.0	60.0	0.0	
	L1-23	0.0	Leakage Current Filter Time C	sec	0.0	sec	0.0	60.0	0.0	
1	L2-01	0 : Disabled	Momentary power loss detec	-	0	-	0	2	0	
	L2-02	0.1	Momentary power loss rideth	sec	0.1	sec	0.0	25.5	0.1	
	L2-03	0.2	Min. baseblock time	sec	0.2	Sec	0.1	5.0	0.2	
1	L2-04	0.3	Voltage recovery time	sec	0.3	sec	0.0	5.0	0.3	1

Edit Parameter Settings

The Parameter Edit window lets you view and edit parameter settings.

Settingchanges can be made in the column marked, "Current Setting Value." The process for editing parameters will vary depending on the parameter that has been selected.

NOTE: Gray text indica tes that the parameter cannot be edited. This includes parameters that cannot be changed during run. Such parameters can be edited after the drive has come to acomplete stop.

When editing param eter settings, the color of the text and the background color will change.

Select	No.	Working value	Name	Units	Drive
	b1-02	0 : Digital operator	Operation method selection	-	0
	b1-03	0 : Deceleration to stop	Stopping method	-	0
~	b1-04	1 : Reverse disabled	Reverse operation	-	0
	b1-07	0 : Cycle External Run - If the	Local/remote run selection	-	0
	b1-08	0 : Cannot operate	Run command at programming	-	0
	b1-14	0 : Normal	Phase Turn Selection	-	0
	b1-15	0 : Digital Operator	Reference Selection in Local	-	0
	b1-16	0 : Digital Operator	Operation method selection i	-	0
	b1-17	1 : Permission	Operation permission with p	-	1
•	b2-01	11.0	DC injection start frequency	Hz	0.5
•	b2-02	51	DC injection current	%	50
	b2-03	0.00	DC injection time at start	sec	0.00
	b2-04	0.00	DC injection time at stop	sec	0.00

No.	Name	Description
		Parameter currently being edited will appear in green.
	Deremeter diaples	Once that parameter has been written to the drive, the edit status will return
1	Parameter display	to normal and the parameter will appear in light yellow shading.
	during Edit	Parameters that have been changed from their original default values will
		appear in blue text.
		If a parameter has been set outside the allowable setting range, the text will
2	Parameter display	appear in red.
2	outside range	Certain parameters will display "Reserved" when a selection that cannot be
		set has been entered.
3	Parameter default	Settings that have been changed from their original default values will be
3	values differ	displayed in blue text.

Editing a numeric value

Single-click or double-click on the value you want to change, and then enter the new setting.

Select	No.	Working value	Name	Units	Drive's value	Drive's unit	Min	Max	Default
	b1-16	0 : Digital Operator	Operation method selection i	-	0	-	0	3	0
	b1-17	1 : Permission	Operation permission with p	-	1	-	0	1	1
	b2-01	0.0	DC injection start frequency	Hz	0.0	Hz	0.0	10.0	0.5
	b2-02	50	DC injection current	%	50	%	0	75	50
	b2-03	0.00	DC injection time at start	sec	0.00	sec	0.00	10.00	0.00
	b2-04	0.00	DC injection time at stop	sec	0.00	sec	0.00	10.00	0.00
	b3-01	0 : Disabled	Speed search at start	-	0	-	0	1	0

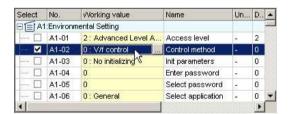
Editing the value selected

Select the item from the drop-down menu, or enter the new value directly into the line provided.

Select	No.	Working value	Name	Units	Drive's value	Drive's unit	Min	Max	Default
	1:Environm	ental Setting		1	1		1		11
	A1-01	2 : Advanced Level Access 💌	Access level	2	2	-	0	9999	2
-	A1-02	0 : Monitoring only	trol method	12	0	-	0	5	0
	A1-03	1 : Used to select user constant	t arameters	12	0	8	0	9990	0
🗌	A1-04	2 : Advanced Level Access	r password	1	0	-	0	9999	0
	A1-05	0	Select password	-	0	-	0	9999	0
·····	A1-06	0 : General	Select application	÷	0	-	0	15	0
[]	A1-07	0 : Disabled	DWEZ Function Selection	-	0	-	0	2	0

Editing the Control Mode

Below is an example of editing the control mode or parameters that depend on the control mode. The Edit window will appear by double-clicking on a parameter row, or by selecting "Control Method Selection" from the parameter list, then clicking the ... icon.



A1-	32	Control metho	d	
0:V	'f contro	1		•
	Paramel			20
he folk No.	owing p Nam		changed due to the setting Working value	g value. Chang
				-

Either select the setting value from the List Box, or enter the value directly. Any parameters that are affected when the control mode is changed will be displayed in this list.

Click "OK" to accept all of these related changes, or click "Cancel" if you decide you do not want to make the changes listed in the window.

SDWP001 will return to the Parameter Edit Screen.

Editing the Access Level of the Selected Parameter

Select "Access Level" from the list, then click on the desired setting in the drop-down list or enter the value manually.

Select	No.	Working value	Name	Un	D.,
PEA	1:Environr	nental Setting			
V	A1-01	2 : Advanced Lev 💌	Access level	-	2
	A1-02	0 : V/f control	Sntrol method	-	0
[]	A1-03	0 : No initializing	Init parameters	20	0
	A1-04	0	Enter password	25	0
	A1-05	0	Select password	2	0
	A1-06	0 : General	Select application	-	0

The value will be displayed, provided the value is within the possible setting range, and all parameters with that access level will appear in the parameter list.

Editing parameters that affect other parameter settings

Changing certain parameters will cause other parameters to change accordingly.

Select	No.	Working value	Name	Un	Drive'	Drive'	ħ
	C1-07	10.0	Acceleration time	sec	10.0	sec	C
	C1-08	10.0	Deceleration time	sec	10.0	sec	C
	C1-09	10.0	Emergency stop ti	sec	10.0	sec	C
	C1-10	1:0.1-second units	Accel/Decel time	4	1	÷	C
	C1-11	0.0	Accel/Decel swit	Hz	0.0	Hz	C
	C2-01	0.00	S-curve accelera	Sec	0.00	sec	C
F	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	12.22			12.2.2.1	1 a 1 C 1 C C C C C C C C C C C C C C C	

Select the parameter you want to edit, then click or double-click on the parameter. The Parameter Edit window will appear.

C1-1	Accel/Decel time settin	g unit	
0:0.0	1-second units		T
hange	Parameters	_	
	wing parameters are changed (-	I I I I I I I I I I I I I I I I I I I
No.	Name	Working value	Chang
C1-01	Acceleration time 1	40.0	40.00
C1-02	Deceleration time 1	10.0	10.00
C1-03	Acceleration time 2	10.0	10.00
C1-04	Deceleration time 2	10.0	10.00
C1-05	Acceleration time 3 for mot	10.0	10.00
C1-06	Deceleration time 3 for mot	10.0	10.00
C1-07	Acceleration time 4 for mot	10.0	10.00
C1-08	Deceleration time 4 for mot	10.0	10.00
	Emergency stop time	10.0	10.00
C1-09			

Either select the setting value from the List Box, or enter the value directly. Any parameters that are affected when the change is made will be displayed in this list.

Click "OK" to accept all of these related changes, or click "Cancel" if you decide you do not want to make the changes listed in the window.

SDWP001 will return to the Parameter Edit Screen.

Changing the Settings for the Drive kVA Selection

Changing the Drive kVA setting will initialize the drive. Most parameters in the drive will be reset to the default values for the kVA setting that was selected.

Attempting to change any settings to the Drive kVA setting will generate the following message. The same will happen by clicking

Warning	L.	×
<u>.</u>	This parameter will change the settings of many parameters which depend on it. This is done by initializing all parameters and overwriting the dependent parameter default va Non-dependent parameters are unaffected (set to their previous setting). Continue?	alues.
	OK Cancel	

Clicking "OK" will display with the following message:

2220 : 1	nitialize using a two-wire sec	quence 💌
No.	Name	Working value
02-04	KVA selection	60 : HF5202-A10
A1-02	Control method	0 : V/f control
02-09	Initialize mode selection	0 : Japanese spec

Either select from the drop-down menu or enter the value manually.

Next, either select "Current Setting Value" from the drop-down menu that appears below, or enter the value manually.

Clicking "OK" will generate the following window:

NOTE: The lower drop-down list is enabled only when editing the drive kVA setting.

No.	Name	W	
b2-03	DC injection time at start	0	Г
b3-01	Speed search at start	0	L
b3-02	Speed search current	120	
b3-06	Output current	1.0	
b3-08	ACR Gain for Speed Search	0	
b5-19	PID Setpoint Value	0	
b5-38	PID Setpoint Setup/Arbitrary display setup	1	
b5-39	PID Setpoint Set up/Display Number of decimals	2	
b8-04	Energy-saving coefficient	2	
C2-01	S-curve acceleration at start	0	
C3-01	Slip compensation gain	0.0	
C3-02	Slip compensation time	2	-
•			

Click "Execute" to start the initialization process.

After the drive has been initialized, the parameter settings that are affected by the type of initialization selected will be automatically set to their new default values.

All changes that have been written to the drive appear in the "Working values" column, and the view will return to the Parameter Edit screen.

Display Digits for Setting Units

Changing the units displayed or the number of digits for a parameter setting will automatically recalculate parameter values.

Setting Units

Select "Frequency Reference Setting/Display Units" from the parameter list and clickor double-click on the corresponding row.

Some drives do not show "Display scaling".

	B Display scaling			
1:0.0	1% units		•	
hange F	arameters			
he follo	wing parameters are change Name		1	100
NO. d1-01	Frequency reference 1	Working value	Chang	F
d1-02	Frequency reference 2	10.00	0.00	1
d1-03	Frequency reference 3	0.00	0.00	1
	Frequency reference 4	0.00	0.00	
d1-04	ricidachoj reference +		(-)	18
d1-04 d1-05	Frequency reference 5	0.00	0.00	
	비) 안 있는	0.00	0.00	
d1-05	Frequency reference 5	10000	1210.0	
d1-05 d1-06	Frequency reference 5 Frequency reference 6	0.00	0.00	

Either select the desired setting from the drop-down menu or enter the setting manually.

Once the value has been entered, a list of parameters that are affected by the change in units for the frequency reference will appear in the list shown above.

Click "OK" to accept these changes, or click "Cancel" if you decide you do not want to make the changes listed in the window. SDWP001 will return to the Parameter Edit Screen.

User Parameter Setting

Setting parameters to the User Access Level creates a select list of parameters that can be quickly view and edited.

Select a parameter from "A2: Favorite Parameters Setting" from the parameter list and click _____ or double-click on the appropriate row.

The following window will appear: 🕒 User Constant Setting × **User Constant Candidate** User Parameter(A2-01-A2-32) : All b1-01 : Reference selection A1-02 : Control method * * A1:Environmental Setting b1-02 : Operation method selection b1-01 : Reference selection **B**:Application Add all b1-03 : Stopping method b1-02 : Operation method selection C:Tuning b1-04 : Reverse operation b1-03 : Stopping method D:Instructions E:Motor Parameter b1-07 : Local/remote run selection C1-01 : Acceleration time 1 F:Option b1-08 : Run command at programm C1-02 : Deceleration time 1 H:Terminal Function Selection b1-14 : Phase Turn Selection C6-01 : Duty Cycle L:Protection Function Selectic N:Special Adjustment b1-15 : Reference Selection in Loc C6-02 : Carrier frequency selection O:Operator Relation b1-16 : Operation method selection d1-01 : Frequency reference 1 - Delete b1-17 : Operation permission with d1-02 : Frequency reference 2 b2-01 : DC injection start frequenc d1-03 : Frequency reference 3 差 Delete all F + OK Cancel

Select the parameter to add to the User Parameter list and click "Add".

Parameters that have been set to the User Parameter List will appear in the corresponding box on the right.

All A1:Environmental Setting B:Application C:Tuning D:Instructions E:Motor Parameter F:Option H:Terminal Function Selection L:Protection Function Selectic N:Special Adjustment O:Operator Relation	b1-01 : Reference selection b1-02 : Operation method selection b1-03 : Stopping method b1-04 : Reverse operation b1-07 : Local/remote run selection b1-08 : Run command at programm b1-14 : Phase Turn Selection b1-15 : Reference Selection in Loc b1-16 : Operation method selection	Add all Add Add	b1-01 : Reference selection b1-02 : Operation method selection b1-03 : Stopping method C1-01 : Acceleration time 1 C1-02 : Deceleration time 1 C6-01 : Duty Cycle C6-02 : Carrier frequency selection d1-01 : Frequency reference 1 d1-02 : Frequency reference 2
<u> </u>	b1-17 : Operation permission with b2-01 : DC injection start frequenc	≠ Delete all	d1-03 : Frequency reference 3 d1-04 : Frequency reference 4

Click "OK" to accept these changes, or click "Cancel" if you decide you do not want to make the changes listed in the window.

SDWP001 will return to the Parameter Edit Screen.

SDWP001	×
4	When "User selection constant" is set at the access level, the setting of the user

Clicking "OK" will save the changes that were made and SDWP001 will return to the Parameter Edit Screen.

Saving parameter settings to be used as a User Initialization

Select parameter o2-03 and set the Working value so that the current parameter settings become the default values when a User Initialization is performed.

Select	No.	Name	Working value	Units	Drive's value	Drive's unit	Min
	o2-01	LOCAL/REMOTE key enable/	1 : Enabled	-	1	-	0
	o2-02	Operation STOP key	1 : Always enabled	-	1	-	0
	o2-03	User constant initial value	0 : Stores/not set	-	0	-	0
	o2-04	KVA selection	0 : Stores/not set	r -	0061	-	0000
	o2-05	Frequency Reference Settin	1 : Begin storing	-	0	-	0
	o2-06	Operator detection	2 : All clear	J.	0	-	0
	o2-07	Bidirectional when the invert	0 : Forward run	-	0	-	0

NOTE: Any parameters that have been edited will be returned to their previous values if a function is executed and those changes were not first saved.

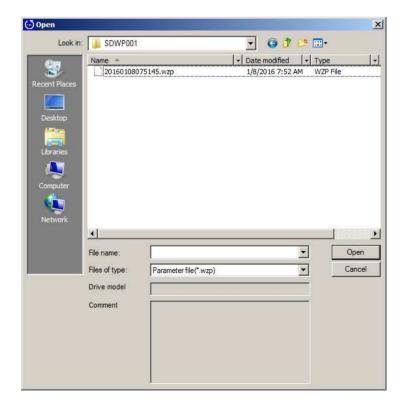
*These parameters cannot be edited when online (i.e., they can only be viewed and not changed). *Initialize parameter values first. Next either select "1: Begin storing" from the drop-down menu or enter the value manually.



Clicking "Execute" will save the current parameter settings to be used as a User Initialization. Click "Cancel" if you decide not to save the current parameter settings. When finished, SDWP001 will return to the Parameter Edit window.

Comparing Files

To compare all parameter settings (both those displayed in the current window as well as those that are not displayed) from one file with all parameter settings in another file, follow the directions below. Click on the "File Compare" button located on the toolbar. The following screen will appear:



Select the file you wish to compare and click "Open". The following message will appear:

Compar	e 🛛 🔀
Ų	Comparison of current parameter settings with parameter file will start. Continue?
	OK Cancel

If you do not wish to compare the file, click "Cancel" and the screen will return to the Parameter Edit window.

