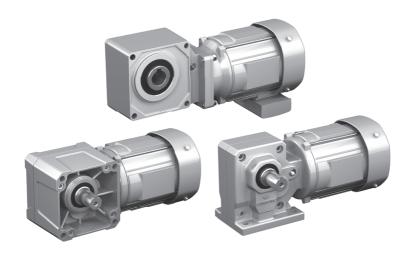
Sumitomo Drive Technologies

HYPONIC Gearmotor®

Gearmotor
Hollow Type Input Shaft
Application Product:
HYPONIC Gearmotor® with Current Limiter



<<CAUTION>>

- This product should be handled by only those who have been trained for the work. Carefully read the maintenance manual before use.
- Deliver this manual to the customer who will actually use the product.
- This maintenance manual should be kept by the user for future reference.

Introduction: Safety Precautions

 Carefully read this maintenance manual and all accompanying documents before use (installation, operation, maintenance, inspection, etc.). Thoroughly understand the machine, information about safety, and all precautions for correct operation.

After reading, retain this manual for future reference.

- Pay close attention to the "DANGER" and