Click "OK" to compare the files. When finished, the following screen will appear:

When all parameters agree

A message appears, indicating that parameters match the file.



When parameters do not agree

The Status bar will read, "Parameters settings differ." A list of the parameter setting differences will appear as shown below:

No.	Name	Working value	Units	File's value	File's unit
d1-01	Frequency reference 1	0.00	Hz	0.10	Hz

To save the file compare results, right-click on the Results window and select "Save" from the pop-up menu.

Initializing the Drive

Returns all settings to their original default values. To initialize the drive, follow the instructions below:

 To initialize the drive, select "Drive initialized" from the Edit menu or the toolbar, or double-click A1-03, Init Parameters from the Parameter Edit window.

The following window will appear:

	ns for initialization	
A1-03 : Init parameters	54	
1110 : User Initialize		-

If you decide that you do not want to initialize the drive at this point, click "Cancel" and SDWP001 will return to the Parameter Edit window.

- Select the type of initialization to perform using the drop-down menu. Normally, initializing the drive does not require information such as the drive capacity or control mode.
 If there are any changes to drive capacity or control mode, those changes should be entered directly into the appropriate parameters.
- 3) Click "OK" and the following window will appear:



4) Click "Execute," and the SDWP001 will begin to initialize the drive.

Comparing Drives

To compare all parameters in a drive with the settings in a Project (including parameters that may not be displayed on the screen), follow the procedure below:

 Go to the Edit menu or the toolbar and select "Drive Compare". The following screen will appear:

Compare			×
i)	Comparison of c with drive parar Continue?	Cancel	ettings egin.

If you decide you do not to compare parameter settings at this point, click "Cancel" and SDWP001 will return to the Parameter Edit window.

2) Click "OK" to compare parameter settings in the drive.

When All Parameters Agree

The Status Bar will display the message "Parameters are matched to the drive."



When Parameters Do Not Agree

The Status bar will read, "Parameter values in the drive differ." A list of parameters that have different setting values will appear.

No.	Name	13	Working value	Units	Drive's value	Drive's unit	
o4-01	Cumulative ope	eration time setting	3	Н	4	Н	

To save the results after comparing parameters, right-click on the Results window and select "Save" from the pop-up menu.

Reading parameter settings from the drive

Reads the selected parameters from the drive and writes them to the Project.

From the Edit menu or the toolbar, click "Read selected parameters", "Group Read", or "Read All Parameters".

Read Selected Parameters

SDWP001 will read the parameters selected in the Parameter Edit window.

Read Parameter Group

SDWP001 will read the selected group of parameters.

Read All Parameters

Reads all parameters, including those that are not displayed.

When parameters are currently being edited

If parameter settings are currently being edited, the following warning message will appear:

Read fro	m drive	×
<u>.</u>	Parameters will be read from t The setting value under edit is Continue? Yes No	0.73/173223/7/07

To erase the changes to parameters that are currently being edited and then read parameters in the drive, click "Yes".

If you decide you do not want to erase the changes currently being made, click "No" and SDWP001 will return to the Parameter Edit window.

When parameters settings are affected by a change to another parameter group The following window will appear:

A1-0	2 Control method		
2 : Op	en-loop vector control 1		•
banga	Decomotors		
21 1 2 C 1 6 T	Parameters wing parameters are changed (due to the setting v	value.
No.	Name	Working value	Chang
b2-03	DC injection time at start	0.00	0.00
b3-01	Speed search at start	0	0
b3-02	Speed search current	120	100
b3-08	ACR Gain for Speed Search	0.50	0.50
b5-19	PID Setpoint Value	0.00	0.00
b5-38	PID Setpoint Setup/Arbitrar	10000	10000
b5-39	PID Setpoint Set up/Display	2	2
b8-02	Energy-saving gain	0.0	0.7
b8-03	Energy-saving filter time c	0.00	0.50

To read the entire list of parameters including related parameters, click "OK". If you decide not to read the parameters in the list, click Cancel and SDWP001 will return to the

Parameter Edit window.

Write to Drive

Saves the selected parameters to the drive.

From the Edit menu or the toolbar, and click "Write selected parameters", "Write Group", or "Write all parameters".

Write Selected Parameters

Writes the parameters selected in the Parameter Edit window. A shortcut key to write parameter settings is available by pressing Ctrl + W.

Write Group

Writes all parameters in the group shown in the Parameter Edit window.

Write All Parameters

Write all parameters (including those that are not displayed).

When parameters selected in a group affect the settings of parameters in other groups The following window will appear:

A1-0	2 Control method			
2 : Op	en-loop vector control 1		•	
hange	Parameters			
	wing parameters are changed (-		
No.	Name	Working value	Chang	
b2-03	DC injection time at start	0.00	0.00	
b3-01	Speed search at start	0	0	
b3-02	Speed search current	120	100	
b3-08	ACR Gain for Speed Search	0:50	0.50	
b5-19	PID Setpoint Value	0.00	0.00	
b5-38	PID Setpoint Setup/Arbitrar	10000	10000	
b5-39	PID Setpoint Set up/Display	2	2	
	Energy-saving gain	0.0	0.7	
b8-02	Energy-saving filter time c	0.00	0.50	

To write all parameters, including related parameters listed in the window, click "OK".

If you decide not to write the parameter values show, click "Cancel" and SDWP001 will return to the Parameter Edit window.

4.2.1.2 Parameter Edit Screen Working Online

Selecting "Parameter Edit" from the function tree in SDWP001 will call up the Parameter Edit window. * Parameter "Q", "R" is a reservation area. DWEZ is not usable.

Select	No.	Name	Working value	Units	Drive's value	Drive's unit	Min	Max	Default
± A	1.Environme	ntal Setting					9	1	
EEA	2:Favorite Pa	arameters Setting							
±≡ 8:	Application								
EEC:	Tuning								
E D:	Instructions								
±≡ E:	Motor Param	eter							
∃ F :	Option								
E H	Terminal Fun	ction Selection							
E E L:	Protection Fu	unction Selection							
E N:	Special Adju	stment							
HE 0	Operator Re	lation							
±≣ Q	DWEZ Parar	neter							
E R	Connection I	Data							
±≣s:	Group								

Parameter List Pop-Up Menu

Right-clicking on the parameter list will call up a pop-up menu. Possible menu items will vary depending on which tabs are currently active.

When all parameter tabs are active

Add Direct Parameter edit Check all Remove All Checks Open All Tree Close All Tree Help Environmental setup...

Check all

Selects all parameters in the active tab, including those that aren't displayed.

Remove All Checks

Clears all checks, including those that aren't displayed.

Open All Tree

Opens all trees in the parameter tab.

Close All Tree

Closes all trees in the parameter tab.

Environmental setup

Displays the Environment setup window.

When other tabs are active

- Add Direct Parameter edit
 - ⊆heck all
 - <u>R</u>emove All Checks

Open All Tree Close All Tree

<u>H</u>elp

Environmental setup...

Check all

Selects all parameters in the active tab, including those that aren't displayed.

Remove All Checks

Clears all checks, including those that aren't displayed.

Environmental setup

Displays the Environment setup window.

Pop-up menu displayed in the column head

The following pop-up menu is generated by clicking on a column head in the parameter list.

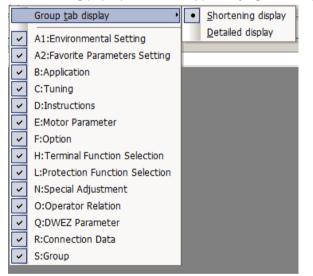
4	Name
~	Unit
4	Drive's value
~	Drive's unit
~	Min
~	Max
~	Default

Column Heading

Column headings can be displayed or hidden from view. It is not possible, however, to hide "Select", "No.", or "Working value".

Tab pop-up menu

The following pop-up menu will appear by right-clicking on the tab:



Shortening display

Displays only the parameter group names.

Detail display

Displays the details for each parameter group.

Group tab display

Switches between displaying and not displaying tabs.

NOTE: The tabs for "All Parameters" and "Modified Parameters" cannot be switched. NOTE: Parameter "Q", "R" is a reservation area. DWEZ is not usable.

Edit Parameter Settings

The Edit window lets you view and edit parameter settings. Setting changes can be made in the column marked, "Working value."

The process for editing parameters will vary depending on the parameter that has been selected.

NOTE: Gray text indicates that the parameter cannot be edited. This includes parameters that cannot be changed during run. Such parameters can be edited after the drive has come to a stop.

When editing parameter settings, the color of the text and the background color will change.

			3	Γ	Ð	/2				
Select	No.	Name	Working value		Units	Drive's value	Drive's unit	Min	Max	De
	b1-02	Operation method selection	0 · Digital operator		-	0	-	0	3	1
	b1-03	Stopping method	0 : Deceleration to stop		- /	0	-	0	9	0
•	b1-04	Reverse operation	1 : Reverse disabled		- /	0	-	0	1	0
	b1-07	Local/remote run selection	0 : Cycle External Run - I	f	- /	0	-	0	1	0
	b1-08	Run command at programming	0 : Cannot operate		-/	0	-	0	2	0
	b1-14	Phase Turn Selection	0 : Normal		F	0	-	0	1	0
	b1-15	Reference Selection in Local	0 : Digital Operator	1	-	0	-	0	4	0
	b1-16	Operation method selection i	0 : Digital Operator	/	-	0	-	0	3	0
	b1-17	Operation permission with p	1 : Permission	/	-	1	-	0	1	1
✓	b2-01	DC injection start frequency	11.0		Hz	0.5	Hz	0.0	10.0	0.5
•	b2-02	DC injection current	51		%	50	%	0	75	50
	b2-03	DC injection time at start	0.00		sec	0.00	sec	0.00	10.00	0.0

No.	Name	Description
		Parameters currently being edited will appear in green.
		Once a parameter has been written to the drive, the edit status
1	Parameter display during Edit	will return to normal and the parameter will appear in light yellow
U		shading.
		Parameters that have been changed from their original default
		values will appear in blue text.
		If a parameter has been set outside the allowable setting range,
(2)	Baramatar dianlay, autoida ranga	the text will appear in red.
2	Parameter display outside range	Certain parameters will display "Reserved" when a selection that
		cannot be set has been entered.
3	Parameter default values differ	Settings that have been changed from their original default
3		values will be displayed in blue text.

Editing a numeric value

Click on the value you want to change, and then enter the new setting.

Double-clicking on the value also works.

Select	No.	Working value	Name	Units	Drive's value	Drive's unit	Min	Max	Default
	b1-16	0 : Digital Operator	Operation method selection i	-	0	-	0	3	0
	b1-17	1 : Permission	Operation permission with p	-	1	-	0	1	1
	b2-01	0.0	DC injection start frequency	Hz	0.0	Hz	0.0	10.0	0.5
	b2-02	50	DC injection current	%	50	%	0	75	50
	b2-03	0.00	DC injection time at start	sec	0.00	sec	0.00	10.00	0.00
	b2-04	0.00	DC injection time at stop	sec	0.00	sec	0.00	10.00	0.00
	b3-01	0 : Disabled	Speed search at start	-	0	-	0	1	0

Editing the value selected

Either select the item from the drop-down menu, or enter the new value directly into the line provided.

Select	No.	Working value	Name	Units	Drive's value	Drive's unit	Min	Max	Default
AIEG	1:Environm	ental Setting		1					11
	A1-01	2 : Advanced Level Access 💌	Access level	E.	2	-	0	9999	2
-	A1-02	0 : Monitoring only	trol method	12	0	-	0	5	0
	A1-03	1 : Used to select user constant	t arameters	12	0	8	0	9990	0
	A1-04	2 : Advanced Level Access	er password	1	0	-	0	9999	0
	A1-05	0	Select password	-	0	-	0	9999	0
·····	A1-06	0 : General	Select application	÷	0	-	0	15	0
	A1-07	0 : Disabled	DWEZ Function Selection	-	0	-	0	2	0

Editing the Control Mode

Below is an example of editing the control mode or parameters that depend on the control mode. The Edit window will appear by double-clicking on a parameter row, or by selecting "Control Method Selection" from the parameter list, then clicking the ... icon.

Select	No.	Working value	Name	Un	D	•
PEA	1:Environr	nental Setting	1	11 1		-
	A1-01	2: Advanced Level A	Access level	2	2	
Image: A start of the start	A1-02	0: V/f control	Control method	-	0	
	A1-03	0 : No initializing	Init parameters	2	0	
	A1-04	0	Enter password	4	0	
	A1-05	0	Select password	-	0	
	A1-06	0 : General	Select application	-	0	-
4		3			•	Г

A1-	02 Control met	nod	
0:V	/f control		•
10000	Parameters	20. 0027 -5044 avec	
he foll No.	owing parameters are Name	changed due to the setting volue	value. Chang 🔺
			121

Either select the setting value from the List Box, or enter the value directly.

Any parameters that are affected when the control mode is changed will be displayed in this list. Click "OK" to accept all of these related changes, or click "Cancel" if you decide you do not want to make the changes listed in the window.SDWP001 will return to the Parameter Edit Screen.

Editing the Access Level of the Selected Parameter

Select "Access Level" from the list, then click on the desired setting in the drop-down list or enter the value manually.

Select	No.	Working value	Name	Un	D.,
AIEG	1:Environr	nental Setting			
V	A1-01	2 : Advanced Lev 💌	Access level	-	2
	A1-02	0 : V/f control	Control method	-	0
}	A1-03	0 : No initializing	Init parameters	36	0
	A1-04	0	Enter password	28	0
	A1-05	0	Select password	8	0
	A1-06	0 : General	Select application	~	0

The value will be displayed, provided the value is within the possible setting range and all parameters with that access level will appear in the parameter list.

Editing parameters that affect other parameter settings

Changing certain parameters will cause other parameters to change accordingly.

Select	No.	Working value	Name	Un	Drive'	Drive'	N
	C1-07	10.0	Acceleration time	sec	10.0	sec	C
	C1-08	10.0	Deceleration time	sec	10.0	sec	C
	C1-09	10.0	Emergency stop ti	sec	10.0	sec	C
	C1-10	1:0.1-second units	Accel/Decel time	4	1	÷	0
	C1-11	0.0	Accel/Decel swit	Hz	0.0	Hz	C
	C2-01	0.00	S-curve accelera	Sec	0.00	sec	C
					12.2.2	110000000	

Select the parameter you want to edit, then click or double-click on the parameter. The Parameter Edit window will appear.

C1-1	0 Accel/Decel time settin	g unit	
0:0.0	1-second units		•
hange	Parameters		
4 H H H	wing parameters are changed o	due to the setting	value.
No.	Name	Working value	Chang 🔺
C1-01	Acceleration time 1	10.0	10.00
C1-02	Deceleration time 1	10.0	10.00
C1-03	Acceleration time 2	10.0	10.00
C1-04	Deceleration time 2	10.0	10.00
C1-05	Acceleration time 3 for mot	10.0	10.00
C1-06	Deceleration time 3 for mot	10.0	10.00
C1-07	Acceleration time 4 for mot	10.0	10.00
C1-08	Deceleration time 4 for mot	10.0	10.00
C1-09	Emergency stop time	10.0	10.00

Either select the setting value from the List Box, or enter the value directly. Any parameters that are affected when the change is made will be displayed in this list.

Click "OK" to accept all of these related changes, or click "Cancel" if you decide you do not want to make the changes listed in the window. SDWP001 will return to the Parameter Edit Screen.

Changing the Settings for the Drive kVA Selection or Initialization

Changing the Drive kVA setting or entering a value into the Initialization parameter will initialize the drive. Most parameters in the drive will be reset to the default values for the kVA setting that was selected, or according to the type of initialization that was entered.

	43
1	This parameter will change the settings of many othe parameters which depend on it.
-	This is done by initializing all parameters and
	overwriting the dependent parameter default values
	Non-dependent parameters are unaffected (set bac
	Non-dependent parameters are unaffected (set to their previous setting).

Clicking "OK" will display with the following message:

41-03 : 1	nit parameters	
2220 : 1	nitialize using a two-wire see	quence
	-11	
No.	Name	Working value
02-04	KVA selection	60 : HF5202-A10
A1-02	Control method	0 : V/f control
o2-09	Initialize mode selection	0 : Japanese spec
	******	1092.
		-7
•		•

Either select the type of initialization from the drop-down menu or enter the value manually. Next, either select "Current Setting Value" from the drop-down menu that appears below, or enter the value manually. Clicking "OK" will generate the following window:

No.	Name	W		
b2-03	DC injection time at start	0	Γ	
b3-01	Speed search at start	0		
b3-02	Speed search current	120		
b3-06	Output current	1.0		
b3-08	ACR Gain for Speed Search	0		
b5-19	PID Setpoint Value			
b5-38	PID Setpoint Setup/Arbitrary display setup			
b5-39	PID Setpoint Set up/Display Number of decimals	2		
b8-04	Energy-saving coefficient	2		
C2-01	S-curve acceleration at start	0		
C3-01	Slip compensation gain	0.0		
C3-02	Slip compensation time	2	-	
(A.)				

NOTE: The lower drop-down list is enabled only when editing the drive kVA setting and when selecting the type of initialization to perform on the drive settings.

Click "Execute" to start the initialization process.

After the drive has been initialized, the parameter settings that are affected by the type of initialization selected will be automatically set to their new default values.

All changes that have been written to the drive appear in the "Working values" column, and the view will return to the Parameter Edit screen.

Display Digits for Setting Units

Changing the units displayed or the number of digits for a parameter setting will automatically recalculate parameter values.

Setting Units

Select "Frequency Reference Setting/Display Units" from the parameter list and click or double-click on the corresponding row.

"Display scaling" is not available in some drives.

01-0	3 Display scaling			
1:0.0	1% units		•	
hanne F	Parameters			
he follo	wing parameters are change			
No.	Name	Working value	Chang	
d1-01	Frequency reference 1	0.00	0.00	
d1-02	Frequency reference 2	0.00	0.00	1
d1-03	Frequency reference 3	0.00	0.00	
d1-04	Frequency reference 4	0.00	0.00	_
d1-05	Frequency reference 5	0.00	0.00	
d1-06	Frequency reference 6	0.00	0.00	
d1-07	Frequency reference 7	0.00	0.00	
d1-08	Frequency reference 8	0.00	0.00	
	Frequency reference 9	0.00	0.00	

Either select the desired setting from the drop-down menu or enter the setting manually.

Once the value has been entered, a list of parameters that are affected by the change in units for the frequency reference will appear in the list shown above.

Click "OK" to accept these changes, or click "Cancel" if you decide you do not want to make the changes listed in the window. SDWP001 will return to the Parameter Edit Screen.

User Parameter Setting

Setting parameters to the User Access Level creates a select list of parameters that can be quickly viewed and edited.

Select a parameter from "A2: Favorite Parameters Setting" from the parameter list and click, or double-click on the appropriate row. The following window will appear:

All A1:Environmental Setting B:Application C:Tuning D:Instructions E:Motor Parameter F:Option H:Terminal Function Selection L:Protection Function Selection N:Special Adjustment O:Operator Relation	b1-01 : Reference selection b1-02 : Operation method selection b1-03 : Stopping method b1-04 : Reverse operation b1-07 : Local/remote run selection b1-08 : Run command at programm b1-14 : Phase Turn Selection b1-15 : Reference Selection in Loc b1-15 : Reference Selection in Loc b1-16 : Operation method selection b1-17 : Operation permission with b2-01 : DC injection start frequenc	Add all Add Delete	A1-02 : Control method b1-01 : Reference selection b1-02 : Operation method selection b1-03 : Stopping method C1-01 : Acceleration time 1 C1-02 : Deceleration time 1 C6-01 : Duty Cycle C6-02 : Carrier frequency selection d1-01 : Frequency reference 1 d1-02 : Frequency reference 2 d1-03 : Frequency reference 3
--	--	--------------------------	--

Select the parameter to add to the User Parameter list and click "Add".

Parameters that have been set to the User Parameter List will appear in the corresponding box on the right.

A1:Environmental Setting B:Application C:Tuning D:Instructions E:Motor Parameter F:Option H:Terminal Function Selection L:Protection Function Selectic N:Special Adjustment O:Operator Relation	b1-01 : Reference selection b1-02 : Operation method selection b1-03 : Stopping method b1-04 : Reverse operation b1-07 : Local/remote run selection b1-08 : Run command at programm b1-14 : Phase Turn Selection b1-15 : Reference Selection in Loc b1-16 : Operation method selection b1-17 : Operation permission with b2-01 : DC injection start frequenc	 Add all Add Add ← Delete Æ Delete all 	b1-01 : Reference selection b1-02 : Operation method selection b1-03 : Stopping method C1-01 : Acceleration time 1 C1-02 : Deceleration time 1 C6-01 : Duty Cycle C6-02 : Carrier frequency selection d1-01 : Frequency reference 1 d1-02 : Frequency reference 2 d1-03 : Frequency reference 3 d1-04 : Frequency reference 4
--	---	---	---

Click "OK" to accept these changes, or click "Cancel" if you decide you do not want to make the changes listed in the window.

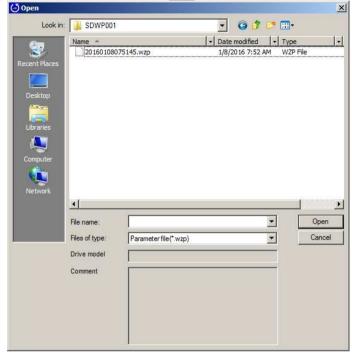
SDWP001 will return to the Parameter Edit Screen.

SDWP001		1
<u> </u>	When "User selection constant" is set at the access level, the setting of the user	
		12 - 16

Clicking "OK" will save the changes that were made and SDWP001 will return to the Parameter Edit Screen.

Comparing Files

To compare all parameter settings (both those displayed in the current window as well as those that aren't displayed) from one file with all parameter settings in another file, follow the directions below. Click on the "File Compare" button located on the toolbar. The following screen will appear:



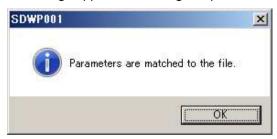
Select the file you wish to compare and click "Open". The following message will appear:

Compar	e 🛛 🔀
į)	Comparison of current parameter settings with parameter file will start. Continue?

If you do not wish to compare the file, click "Cancel" and the screen will return to the Parameter Edit window. Click "OK" to compare the files. When finished, the following screen will appear:

When all parameters agree

A message appears, indicating that parameters match the file.



When parameters do not agree

The Status bar will read, "Parameters settings differ." A list of the parameter setting differences will appear as shown below:

Comparison results with file							
No.	Name	Working value	Units	File's value	File's unit		
d1-01	Frequency reference 1	0.00	Hz	0.10	Hz		
aror	Troquency Telefence T	0.00	112	0.10	116		

To save the file compare results, right-click on the Results window and select "Save" from the pop-up menu.

4.2.2 Direct Parameter Edit

The Direct Parameter Edit window lets you view and edit parameter settings. NOTE: Changes made in the "Direct Parameter Edit" window are immediately saved to the drive.

Follow the procedure below to directly edit parameter settings.

 Starting in the Main Screen, go to "View" and "Direct Parameter Edit". The screen shown below will appear.

NOTE: When a different model of drive is connected, previously edited parameter settings will be returned to their default value.

No.	Name	Working v	Units	Drive's value	Drive's unit	Min	Max	Default
b1-14	Phase Tur	0 : Normal		0	-	0	1	0
C1-03	Accelerati	10.0	sec	10.0	sec	0.0	6000.0	10.0
C1-01	Accelerati	10.0	sec	10.0	sec	0.0	6000.0	10.0
A2-07	User para	C6-01 : Du	-	0223	-	0180	0528	0223
C6-01	Duty Cycle	1: ND(VT)	-	1	4	0	1	1

There are three ways to add parameters to the list above:

- Select, "Add to Direct Parameter Edit" from the pop-up menu in the Parameter Edit window.
- · Manually enter the parameter number into the "Number" column.
- Drag and drop from the Parameter Edit window into the Direct Parameter Edit window.

Be careful when entering values into the Working value column, as these new settings will be written immediately to the drive.

After settings are changed, the Parameter Edit window is refreshed and the new values displayed.

NOTE: Parameters that are grayed out cannot be edited. Parameters that cannot be changed while the drive is running the motor will also be grayed out during run. Stop the drive to edit those parameters.

2) To remove parameters from the list, right-click on the parameter and select, "Remove" from the pop-up menu.

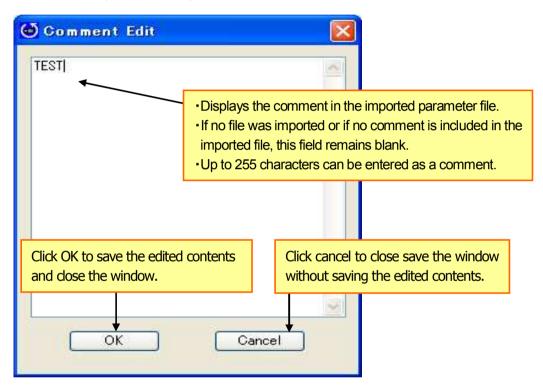
You can also select the parameter and click "Delete" to remove it.

4.2.3 Comment Edit

The Comment Edit window allows you to edit the comment in the imported parameter file. Additionally, it allows you to export a parameter file and include the comment that was edited on the Comment Edit window at printing.

Use either of the following methods to open the Comment Edit window.

- Select "Edit "→ "Comment Edit" from the SDWP001 main menu.
- Click the
 (Comment Edit) icon in the Parameter Edit toolbar.



<Comment Edit Window>

4.3 Troubleshooting

The Troubleshooting function lets you view and verify fault information for the drive that is currently connected.

NOTE: This display will be blank if the drive is not online or is not connected.

To display the Troubleshooting window, go to the SDWP001 Function Tree or select "View (V)" from the Main Menu and select "Troubleshooting".

The Troubleshooting window can be displayed as a docking window or as a floating window.

Curre	ent Fault No Erro	or.		Fault occurred when attempting to save file
1	Reset	Help		Reset Help
ult I	History			Fault History
1	Erase	Update		Erase Update
	No.	Name	Contents 🔺	
-	Most re	cent fault EF3:External Fault at Terminal 3 0H		No. Name Contents Unit
	U2-03	Frequency reference at fault		
	U2-04	Output frequency at fault		
	U2-05	Output current at fault		
	U2-06	Motor speed at fault		
	U2-07	Output voltage at fault		
	U2-08	DC bus voltage at fault		
	U2-09	Output power at Fault		
	U2-11	Input terminal status at fault	00000000 000	
innin (U2-12	Output terminal status at fault	00000000 000	
inin -	U2-13	Operation status at fault	0000000 001	
	U2-14	Cumulative operation time at Fault		
	U2-15	Speed Reference during Fault at Soft Start		
à an	U2-16	Motor q-Axis Current during Fault		
		most recent fault EF3:External Fault at Termina	H 3 0H	
	0.0000000000000000000000000000000000000	ost recent fault No Error OH		
		nost recent fault No Error OH		
		t Recent Fault No Error 0H		
	6th Mos	t Recent Fault No Error OH	•	

<Troubleshooting Screen with Drive Online> <Troubleshooting Screen with Drive Offline>

4.3.1 Current Fault



The message above will appear when a fault occurs.

If the drive is operating normally without any problems, the Status window will read, "Normal".

When a fault occurs, a message will appear showing the name of the fault, and will remain until the fault is cleared or until another fault occurs.

Fault Reset

To reset a fault, remove whatever is causing the fault and click the "Reset" button that appears in the fault message box.

You can also reset the fault using the digital operator on the drive if SDWP001 is closed before the fault is cleared.

4.3.2 Fault History Display

You can view the current fault and any other faults that have already occurred using the History Display. The drive saves data on faults that have occurred, including the order in which the faults occurred, and information on the total operation time of the drive when the fault happened.

The Fault History lists the most recent faults first so that the most recent fault appears at the top of the list in the display window.

NOTE: SDWP001 keeps track of a maximum of ten faults. (The maximum number of faults that are displayed differs in accordance with the model used.)

Re	eset	Help	ß
ult His Er	story ase	Update	
No.	Name	Contents	Unit
- Mos	t recent fault	EF3:External Fault at Te	erminal
U	Frequenc	20.00	Hz
U	Output fre	20.00	Hz
- U	Output cu	0.28	А
- U	Motor spe	0.00	Hz
- U	Output vol	75.1	V
- U	DC bus v	327	VDC
- U	Output po	0.0	KVV
- U	Input termi	00000000 00000000	-
- U	Output ter	00000000 00000110	<u>6</u>
11	Operation	00000000 00110001	-

Below is an example of the data saved when a fault occurs:

	No.	Name	Contents	Unit		
Ð	Mos	t recent fault	EF3:External Fault at Te	erminal		
	U	Frequenc	20.00	Hz		
-	U	Output fre	20.00	Hz		
1	U	Output cu	0.28	А		
-	U	Motor spe	0.00	Hz		
	U	Output vol	75.1	V		
-	U	DC bus v	327	VDC		
		Output po		KVV		
-	U	Input termi 00000000 00000000	100			
	U	Output ter	Output ter 00000000 00000110	×		
ŀ	U	Operation	00000000 00110001	8		
ļ.,	U	Cumulativ	41	н		
1	U	Speed Re	20.00	%		
	Second most recent fault No Error OH					
	Third most recent fault No Error OH					
	Fourth most recent fault No Error OH					
	5th	Most Recent F	Fault No Error OH			
	6th	Most Recent F	Fault No Error OH			
	7th Most Recent Fault No Error 0H					

4.3.3 Clearing the Fault History

To erase the data saved to the Fault History, click "Delete".

NOTE: Depending on the drive, it may not be possible to erase data from previous faults.

Fault History			
Erase	Update	12	

Clicking "Erase" will generate the following warning message:



Click "Cancel" if you do not want to erase the information; SDWP001 will return to the Troubleshooting display. Clicking "OK" will clear the contents saved to the Fault History.

NOTE: After clearing the Fault History or other fault data, remove the cause of the fault and reset the fault using the digital operator on the drive. If the Fault History or fault data is erased before the fault is properly reset, the digital operator will indicate that the drive is ready operate the motor, although the cause of the fault still exists. In such occasions SDWP001 will indicate that a fault is still present.

4.3.4 Updating the Fault History

To update the Fault History display, click "Update".

Fault History		÷.
Erase	Update	
	1	

4.3.5 Saving the Fault History

To save the Fault History, use the Export function. Under "File", select "Export (E)".

V	Parameter file]
<u></u>	Oscilloscope file]
<u>×</u>	Pattern Operation file	
*	Trouble Shooting file	
×	Monitor Setting file	
<u>×</u>	Direct Parameter Setting file]

4.3.6 Reading the Fault History

If the drive is not connected to the PC, you can still view Troubleshooting data that was saved previously. Go the Main Menu, select "View (\underline{V})", and then click "Troubleshooting". You can also go to "File (<u>F</u>)" in the Main Menu, and then select "Import (<u>I</u>)". The following window will appear:

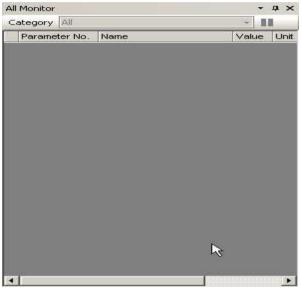
Import			×
Please select	t file type.		
	24	Parameter file	
	*	Oscilloscope file	
	<u>×</u>	Pattern Operation file	
	1	Trouble Shooting file	
	*	Monitor Setting file	
	<i>.</i>	Direct Parameter Setting file	
File name:			b
		OK E	Cancel

4.4 Monitor

Monitors allow you to view various aspects of drive performance including operation status and I/O signal settings. There are five types of Monitor displays: All Monitors, User Monitors, I/O Monitors, Status Monitors, and Operation Monitors.

4.4.1 All Monitors

When the drive is connected, a window displaying all monitor items will appear automatically. If the drive is not connected, the window will appear blank as shown below:



<All Monitors Display Window (Drive Offline)>

When the drive is connected, all monitor items will appear automatically as shown in the screen below. When a Project is open and a drive is connected, monitor items will appear in the order that they have been saved to the Project.

Ca	ategory All		- 00				
	Parameter	Name	Value	Unit	Max	Min	
	U1-01	Frequency reference	0.00	Hz	0.00	0.00	122
•	U1-02	Output frequency	0.00	Hz	0.00	0.00	
V	U1-03	Output current	0.00	A	0.00	0.00	
V	U1-04	Control method	0		0	0	
V	U1-05	Motor speed	0.00	Hz	0.00	0.00	
V	U1-06	Output voltage	0.0	VAC	0.0	0.0	
•	U1-07	DC bus voltage	227	VDC	227	227	
•	U1-08	Output power	0.00	kW	0.00	0.00	
•	U1-10 - 00	Terminal S1	Open		-	-	
•	U1-10 - 01	Terminal S2	Open		-	-	
•	U1-10 - 02	Terminal S3	Open		5	0	
•	U1-10 - 03	Terminal S4	Open		2	1	
•	U1-10 - 04	Terminal S5	Open		-		
•	U1-10 - 05	Terminal S6	Open		-	-	
•	U1-10 - 06	Terminal S7	Open		-	-	
•	U1-11 - 00	Terminal Output(Terminal MA/	Open		-	-	
1	U1-11 - 01	Photocoupler 1(Terminal P1)	Open		-	-	
•	U1-11 - 02	Photocoupler 2(Terminal P2)	OFF		-	-	
V	U1-12 - 00	During Run	Stopp		5	- C	
V	U1-12 - 01	During zero speed	At zer		2	1	
V	U1-12 - 02	During reverse	Forw		-	-	
V	U1-12 - 03	During external reset signal i			-	-	
•	U1-12 - 04	During speed agree			-	-	
V	U1-12 - 05	Inverter ready	Ready		-	-	
V	U1-12 - 06	Minor Fault			-	-	
•	U1-12 - 07	Major Fault			-	-	
•	U1-13	Terminal A1 input voltage level	0.0	%	0.0	0.0	
V	U1-14	Terminal A2 input voltage level	0.0	%	0.0	0.0	
•	U1-16	Output frequency after soft	0.00	Hz	0.00	0.00	10

<All Monitors Display Window (Drive Online)>

If the drive is disconnected, then monitors will appear as shown below:

Ca	tegory All						
	Parameter	. Name	Value	Unit	Max	Min	
~	U1-01	Frequency reference	0.00	Hz	0.00	0.00	l
4	U1-02	Output frequency	0.00	Hz	0.00	0.00	I
~	U1-03	Output current	0.00	A	0.00	0.00	l
~	U1-04	Control method	0		0	0	I
1	U1-05	Motor speed	0.00	Hz	0.00	0.00	I
2	U1-06	Output voltage	0.0	VAC	0.0	0.0	ł
1	U1-07	DC bus voltage	227	VDC		227	ł
~	U1-08	Output power	0.00	kW	0.00	0.00	l
1		Terminal S1	Open				ł
2	U1-10 - 01	Terminal S2	Open		*	-	l
1	U1-10 - 02	Terminal S3	Open	1			l
2	U1-10 - 03	Terminal S4	Open				ł
1	U1-10 - 04	Terminal S5	Open				l
1		Terminal S6	Open				ł
1	U1-10 - 06	Terminal S7	Open				ł
1		Terminal Output(Terminal MA/	Open				ł
2	U1-11 - 01	Photocoupler 1(Terminal P1)	Open				ł
1	U1-11 - 02	Photocoupler 2(Terminal P2)	OFF				ł
1	U1-12 - 00	During Run	Stopp				l
/	U1-12 - 01	During zero speed	At zer				l
1		During reverse	Forw				l
1	U1-12 - 03	During external reset signal i			1	-	I
2	U1-12 - 04	During speed agree			-	-	I
~	U1-12 - 05	Inverter ready	Ready				I
1	U1-12 - 06	Minor Fault			-		l
1	U1-12 - 07	Major Fault					l
~	U1-13	Terminal A1 input voltage level	0.0	%	0.0	0.0	l
2	U1-14	Terminal A2 input voltage level	0.0	%	0.0	0.0	l
1	U1-16	Output frequency after soft	0.00	Hz	0.00	0.00	l

<All Monitors Display Window (Drive Connection Interrupted)>

Main Screen Display

Select the type of monitors that are displayed as described below.

Monitors can be arranged and displayed using the combo-box in the Monitor display window.

	Monitor							#	^
	1997 - 1 997 - 1997	All			U				
1	Parame	All		de	Unit	Max	Min	A	-
	Control Providence	Input Output							
~	U1-02	Motion							
		Status				-			
2	114 04		Control method						

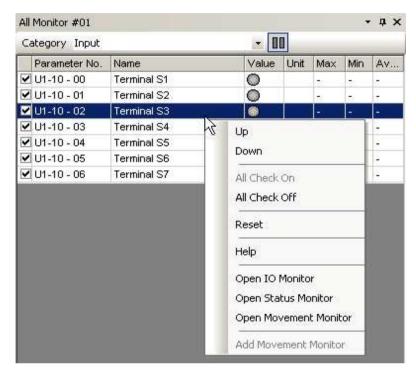
This example shows the Monitor display after selecting to view Input monitors.

Category Input		. 0				
Parameter No	. Name	Value	Unit	Max	Min	Av
🗹 U1-10 - 00	Terminal S1	0		-	-	-
🗹 U1-10 - 01	Terminal 2 Terminal S3	0		5 8	58	<u>.</u>
🗹 U1-10 - 02	Terminal S3	0		18	8	
🗹 U1-10 - 03	Terminal S4	0		50	50	-
🗹 U1-10 - 04	Terminal S5	0		83	83	<u>.</u>
🗹 U1-10 - 05	Terminal S6	0		£	2	-
🗸 U1-10 - 06	Terminal S7			- St.	2	-

NOTE: When changing between input and output monitor displays, SDWP001 maps out the I/O settings.

Setting the order in which monitors are displayed

Right-click on the monitor items selected in the monitor screen and select the desired order from the popup menu.



<Selecting Monitor Order>

Category Input		- 8				
Parameter No.	Name	Value	Unit	Max	Min	Av
🗹 U1-10 - 00	Terminal S1	0		-	-	-
🗹 U1-10 - 02	Terminal S3	0		7	5	-
🗹 U1-10 - 01	Terminal S2	0		10	8	
🗹 U1-10 - 03	Terminal S4	0		50	-	1.
🗹 U1-10 - 04	Terminal S5	0		83	83	12
🗹 U1-10 - 05	Terminal S6	0		<u>s</u>	<u>s</u>	i.
🗹 U1-10 - 06	Terminal S7	0		4	4	1

<After Selecting the Order>

Another way to select the order of the monitors is to select the monitor and use the Shift and \uparrow or \downarrow keys. It is also possible to use the mouse to drag and drop monitors in the desired order.

Monitor Status Display

To display specific monitors, click on the check box located in the far left column of each row. To select all monitors right-click on the window and select "Check All" from the pop-up menu.

All Monitor						7	ų,	×
Category All			- 1					
Parameter	No. Name	9	Value	Unit	Max	Min	A	
U1-01	Frequ	uency reference	-		-	-	-	
🗌 U1-02	Outp	ut frequency			58	28	-	
🗌 U1-03	Outp	ut current	100		18	18	-	
U1-04	Contr	rol method	8		55	55	-	
U1-05	Moto	r speed	8		88	88	4	

Monitors that have been checked will display data in each column.

All Monitor					Z	д	×
Category All		- 1	0				
Parameter No.	Name	Value	Unit	Max	Min	A	
V1-01	Frequency reference	0.00	Hz	0.00	0.00	0.	
LJ1-02	Output frequency	8		5 8	58	i.	
🗌 U1-03	Output current	æ		3	3	-	
🗌 U1-04	Control method	*		50	50	-	
U1-05	Motor speed	8		83	83	4	

NOTE: The first display screen shows all monitors as checked and has all data displayed.

Hold

By clicking the "Hold" button, the values displayed in the monitor will no longer be refreshed. To update the data that is currently frozen, click "Hold" again.

Tool Tips

If the mouse pointer rests on one of the monitors, a "tool tip" will appear listing monitor data.

All	Monit Max	ue : 0.00[Hz] : 0.00[Hz] : 0.00[Hz]					- д			
Ca		rage : 0.00[Hz]		- 00						
J	Paramete /	Name	Value	Unit	Max	Min	Ave			
~	U1-01	Frequency refere	0.00	Hz	0.00	0.00	0.00			
~	U1-02	Output frequency	0.00	Hz	0.00	0.00	0.00			
•	U1-03	Output current	0.00	A	0.00	0.00	0.00			
~	U1-04	Control method	0		0	0	0			
~	U1-05	Motor speed	0.00	Hz	0.00	0.00	0.00			
~	U1-06	Output voltage	0.0	VAC	0.0	0.0	0.0			
~	U1-07	DC bus voltage	227	VDC	227	227	227			
~	U1-08	Output power	0.00	kW	0.00	0.00	0.00			
~	U1-10 - 00	Terminal S1	Open		-	120	-			
~	U1-10 - 01	Terminal S2	Open		-		-			
4	U1-10 - 02	Terminal S3	Open		-		-			
~	U1-10 - 03	Terminal S4	Open		-		-			
~	U1-10 - 04	Terminal S5	Open		-	-	-			
~	U1-10 - 05	Terminal S6	Open		-	-	-			
~	U1-10 - 06	Terminal S7	Open		-	141	-			
~	U1-11 - 00	Terminal Output(Te	Open		-	-	-			
~	U1-11 - 01	Photocoupler 1(Te	Open		27	12	2			
~	U1-11 - 02	Photocoupler 2(Te	OFF		-	1-1	-			
~	U1-12 - 00	During Run	Stopp.		-	-	-			

Column Heading

Parameter No	. Name	Value	Unit	Max	Min	Average
🗹 U1-01	Frequency reference	0.00	Hz	0.00	0.00	0.00
🗹 U1-02	Output frequency	0.00	Hz	0.00	0.00	0.00
🗹 U1-03	Output current	0.00	А	0.00	0.00	0.00
🗹 U1-04	Control method	0		0	0	0
🗹 U1-05	Motor speed	0.00	Hz	0.00	0.00	0.00
🗹 U1-06	Output voltage	0.0	VAC	0.0	0.0	0.0

Column headings describe the type of data listed in the column.

You can move columns by using the mouse to drag and drop the columns into the desired order.

Parameter No.	Value	Name	Unit	Max	Min	Average
🗹 U1-01	0.00	Frequency reference	Hz	0.00	0.00	0.00
🗹 U1-02	0.00	Output frequency	Hz	0.00	0.00	0.00
🗹 U1-03	0.00	Output current	A	0.00	0.00	0.00
🗹 U1-04	0	Control method		0	0	0
🗹 U1-05	0,00	Motor speed	Hz	0.00	0.00	0.00
🗹 U1-06	0.0	Output voltage	VAC	0.0	0.0	0.0

Right-clicking on a column head displays a pop-up menu that lets you hide or show certain columns.

Parameter No.	Value	Name	_	1	Unit	Max	Min	Average
🗹 U1-01	0.00	Frequenc	~	Name	Hz	0.00	0.00	0.00
🗹 U1-02	0.00	Output fre	4	Unit	Hz	0.00	0.00	0.00
🗹 U1-03	0.00	Output cu	~	Max	A	0.00	0.00	0.00
✓ U1-04	0	Control me	~	Min		0	0	0
🗹 U1-05	0.00	Motor spe	0.28	Concernance and Concernance of Conce	Hz	0.00	0.00	0.00
🗹 U1-06	0.0	Output vo	~	Average	VAC	0.0	0.0	0.0
🗹 U1-07	323	DC bus vo	tage	9	VDC	324	322	322

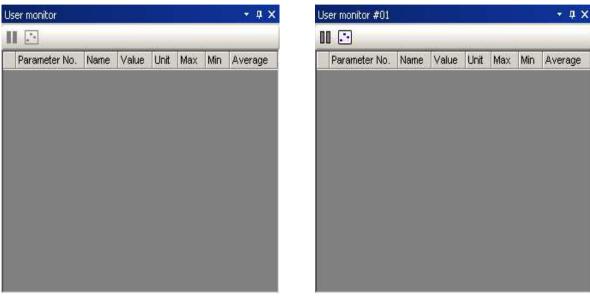
The following example shows how to hide a column:

Paramet	er No.	Value	Name	Max	Average
✔ U1-01	V N	ame	Frequency reference	0.00	0.00
✔ U1-02	- 11	nit	Output frequency	0.00	0.00
✔ U1-03		0.407	Output current	0.00	0.00
✓ U1-04	M	lax	Control method	0	0
🗹 U1-05	M	lin	Motor speed	0.00	0.00
✔ U1-06	- A	verage	Output voltage	0.0	0.0
✔ U1-07		324	DC bus voltage	324	322

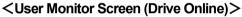
4.4.2 User Monitor

User Monitors can be selected and displayed using the Monitor Setting Dialog.

If the drive is not connected when the User Monitor is displayed, a window that looks like this will appear: When the drive is first connected, the display will initially be blank.



<User Monitor Screen (Drive Offline)>



If the drive is connected while a Project is open, then the monitor items that were previously saved to that Project will appear as shown below:

00 🖸						
Parameter No.	Name	Value	Unit	Max	Min	Average
V1-01	Freq	0.00	Hz	0.00	0.00	0.00
🗹 U1-02	Outp	0.00	Hz	0.00	0.00	0.00
🗹 U1-03	Outp	0.00	A	0.00	0.00	0.00
🗹 U1-04	Cont	0		0	0	0
✓ U1-06	Outp	0.0	VAC	0.0	0.0	0.0

<User Monitor Screen (Drive Connected while Project is Open)>

If the drive is suddenly disconnected, then the monitor items will appear as follows:

Į,	Parameter No.	Name	Value	Unit	Max	Min	Average
•	U1-01	Freq	0.00	Hz	0.00	0.00	0.00
~	U1-02	Outp	0.00	Hz	0.00	0.00	0.00
~	U1-03	Outp	0.00	A	0.00	0.00	0.00
~	U1-04	Cont	0		0	0	0
~	U1-06	Outp	0.0	VAC	0.0	0.0	0.0

<User Monitor Screen (Drive Connection Interrupted)>

Main Screen Display

To select the order in which User Monitors are displayed, follow the instructions below.

1) Right-click on the "User Monitor" in the Function Tree to open the pop-up menu as shown:



2) Select "Monitor item setting" and the following window will appear:

All Input Dutput Motion Status	U1-05:Motor speed U1-07:DC bus voltage U1-08:Output power U1-10-00:Terminal S1 U1-10-01:Terminal S2 U1-10-02:Terminal S3 U1-10-03:Terminal S4 U1-10-04:Terminal S5 U1-10-06:Terminal S6 U1-10-06:Terminal S7 U1-11-00:Terminal Output/Terminal	Add all Add Add Add Add Add	U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-06:Output voltage
--	--	--	---

3) A list of monitor items and categories will appear.

All Input Output Motion Status	U1-10-00:Terminal S1 U1-10-01:Terminal S2 U1-10-02:Terminal S3 U1-10-03:Terminal S4 U1-10-04:Terminal S5 U1-10-05:Terminal S6 U1-10-06:Terminal S7	Add all	U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-06:Output voltage
		- Delete	

4) Select the item(s) you wish to display and click "Add".

All Input Output Motion Status	U1-10-00:Terminal S1 U1-10-01:Terminal S2 U1-10-02:Terminal S3 U1-10-03:Terminal S4	Add all Add Add Add Add Add	U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-06:Output voltage U1-10-06:Terminal S7 U1-10-05:Terminal S6 U1-10-04:Terminal S5
--	--	--	---

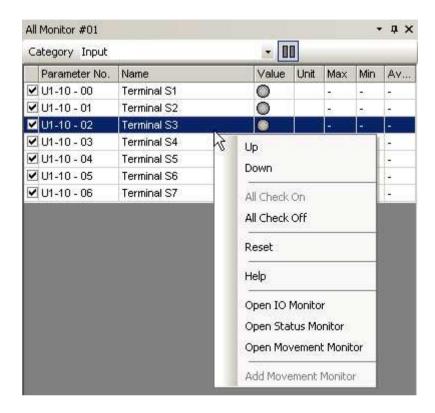
5) Click "OK". Items selected will then appear in the User Monitor screen.

00		102 75					
P	arameter No.	Name	Value	Unit	Max	Min	Average
٧U	1-01	Freq	0.00	Hz	0.00	0.00	0.00
٧U	1-02	Outp	0.00	Hz	0.00	0.00	0.00
٧U	1-03	Outp	0.00	А	0.00	0.00	0.00
٧U	1-04	Cont	0		0	0	0
٧U	1-06	Outp	0.0	VAC	0.0	0.0	0.0
٧U	1-10 - 06	Term	Open		s.	<u>s</u>	-
٧U	1-10 - 05	Term	Open		4	4	-
V U	1-10 - 04	Term	Open		24	2	2

Double-clicking on items in the User Monitor window will also display monitor items.

Setting the order in which monitors are displayed

Right-click on the monitor items selected in the monitor screen and select the desired order from the popup menu.



Category Input		- 8				
Parameter No	Name	Value	Unit	Max	Min	Av
🗹 U1-10 - 00	Terminal S1	0		-	-	-
🗹 U1-10 - 02	Terminal S3			5	5	-
🗹 U1-10 - 01	Terminal S2	0		10	*	
🗹 U1-10 - 03	Terminal S4	0		50	50	
🗹 U1-10 - 04	Terminal S5	0		83	83	2
🗹 U1-10 - 05	Terminal S6	0		s)	s)	÷.
🗹 U1-10 - 06	Terminal S7	0		4	4	4

Another way to select the order of the monitors is to select the monitor and use the Shift and \uparrow or \downarrow keys together.

It is also possible to use the mouse to drag and drop monitors in the desired order.

Monitor Status Display

To display specific monitors, click on the check box located in the far left column of each row. To select all monitors right-click on the window and select "Check All" from the pop-up menu.

Category All		- 8					
Parameter No.	Name	Value	Unit	Max	Min	A	
U1-01	Frequency reference	-		-	-	-	
🗌 U1-02	Output frequency	2		1 20	7 8	ļ.	
U1-03	Output current			-	18		
🗌 U1-04	Control method	8		55	55	1.	
U1-05	Motor speed	8		83	83	-	
U1-06	Output voltage	1.4		÷.	<u>s</u> .	4	

Monitors that have been checked will display data in each column.

Category All	144	× 00					
Parameter No.	Name	Value	Unit	Max	Min	A	
C U1-01	Frequency reference	0.00	Hz	0.00	0.00	0.	
Liju1-02	Output frequency	5		1 23	5	÷	
🗌 U1-03	Output current	1.0		3	3	-	
🗌 U1-04	Control method			50	50	-	
🗌 U1-05	Motor speed	8		83	83	4	
🗌 U1-06	Output voltage	1.2		s)	s)	-	
🗌 U1-07	DC bus voltage	12		4	4	-	
U1-08	Output power	1.2		20	22	1	

The first display screen shown has all monitors checked and all data displayed.

Hold

By clicking "Hold", the values displayed in the monitor will no longer be refreshed. To update the data that is currently frozen, click "Hold".

Tool Tips

If the mouse pointer rests on one of the monitors, a "tool tip" will appear listing monitor data.

2,111	Monitor #01 ategory All	Name : F Value : 0 Max : 0.0 Min : 0.0)0[Hz]	0.078550			→[• ŋ	×
	Parameter No.	Name	Value	Unit	Max	Min	Aver	
•	U1-01	Frequency reference	0.00	Hz	0.00	0.00	0.00	
•	U1-02	Output frequency	0.00	Hz	0.00	0.00	0.00	
~	U1-03	Output current	0.00	A	0.00	0.00	0.00	
•	U1-04	Control method	0		0	0	0	

Column heading

Parameter No.	Name	Value	Unit	Max	Min	Average
🗹 U1-01	Frequency reference	0.00	Hz	0.00	0.00	0.00
✓ U1-02	Output frequency	0.00	Hz	0.00	0.00	0.00
🗹 U1-03	Output current	0.00	А	0.00	0.00	0.00
✓ U1-04	Control method	0	i î	0	0	0
✓ U1-05	Motor speed	0.00	Hz	0.00	0.00	0.00

Column headings describe the type of data listed in the column.

You can move columns by using the mouse to drag and drop the columns into the desired order.

Parameter No.	Value	Name	Unit	Max	Min	Average
🗹 U1-01	0.00	Frequency reference	Hz	0.00	0.00	0.00
✔ U1-02	0.00	Output frequency	Hz	0.00	0.00	0.00
🗹 U1-03	0.00	Output current	А	0.00	0.00	0.00
✓ U1-04	0	Control method		0	0	0
✓ U1-05	0.00	Motor speed	Hz	0.00	0.00	0.00

Right-clicking on a column head displays a pop-up menu that lets you hide or show certain columns.

Parameter No.	Value	Name T	-	6	Unit	Max	Min	Average
🗹 U1-01	0.00	Frequenc	~	Name	Hz	0.00	0.00	0.00
✓ U1-02	0.00	Output fre	~	Unit	Hz	0.00	0.00	0.00
🗹 U1-03	0.00	Output cu	<	Max	A	0.00	0.00	0.00
🗹 U1-04	0	Control me	~	Min		0	0	0
🗹 U1-05	0.00	Motor spe		Constanting and the	Hz	0.00	0.00	0.00
🗹 U1-06	0.0	Output vo	~	Average	VAC	0.0	0.0	0.0
🗹 U1-07	323	DC bus vot	tage		VDC	324	322	322

The following example shows how to hide a column.

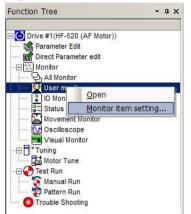
Parameter	No. Value	Name	Max	Average
✔ U1-01	Name	Frequency reference	0.00	0.00
✔U1-02	Unit	Output frequency	0.00	0.00
✓ U1-03		Output current	0.00	0.00
🗹 U1-04 📘	Max Max	Control method	េ	0
🗹 U1-05	Min	Motor speed	0.00	0.00
✔ U1-06	Average	Output voltage	0.0	0.0
🖌 U1-07	324	DC bus voltage	324	322

Add or remove a Monitor Address

SDWP001 lets you add a MEMOBUS/Modbus address to the monitor items to view user-selected parameters.

To add or delete a monitor address, follow the instructions below:

1) Right-click on "User Monitor" in the Function Tree.



2) Click "Monitor item setting" and the following window will appear

All Input Output Motion Status	U1-10-00:Terminal S1 U1-10-01:Terminal S2 U1-10-02:Terminal S3 U1-10-03:Terminal S4	Add all Add all Add Add U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-06:Output voltage U1-10-06:Terminal S7 U1-10-04:Terminal S5 Elefete Elefete	
--	--	---	--

3) Click "Add/Remove Address" to open the following window:

Address Setting	10	
)isplay Type:	Hex	
Nonitoring Address	:	н
lit Address;		(0to15)
)atasize:	2Byte	-
nitor entry list		Add

4) Enter the necessary items and click "Add". If the addresses entered can be accessed, then those items will be added to the list of monitors.

If access is not possible, a message will appear that indicates that the address entered is not allowed. Click "OK" to return to the "Add/Delete Monitor Address" window.



5) Clicking "OK" in the "Add/Remove Address" window will return you to the Monitor Item Setting window. Any added monitors will now be listed.

All Input Output Motion Status	U6-82:Option Monitor 3 U6-83:Option Monitor 4 U6-84:Option Monitor 5 U6-85:Option Monitor 6 U6-86:Option Monitor 7 U6-87:Option Monitor 8 U6-88:Option Monitor 9 U6-89:Option Monitor 10 U1-28:Message ID(Inverter) MEMOBUS@2:04BBH	 Add all Add → Add ← Delete Æ Delete all 	U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-06:Output voltage U1-10-05:Terminal S6 U1-10-04:Terminal S5 U1-10-03:Terminal S4
--	--	---	---

4.4.3 I/O Monitor

I/O monitors display the status of any input and output terminals that have been selected. The following window will appear automatically whenever the drive is connected to SDWP001:

Close Project

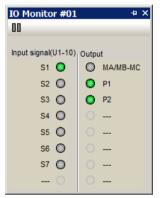
When the drive is not connected, the window will appear blank:

IO Monitor #01	. ⇔×
00	
Input signal(U1-10)	Output
S1 🔘	MA/MB-MC
S2 🔘	O P1
S3 🔘	P2
S4 🔘	0
S5 🔘	0
S6 🔘	0
S7 🔘	0
0	0

<I/O Monitor Screen (Drive Offline)>

Drive Online

When the drive is connected, the following window will appear automatically:



<I/O Monitor Screen (Drive Online)>

Project Open

If a Project is open and the connection with the drive is suddenly interrupted, the window will appear as follows:

IO Monitor #01	- + X
Input signal(U1-10)	Output
S1 🔘	MA/MB-MC
S2 🔘	O P1
S3 🔘	P2
S4 🔘	0
S5 🔿	0
S6 🔿	0
S7 🔿	0
- 0	0

<I/O Monitor Screen (Drive Connection Interrupted)>

Main Screen Display

All monitor items appear automatically when viewing the I/O Monitor window.

I/O data will appear much like an LED display, indicating the terminal name and the current input/output status.

IO Monitor #01		×₽
Input signal(U1-10)	Outpu	ıt
S1 🥥	\bigcirc	MA/MB-MC
S2 🔘	٥	P1
S3 🔘	0	P2
S4 🔘		
S5 🔘		
S6 🔘		
S7 🔘		
0		

Display Status Switch

By clicking 📮 in the Title Bar, you can switch the display status.

Auto-Reveal Monitor Status 📮

All items are usually displayed.

IO Monitor #01	μ×	
00		
Input signal(U1-10)	Output	
S1 🔘	MA/MB-MC	
S2 🔘	O P1	
S3 🔘	O P2	
S4 🔘	0	
S5 🔘	0	
S6 🔘	0	
S7 🔘	0	
0	0	
	/eal Status 🧧	

Auto-Hide Monitor Status 😐

When the display is hidden, the icon in the title bar will appear sideways. Click on the icon to reveal the entire window.

IO Monitor #01 + X				
ţ	· 1			
IO Monitor #01	+ ×			
00				
Input signal(U1-10)	Output			
S1 🔘	МА/МВ-МС			
S2 🔘	O P1			
S3 🔘	O P2			
S4 🔘	0			
S5 🔘	0			
S6 🔘	0			
S7 🔘	0			
0	0			
 <auto-hid< th=""><th>de 😐 ></th></auto-hid<>	de 😐 >			

Monitor Start/Stop

Clicking [] ("Monitor Start/Stop") will freeze the monitors at their current values. Click [] again to update the monitors with data from the drive.

Tool Tips

If the mouse pointer rests on one of the monitors, a "tool tip" will appear listing monitor data.

Parameter No.: U1-10 - 00 Name : Terminal S1 Value : Open Max : - Min : - Average : -				1 - 00			→ [] • # ×
	Parameter No.	Nam	Value	Unit	Max	Min	Average
2	U1-10 - 00	Terminal S1	Open		-	-	-
•	U1-10 - 02	Terminal S3	Open		-	-	
~	U1-10 - 03	Terminal S4	Open		-	-	-
~	U1-10 - 04	Terminal S5	Open		-3	-3	-3

4.4.4 Status Monitor

Status Monitors provide information on the operation status of the drive. When the drive is first connected, the Status Monitor window is automatically opened.

Project Closed

When the Status Monitor is first opened, it will appear blank:

<u> </u>
-

<Status Monitor Window (Drive Offline)>

Drive Online

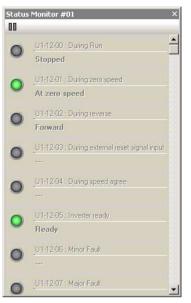
When the drive is connected, SDWP001 will display the following window.



<Status Monitor Window (Drive Online)>

Project Open

If the connection with the drive is suddenly interrupted, the Status Monitor window will appear as follows:



<Status Monitor Screen (Drive Connection Interrupted)>

Main Screen Display

Status Monitor automatically displays all monitor items. Monitor numbers and names appear along side an LED-type of display:



Monitor Start/Stop

Clicking ("Monitor Start/Stop") will freeze the monitors at their current values. Click again to update the monitors with data from the drive.

4.4.5 Movement Monitor

Movement Monitor displays the data selected in the Monitor Setting dialog box.

Project Closed

When a Project is first opened but no drive is connected, the Movement Monitor will appear blank:

Movement Monitor	- ‡ X
Column Auto	· II 🖸

<Movement Monitor Screen (Drive Offline)>

When Drive is Online

When the drive is first connected, the Movement Monitor window will appear blank:

Column Auto	
Movement Monitor #01	占All Monitor #01 /

<Movement Monitor Screen (Drive Online)>

As monitor items are added, the Movement Monitor window will appear like this:

Movement Monitor #01	• # X
Column Auto	- 00 💽
1-01(Frequency reference	U1-02(Output frequency)
	I DEGENOR
U1-03(Output current)	U1-04(Control method)
U1-05(Motor speed)	U1-06(Output voltage)
Movement Monitor #	+01 / 纪 All Monitor #01 /

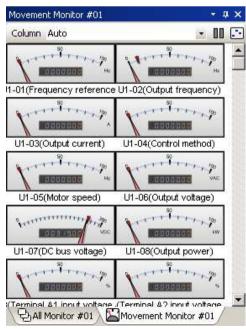
<Movement Monitor Screen (Drive Online, Monitors Items Added)>

Drive Connected and Project Opened

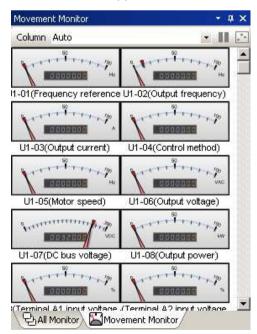
When the drive is connected and a Project is already opened, the monitor items that were already saved to the Project will automatically appear:

Project Open

If the drive connection is suddenly interrupted, the Movement Monitor will appear as follows:



<Movement Monitor Screen> (Drive Online and Project Open)

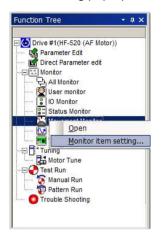


<Movement Monitor Screen> (Drive Connection Interrupted)

Main Screen Display

To display monitor items in the Movement Monitor window, follow the instructions below. Each item selected will appear in the Movement Monitor with the monitor name, item, and a graphic meter display.

1) Right-click on "Movement Monitor" in the function tree. The following pop-up menu will appear:



2) Select "Open Monitor Item Setting" to generate the following window:

ion	U1-01:Frequency reference		
	U1-02:Output frequency		
	U1-03:Output current	🚔 Add all	
	U1-04:Control method		
	U1-05:Motor speed	Add	
	U1-06:Output voltage		
	U1-07:DC bus voltage		
	U1-08:Output power		
	U1-13:Terminal A1 input voltage lev	- Delete	
	U1-14:Terminal A2 input voltage lev	- Delete	
	U1-16:Output frequency after soft	🪈 Delete all	

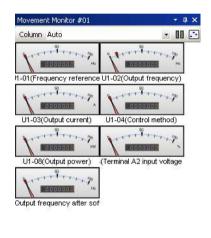
Select the items you would like to appear in the Movement Monitor window.
 NOTE: Parameter categories that set monitor items do not need to be selected.

Motion	U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-05:Motor speed U1-06:Output voltage U1-07:DC bus voltage U1-08:Output power U1-13:Terminal A1 input voltage lev U1-14:Terminal A2 input voltage lev U1-14:Terminal A2 input voltage lev	Add all Add Add Add Delete E Delete all	
--------	---	---	--

4) Click "Add".

Motion	U1-06:Output voltage U1-07:DC bus voltage U1-13:Terminal A1 input voltage lev U1-18:OPE fault constant U1-24:Input pulse monitor U1-25:Software No. (flash memory	Add all	U1-01:Frequency reference U1-02:Output frequency U1-03:Output current U1-04:Control method U1-08:Output power U1-14:Terminal A2 input votage level
	U1-26:Software No. (ROM) U2-01:Current fault U2-02:Last fault U2-03:Frequency reference at fau U2-04:Output frequency at fault	🖛 Delete	U1-16:Output frequency after soft-star

5) Click "OK" and the selected items will now appear in the Movement Monitor window.



All Monitor #01

You can also double-click on the Movement Monitor window to select items to add.

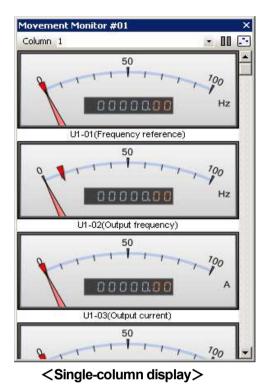
Right-clicking on "All Monitors" or "User Monitors" will generate a pop-up window that lets you add that monitor to the Movement Monitor window.

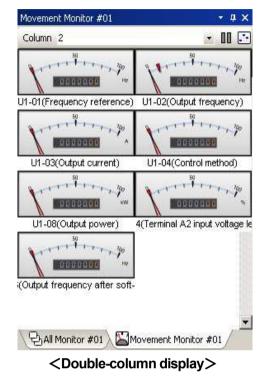
When the row selected is not part of the Movement Monitor, the pop-up menu will offer the option to disable the monitor.

Category	Category All			- 00
	eter No.	Value	Name	
✓ U1-01		0.00 Frequen		cy reference
✓ U1-02		0.00	Output fr	equency
✓ U1-	Up			rent
VU1-	Dowr			thod
✓ U1-				ed
✔ U1-	All C	neck On		tage
✓ U1-	All CI	neck Off		Itage
✓ U1-		17710341		-ver
✓ U1-	Rese	t		1
✓ U1-	1			2
VU1-	Help			3
✓ U1-	Oper	Open IO Monitor		4
✔ U1-	01686613			5
✓ U1-	Oper	n Status M	lonitor	6
✔ U1-	Oper	n Moveme	nt Monitor	7
⊻ U1-	Add	Movement	t Monitor	ler 1(Terminal
•				- <u>></u>

Arranging the Operation Status Display into Columns

A drop-down menu lets you arrange the Operation Status meters into a single column or multiple columns.





Movement Mo	nitor #01		- # X
Column 4		a 1415 1	× 00 🗈
Variation of	Lemmes'	Variation of	Vaning
U1-01	U1-02	U1-03	U1-04
Variation 2	V	Lange S	
U1-08	U1-14	U1-16	



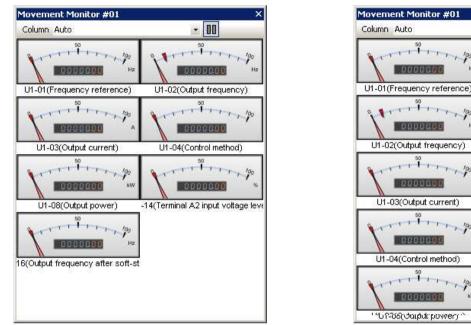
<Four-column display>

Resize

The size of the Movement Monitor window will change depending on how many columns have been selected.

Automatically Arrange Monitors

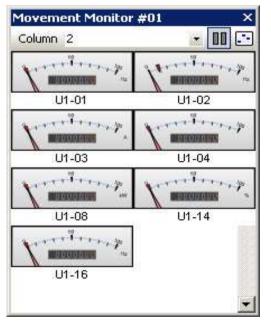
This automatically sets the size of the meter display to fit inside the window.



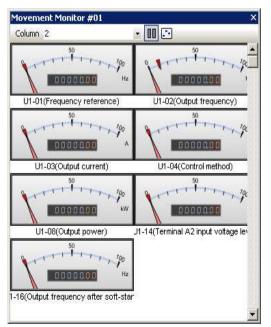
<Before Resizing(Number of Columns Set Automatically)> <After Resizing>

Adjusting the window size with a fixed number of columns

You can adjust the size of the meters by enlarging or shrinking the window where they appear. Here, the number of columns displayed will remain the same as the size of the window changes.



<Before Resizing> (Number of Columns Fixed)



*

<After Resizing>

Monitor Start/Stop

Clicking ("Monitor Start/Stop") will freeze the monitors at their current values. Click again to update the monitors with data from the drive.

Resetting the maximum value

Right-clicking on the Movement Monitor window will produce a pop-up menu. You can reset the maximum value displayed by selecting Reset in this menu.

Movement Monitor #01 Column 2	×
Reset	
U1-01(Free Help Ce)	U1-02(Output frequency)
U1-03(Output current)	U1-04(Control method)
10000000 ***	-14(Terminal A2 input voltage lev
6(Output frequency after soft-si	
	-

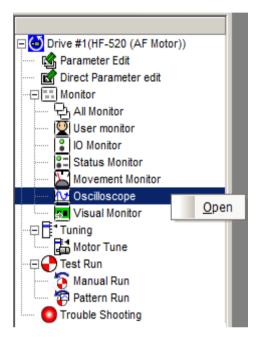
4.4.6 Oscilloscope

The oscilloscope function lets the user view and measure changes to various aspects of drive and motor performance over time.

Main Screen Display

To activate the Oscilloscope from the main screen, follow the instructions below.

1) Right-click on the Oscilloscope in the Function Tree and select Open from the pop-up menu.



2) If the drive is online, the following window will appear:

	Tir	ne-axis [ms/div] 100 Sampling (ycle [ms] 100		
1000	: : : : : : : : : : : : : : : : : : :		Cursi	or Move	1D/div 2 1D/div
	4			Þ	
 ist Display		Data Item No	Current Value		+ ‡ Maximu ▲
Display	Colors	Data Item No. U1-01 : Frequency reference	Current Value	Average Value	+ ⊅ Maximu ▲
l st Display ☑M:1 ☑M:2		Data Item No. U1-01 : Frequency reference U1-02 : Output frequency	Current Value		
Display ✔M:1		U1-01 : Frequency reference	Current Value		
Display ☑M:1 ☑M:2		U1-01 : Frequency reference U1-02 : Output frequency	Current Value		
Display ☑M:1 ☑M:2 ☑M:3		U1-01 : Frequency reference U1-02 : Output frequency	Current Value		
Display 2M:1 2M:2 2M:3 2M:3		U1-01 : Frequency reference U1-02 : Output frequency	Current Value		

Starting and stopping the monitor

1) Click on the bottom of the window and select the desired monitor from the pop-up window. NOTE: If the desired parameter is already part of the default display, then this step is not necessarv.

ecessary.	
1 2 _ 1	2 U1-01 : Frequency reference
	111-02 : Output frequency
n¥desktop¥2016	010(U1-03 : Output current
ACCOUNT OF A DESCRIPTION OF A DESCRIPTIO	U1_04 : Control method
/ 🖸 Oscilloscop	pe #Q U1-05 : Motor speed
	U1-06 : Output voltage
, Tir	ne-axi U1-07 : DC bus voltage
N:1 1.10	0. U1-08 : Output power
M:1 1.10 M:2 1.10 M:3 1.10	0 U1-13 : Terminal A1 input voltage level
M:3 1.10	U1-14 : Terminal A2 input voltage level
	U1-16 : Output frequency after soft-start
	U1-18 : OPE fault constant
	U1-24 : Input pulse monitor
	U1-25 : Software No. (flash memory)
	U1-26 : Software No. (ROM)
	🔶 U1-28 : Message ID(Inverter)
	U2-01 : Current fault
	U2-02 : Last fault
	- U2-03 : Frequency reference at fault
	U2-04 : Output frequency at fault
	U2-05 : Output current at fault
M:1 -1.10	U2-06 : Motor speed at fault
M:1 -1.10 M:2 -1.10 M:3 -1.10	00 U2-07 : Output voltage at fault
M:3 -1.10	02-06 ; DC bus voltage at fault
	U2-09 : Output power at Fault
	U2-11 : Input terminal status at fault
	U2-12 : Output terminal status at fault
1	U2-13 : Operation status at fault
1 <u>1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 </u>	U2-14 : Cumulative operation time at Fault
	U2-15 : Speed Reference during Fault at Soft Start
List	U2-16 : Motor q-Axis Current during Fault
LISC	
Display Color:	s U3-02 : Second most recent fault
	U3-03 : Third most recent fault
M:2	U3-04 : Fourth most recent fault
✓ M:2	U3-05 : 5th Most Recent Fault U3-06 : 6th Most Recent Fault
The second se	
□M:4	

2) From the display column, check the desired monitor item "MN(N = 1 - 16)".

Colors	Data Item No.	Current Value	Average Va
	U1-01 : Frequency reference		
	U1-02 : Output frequency		
	U1-03 : Output current		
	Colors	U1-01 : Frequency reference U1-02 : Output frequency	U1-01 : Frequency reference U1-02 : Output frequency

3) Monitors can be started either by selecting Monitor (M) from the Main Menu, or by clicking the moitor start button on the operation panel.

	-		Test Usta		
ect	1 <u>M</u> OL	hitor	Tool Help		
19	\triangleright	Star	t Monitor	F9	C
Stor		Stop	Monitor	F10	1





<Starting from the Main Menu>

<Using the Toolbar> <Using the operation panel>

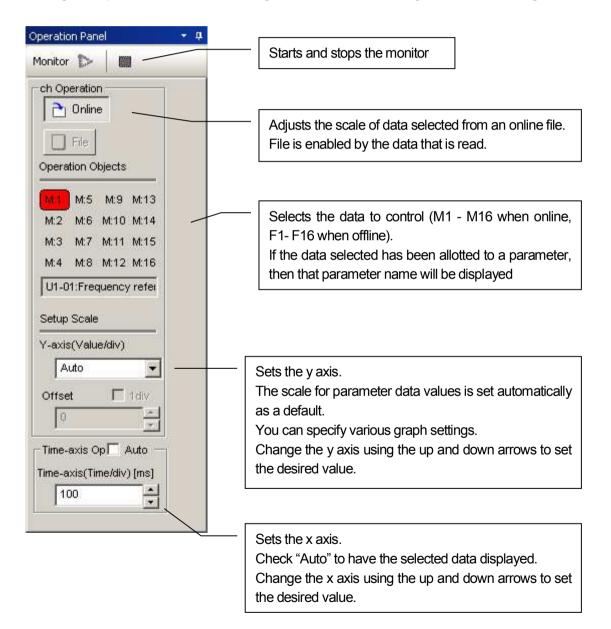
4) Monitors can be stopped either by selecting Monitor (M) from the Main Menu, the toolbar, or the operation panel.

: <u>M</u> o	nitor	<u>I</u> ool <u>H</u> el	þ
g Þ	Star	t Monitor	F9
	Stop	Monitor	F10

Monitor	5	000
MOLICOF	and a	683

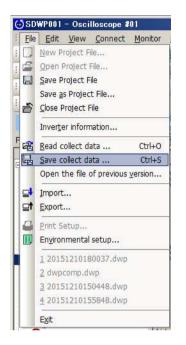
Operation Panel

Clicking the "Operation Panel" tab on the right side of the window will generate the following window:

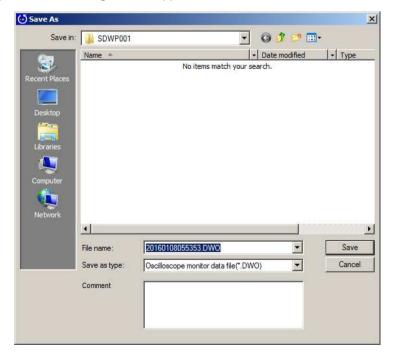


Saving and reading the data collected Saving data

- 1) Start the monitor and collect the desired data. Stop the monitor when finished.
- 2) Next select "Save collect data" from the File (F) menu, or click 4 on the toolbar.



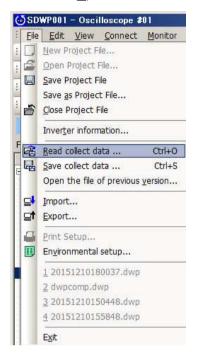
3) The save dialog box will appear. Enter a file name.



4) Click "Save" to save the data.

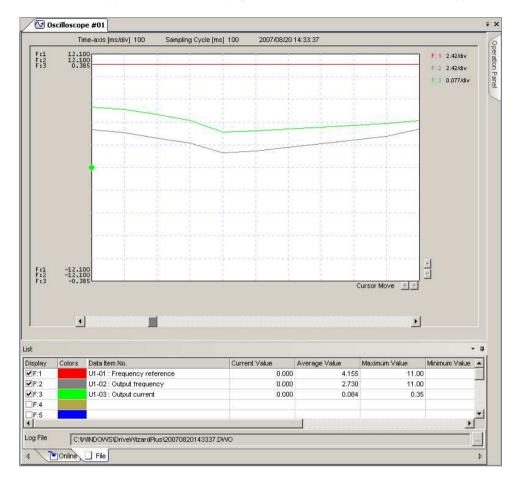
Reading data that has already been saved

1) From "File (<u>F</u>)", select "Read collect data" You can also click \mathbf{E} on the toolbar.



2) The following dialog box will appear. Select the desired file and click "Open".





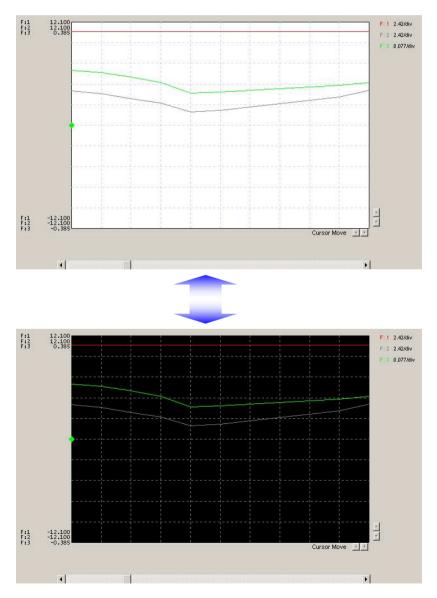
3) The file name appears on the list display, and the data read from the file will appear in the graph.

Switching Waveform Background Color

 Change the background color for the waveform by going to Edit (E) in the Main Menu or by clicking on

Edi	t <u>View Connect Monitor H</u> elp	
26	Change the Background Colors of Waveform	Ctrl+B
6	Copy the Waveform Image	Ctrl+G
‡∓	Calculate	Ctrl+C
Ô	<u>S</u> napshot	
1	Snapshot <u>Release</u>	Ctrl+R

Background color can be set to black or to white.

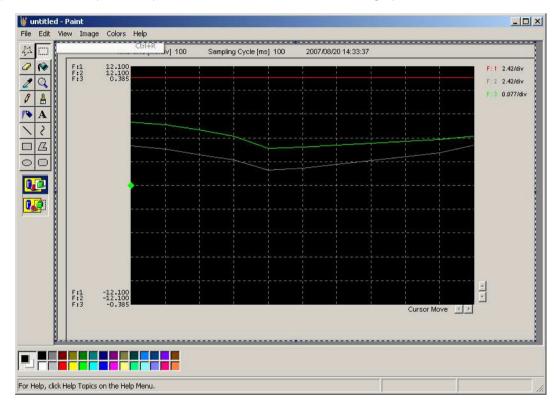


Waveform Image Copy

1) Go to Edit (E) in the Main Menu and select "Copy the Waveform Image", or click 🖄 in the Toolbar.

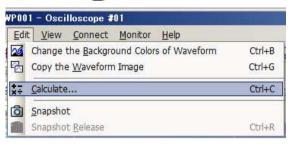
Edit	<u>View Connect Monitor Help</u>	
26	Change the Background Colors of Waveform	Ctrl+B
公	Copy the <u>W</u> aveform Image	Ctrl+G
‡∓	<u>C</u> alculate	Ctrl+C
Ô	Snapshot	
	Snapshot <u>Release</u>	Ctrl+R

2) You can then paste the picture into Microsoft® Paint or another graphics editor.



Data Calculation Functions

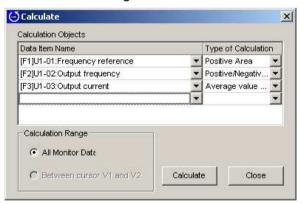
1) Go to the Edit (E) menu and select "Calculate". You can also click on ‡ in the Toolbar.



2) The Calculate dialog box will appear.

Data Item Name		Type of Calcu	lation
	•		-
	-		-
			-
			-
Calculation Range			

3) Use the drop-down menu to select the parameter in the Data column, and then the type of calculations on the right.



4) Click "Calculate" to generate the graph as shown below.

F:2	-12.100						
1.5	F: 1 Plus Area 206075	F: 2 P-M Area	135390.8751	FIG ABS Avo	0.084	Cursor Move 🗾	×
	۲.						

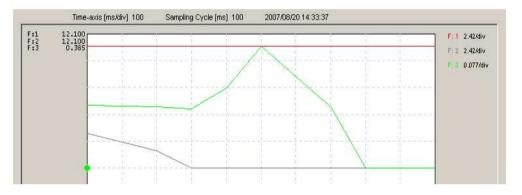
NOTE: Use the cursor to have SDWP001 calculate values within a specified range in the graph.

Taking and Clearing a Snapshot

1) Go to Edit in the Main Menu and select "Snapshot". You can also click on 🙆 in the Toolbar.

Edi	t <u>V</u> iew <u>C</u> onnect <u>M</u> onitor <u>H</u> elp	
26	Change the Background Colors of Waveform	Ctrl+B
6	Copy the Waveform Image	Ctrl+G
‡∓	<u>C</u> alculate	Ctrl+C
Ô	Snapshot	
1	Snapshot <u>R</u> elease	Ctrl+R

2) The portion of the graphs taken with the Snapshot function will appear in gray.



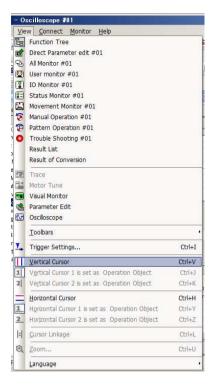
3) To clear the Snapshot data, go the Edit menu and select Snapshot Release, or click 🔀 on the Toolbar.



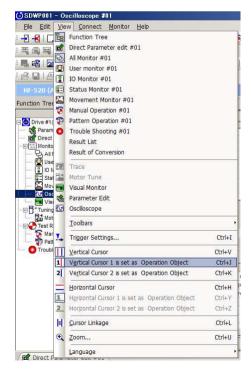
Cursor Display

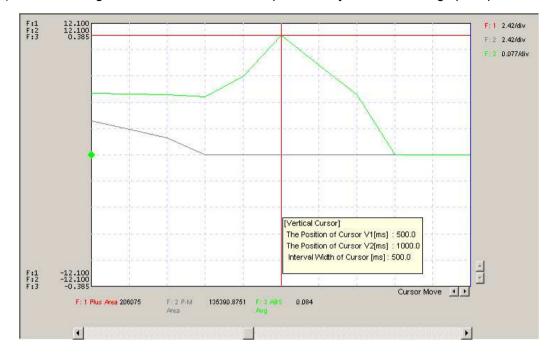
Using the vertical cursor

1) Go to the View (V) menu and select Vertical Cursor (V) or click on ||| in the toolbar.



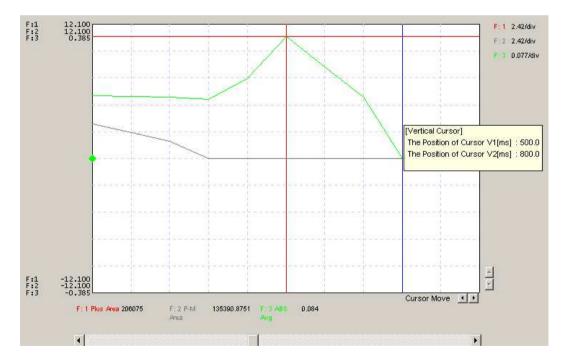
 Set the cursor by selecting "Vertical Cursor 1 is set as Operation Object" from the View (V) menu shown below.



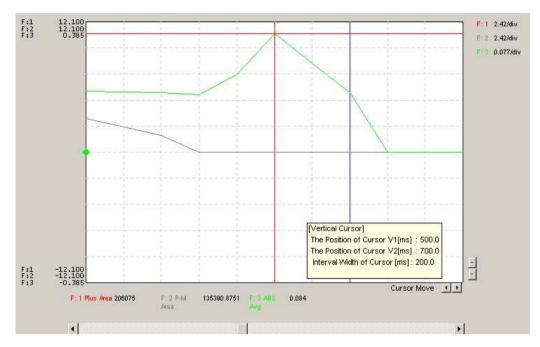


3) After selecting, "Vertical Cursor 1 is set as Operation Object", click on the graph to position the cursor.

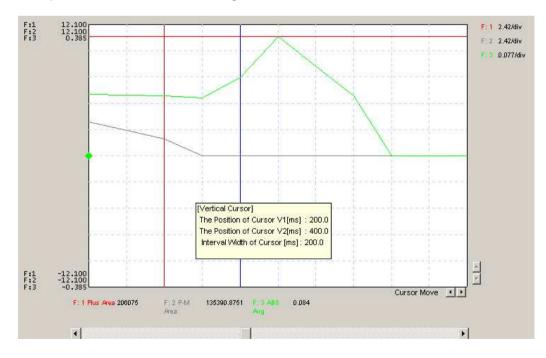
4) Select "Vertical Cursor 2 is set as Operation Object", click on the graph to place the next cursor.



5) You can now use the mouse to move the cursors. Data within the cursor will appear along side the graph.

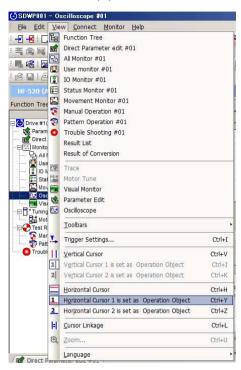


6) You Move the cursor by selecting "Cursor Linkage (<u>C</u>)" from the View (V) menu and then adjusting the space between both cursors using the mouse.

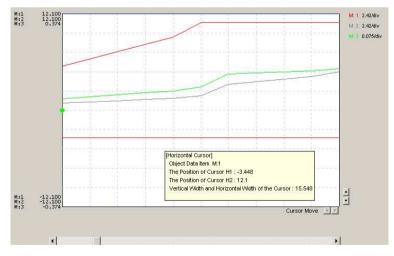


Using the horizontal cursor

1) Go to the View (V) menu and select Horizontal Cursor (H) or click on 🔚 in the toolbar.



- 2) Set the cursor by selecting "Horizontal Cursor 1 is set as Operation Object" and "Horizontal Cursor 2 is set as Operation Object" from the View (V) menu shown below.
- After selecting, "Horizontal Cursor 1 is set as Operation Object", click on the graph to position the cursor.



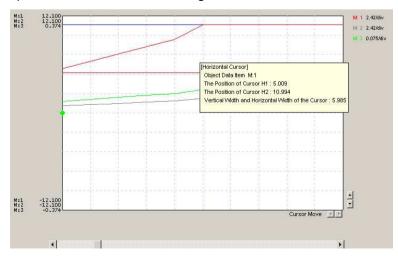
4) Select "Horizontal Cursor 2 is set as Operation Object", and click on the graph to place the next cursor.



5) You can now use the mouse to move the cursors. Data within the cursor will appear along side the graph.

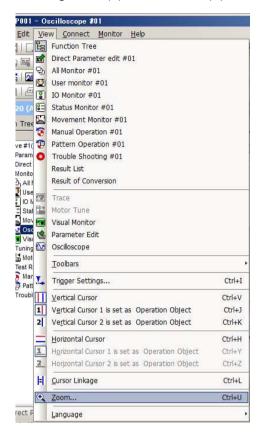


6) Move the cursor by selecting "Cursor Linkage (<u>C</u>)" from the View (V) menu and then adjusting the space between both cursors using the mouse.

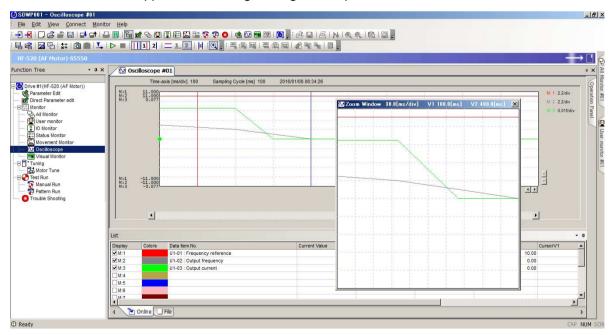


Zoom

You can enlarge the area between the two vertical cursors either by clicking on \bigcirc in the toolbar or by selecting Zoom (Z) from the View (V) menu.



The area selected will appear as an enlarged image in a separate window.

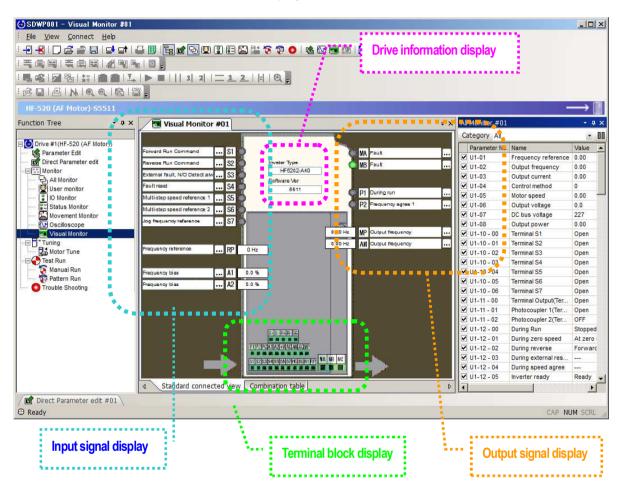


4.4.7 Visual Monitor

The Visual Monitor provides a visual display of the drive operation status and current settings. The image will appear much like a standard wiring diagram.

4.4.7.1 Standard Connection Diagram

The screenshot below indicates the various display features of the Visual Monitor.



Drive Data Display

Displays data on the drive that is currently connected.

Input Signal Display

Displays data for the drive's input terminals.

Output Signal Display

Displays data for the drive's output terminals.

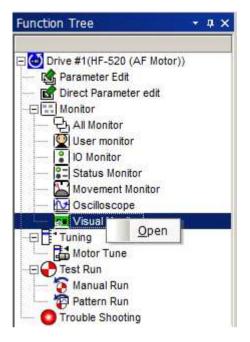
Terminal Block Display Range

Displays data for the terminal block settings in the drive.

Standard Connection Diagram Screen Display

To display the connection diagram using the Visual Monitor Function, follow the instructions below:

1) Right-click on the Visual Monitor icon in the Function Tree to generate the pop-up menu shown below.



2) Selecting "Open" will produce the window below:

Visual Monitor	#01						÷ >
Forward Run Command	S1	0		6	MA	Fault	
Reveise Run Command	S2	Ö	Inveter Type	. 1	MB	Fault	
External fault, N/O Detect alw	S3	6	HF5202-A40				
Fault reset	S4	6	Software Ver 6511	11			
Multi-step speed reference 1	\$5	6		- 9	P1	During run	
Multi-step speed reference 2	S6	6			- P2	Frequency agree 1	
Jog frequency reference	S7	A					
		T.		0.00 Hz	MP	Output frequency	
		100	-2	0.00 Hz	-	Output frequency	
Frequency reference	RP	0 Hz			7.00		
Frequency bias	A1	0.0 %					
Frequency bias	A2	0.0 %					
			SHS RHR IG				
	1962	21220	PCIA1IA2I+YIACIAWIACIWP				
		S1 32 5	53 54 55 56 57 HC 8C 11 RF	NA MB MC		a sector	
					E		
Standard connect	ted vie	v Com	bination table				0

Parameter Edit Screen Display

There are three ways to go to the Parameter Edit window from the Standard Connection Diagram. The Parameter Edit Screen is displayed by clicking on $|\dots|$.

• Display the Parameter Edit window from the bit I/O parameter.

Param	eter Edit							
veter Ty	/pe: HF5202-A20)						
erminal:	S1							
lo.	Name	Working value	Units		Drive's	Min	Max	Default
11-01	Terminal S1 function	0040 : Forward Run Command	-	0040	T	0001	009F	0040

• Display the Parameter Edit window from the Analog Input Parameter.

No.	Name	Working value	Units	Drive's	Drive's	10V		1
43-01	Terminal A1 Signal L		-	0	-			1
13-02		0000 : Frequency bias	-	0000	-	5V		
13-03	Terminal A1 Gain Se	100.0	%	100.0	%			
13-04	Terminal A1 Bias Se	0.0	%	0.0	%	0V	· / ·	
						-5V		
						-54		
						-10V		

• Display the Parameter Edit window from the Analog Output Parameter.

	(Interview)	THE R SHOW AND	Linese.	In s d	In : I	T 10V	ment of analog out
-01	Name	Working value	Units	Drive's		100	/
-01	Multi-Function Anal	102 Output frequency	8	102	*	5V	
-03	Multi-Function Anal	165.65	8	0.0	%		
						0	
						-5V	/ -
						-10V	

4.4.7.2 Terminal Combination for Speed Selection Window

Features of the Terminal Combination for Speed Selection Window appear below:

State of input of	nultifunctional input i	terminal -				
Mu#i-step Spee	Multi-step Speed2	Multi-step Spee	Multi-step Spee	JOG frequen	. Parameters	Frequency Reference
*	1				b1-01=0	Instruction from d1-01
					b1-01=1	Instruction from terminal
OFF	OFF	OFF	OFF	OFF	p1-01=2	Instruction from MEMOB
					b1-01=3	Instruction from option .
		Status of cu	irrently selected	value	b1-01=4	Instruction from pulse r.
					H3-05 != 2 , H3-09 != 2	Instruction from d1-02
ON	OFF	OFF	OFF	OFF	H3-05 != 2 , H3-09=2	Instruction from terminal
					H3-05=2 , H3-09 != 2	Instruction from terminal
					H3-05 != 3 , H3-09 != 3	Instruction from d1-03
OFF	ON	OFF	OFF	OFF	H3-05 != 3 , H3-09 != 3	Instruction from terminal
					H3-05=3 , H3-09 != 3	Instruction from terminal
ON	ON	OFF	OFF	OFF	8	Instruction from d1-04
OFF	OFF	ON	OFF	OFF	2	Instruction from d1-05
ON	OFF	ON	OFF	OFF	2	Instruction from d1-06
OFF	ON	ON	OFF	OFF		Instruction from d1-07
ON	ON	ON	OFF	OFF	8	Instruction from d1-08
OFF	OFF	OFF	ON	OFF		Instruction from d1-09
ON	OFF	OFF	ON	OFF	8	Instruction from d1-10
OFF	ON	OFF	ON	OFF	8	Instruction from d1-11
ON	ON	OFE	ON	OFF	3 4	Instruction from d1-12
OFF	OFF	ON	ON	OFF	4	Instruction from d1-13
ON	OFF	ON	ON	OFF	1	Instruction from d1-14
OFF	ON	ON	ON	OFF	-	Instruction from d1-15
ON .	ON	ON	ON	OFF	8	Instruction from d1-16
OFF	OFF	OFF	OFF	ON		Instruction from d1 17
Standard c	onnected view Co	mbination table	<u> </u>			

Status of multi-function input terminals

Displaying the Terminal Combination for Speed Selection Window

To call up the Terminal Combination for Speed Selection Window using the Visual Monitor, open the Visual Monitor, then select the tab at the bottom of the window marked "Combination Table"



Displaying the Parameter Edit Screen

Follow the procedure below to open the Parameter Edit window from the Combination table:

1) Double-click on one of the parameter settings.

Jen	Parameters	Frequency Reference
	b1-01=0	Instruction from d1-01
	b1-01=1	Instruction from terminal
	b1-01=2	Instruction from MEMOB
	b1-01=3	Instruction from option
	b1-01=4	Instruction from pulse r
	H3-05 != 2 , H3-09 != 2	Instruction from d1-02
	H3-05 != 2 , H3-09=2	Instruction from terminal

2) The Parameter Edit window will open as shown below.

		Working value	Units	Drive's	Drive's	Min	Max	Default
-01 Referen	nce selection	1 : Control circuit terminal	-	1	-	0	4	1

4.5 Test Run

4.5.1 Manual Operation

The motor operates at the specific speed setting that has been entered.

Manual Operation lets the user check the direction of motor rotation and the speed setting without needing to use an upper controller.

Be sure to take proper precautions when performing a Manual Operation. Read the manually thoroughly, paying particular attention to the following points:

Clear the area around the motor.

Clicking on the button marked "Run" will cause the motor to rotate at the designated speed. Make sure proper precautions have been taken for the area surrounding the motor.

Make sure a Fast Stop has been set to one of the terminals.

If an error occurs with the PC or with this function while a Manual Run is being performed, there is a chance the motor will continue rotating.

Be sure that a Fast Stop or some other type of emergency stop has been set to one of the external terminals in order to halt the motor.

Do not edit parameter settings with any other software than SDWP001.

Use SDWP001 only to edit parameter settings.

Changing the frequency reference units, for example, with the digital operator or some other device can cause the motor to suddenly speed up and is extremely dangerous.

Check all parameter settings if a fault occurs.

This function switches the frequency reference selection, parameter settings, and Run command selection over to MEMOBUS communications.

Check PC and all function settings if a communications fault occurs.

Always cycle power to the drive if a fault occurs.

This function works by assigning the frequency reference selection (comnet), parameter settings, and Run command selection (comctrl) over to MEMOBUS communications.

Check PC and all function settings if a communications fault occurs, and cycle power to the drive.

Extra Notes on Using Manual Operation

This function is for setting up the drive and performing a test run. It is strongly recommended that the motor be fully decoupled from the load for proper setup.

NOTE: Manual Operation cannot be performed if the Baseblock command is currently enable via one of the input terminals.

NOTE: To operate manually, set the frequency references units to Hz (the default setting of o1-03).

When performing a Manual Operation, the following conditions are required:

• The drive must be in REMOTE mode, either set by the digital operator or by one of the input terminals

- ·No faults occur
- The drive is not currently running the motor (i.e., a Run command is not present)

Follow the procedure below to perform a Manual Operation:

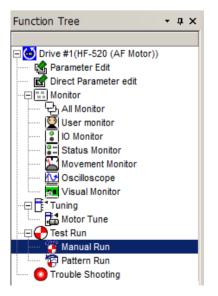
1) Display the Manual Operation window.

0.00 (Hz] (0.00 - 60.00)	
V Apply	
Twd	
🔉 Rev	
💮 Stop(F12)	

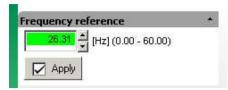
There are three ways to call up the Manual Operation window:

- View (V) in the Main Menu
- View (V) \rightarrow "Manual Operation"
- toolbar
- Click 🛜
- Function Tree

Open "Test Run" and double-click on "Manual Run"



2) Set the frequency reference by entering the frequency reference and clicking "Apply".

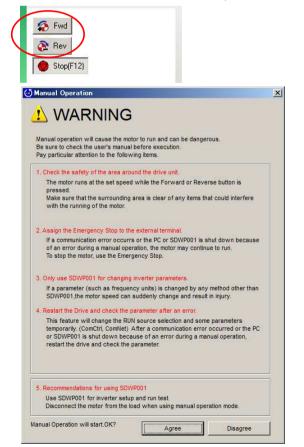


If the frequency reference entered is outside the allowable range, the entered value will appear in red and a warning message will appear.

Frequ	iency reference		
	[Hz] (0.00 - 60.00)	
	Apply		
_			
Setting o	out of range		×
2	The following parameters will no Please set within the correct ran	it be changed because their set d nge,	ata is out of range.
	Frequency reference		
		OK	

3) Rotate the motor

When the Fwd or Rev button is first pushed, a warning message will appear:



4) Click "Agree" to begin rotating the motor. Clicking "Decline" will cancel the process and the motor will not rotate.

NOTE: This warning message is only displayed the first time the Run command is issued, and will not appear again until SDWP001 is restarted.

While the motor is rotating, the following display will appear:

 A display to indicate the current operation status of the motor, which includes During Forward RUN / During Reverse RUN / Zero Speed / During Stop / Fault / Drive Ready)



During run, a window will appear near the task tray to stopping the motor. When a Forward command is given, the icon will rotate counterclockwise.





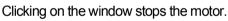


When a Reverse command is given, the icon will rotate clockwise.



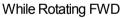


In Reverse



During Stop







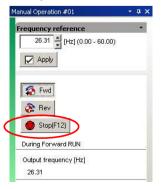
Stopped

During run, an icon will appear in green to indicate that the drive is operating the motor.

> ⊳

5) Stop the motor

To stop the motor, click on the "Stop" button as shown below:



4.5.2 Pattern Operation

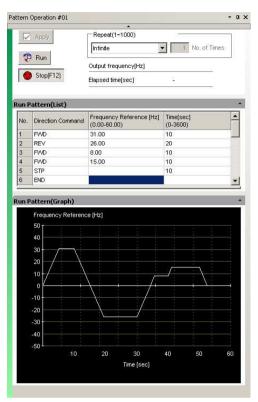
Pattern Operation lets the user take advantage of parameters that have already been programmed to operate the drive automatically.

Be sure to take proper precautions when performing a Pattern Operation.
Read the manually thoroughly, paying particular attention to the following points:
Clear the area around the motor.
Clicking on the button marked "Run" will cause the motor to rotate at the designated speed.
Make sure proper precautions have been taken for the area surrounding the motor.
Make sure a Fast Stop has been set to one of the terminals.
If an error occurs with the PC or with this function while a Manual Run is being performed, there is a
chance the motor will continue rotating. Be sure that a Fast Stop or some other type of emergency
stop has been set to one of the external terminals in order to halt the motor.
Do not edit parameter settings with any other software than SDWP001.
Use SDWP001 only to edit parameter settings. Changing the frequency reference units, for
example, with the digital operator or some other device can cause the motor to suddenly speed up
and is extremely dangerous.
Check all parameter settings if a fault occurs.
This function switches the frequency reference selection, parameter settings, and Run command
selection over to MEMOBUS communications.
Check PC and all function settings if a communications fault occurs.
Always cycle power to the drive if a fault occurs.
This function works by assigning the frequency reference selection (comnet), parameter settings,
and Run command selection (comctrl) over to MEMOBUS communications.
Check PC and all function settings if a communications fault occurs, and cycle power to the drive.
Movement during Operation
Because this function relies on an internal Run command, there may be some movement in regards
to motor shaft position. Take particular caution of positioning when repeating the same task as this
difference may compound.
Operation Status Display during Run
Although this function displays the operation status while running the motor, environmental factors
make cause there to be some difference between what appears on the PC screen and the actual
waveform. Take this into consideration when using this function.
Extra Notes on Using Manual Run
This function is for setting up the drive and performing a test run. It is strongly recommended that the
motor be fully decoupled from the load for proper setup
NOTE: Pattern Operation uses the Accel/Decel Time 1 set to the multi-function contact input
terminals and disregards Accel/Decel Time 2 and 3, as well as acceleration and
deceleration time settings for motor 2.
NOTE: Pattern Operation cannot be performed if the Baseblock command is currently enabled
via one of the input terminals.

NOTE: To operate manually, set the frequency references units to Hz (the default setting of o1-03).

Follow the procedure below to perform a Pattern Operation:

1) Open up the Pattern Operation window.

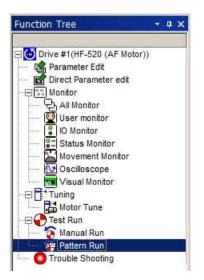


There are three ways to open up the Pattern Operation window:

- From the Main Menu
 - Main Menu: "View (V)" \rightarrow "Pattern Operation"
- · From the toolbar

Click 😰

- From the Function Tree
- Open "Test Run" in the Function Tree and double-click "Pattern Run".



- 2) Set the pattern of operation for a Pattern Operation
 - a) Set the direction of rotation. Select the direction: END / FWD / REV / STP
 - b) Set the output frequency.
 - Set the frequency reference within the allowable range (between 0.0 to 60.0 Hz).
 - c) Set the time for each operation.

Time can be set from 0 to 3600 seconds. Specify the time the drive should operate from when the Run command is given.

This time will start over when a new Run command is given.

3) Set the number of times the drive should execute the command.

Apply	Repeat(1~1000)	95.	
	Infinite	• 1 No.	of Times
P Run	Output frequency[Hz]		
Stop(F12)	Elapsed time[sec]	32	

To set the number of repeat times the command should be executed, first specify whether the command should repeat a specified number of times or repeat indefinitely.

Next, set the number of times the pattern should be repeated.

The total number of times can be set from 1 to 1000.

This value is enabled only when the "Specify number of times" setting is enabled.

4) Apply the settings that have been entered

Click "Apply" to check the contents that have been set.

Drive performance will appear in a graph.

Once the pattern is complete and the drive stops, the following window will appear:

Pattern Operation is set up incorrectly. This may be due to the following:						
 The value of the last frequency reference prior to "END" is not zero. The value of the last frequency reference prior to "END" is not zero and the drive cannot reach zero speed within the set time. 						
Reset the operation pattern to zero-speed automatically?						
Yes No						

To accept the operation pattern that has been set until the drive reaches zero speed, click "Yes". To return to the Pattern Run window and start over again, click "No".

5) Start operation

Clicking 👘 Run will generate the following window:



Click "Agree" to begin rotating the motor. Clicking on "Disagree" will stop the operation and the motor will not rotate.

NOTE: This warning message will appear only once while SDWP001 is operating. It will not appear again until the program is closed and then reopened.

Verify drive operation progress by viewing the display shown below:

Current drive status:

Output frequency[Hz]	18.24		
Elapsed time[sec]	11		
Repeat[times]	17-		

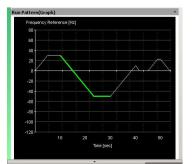
Operation pattern with a list

The current operation pattern being executed will be highlighted in green.

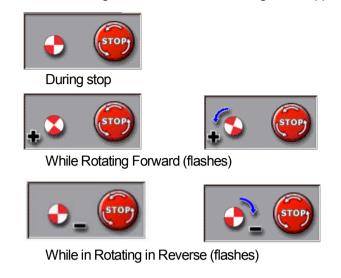
No.	Direction Command	Frequency Reference [Hz] (0.00-60.00)	Time[sec] (0-3600)	
1	FWD	30.00	10	
2	REV	50.00	20	
3	FVVD	10.00	10	

The operation pattern appears in green

During run, a green line will appear to indicate drive operation and progress on the graph.



• During run, the icon shown below will appear near the task tray. The icon contains an animation that will mimic the status of the motor. The animation will change when the motor is running or is stopped.



During run, a green bar will appear in the caption bar.

6) Stop the motor

Clicking "STOP" while the motor is running will cause the drive to stop the motor.



You can stop the motor at any time by clicking the "Stop" button that appears during Run. The icon is related to the task window.



Revision History

The revision dates and numbers of the revised manuals are given on the bottom of this page.

MANUAL No. DM2308E-<u>1.0</u> Revision number

Date of Publication	Rev. No.	Section	Revised Context
January 2016	1.0	-	First edition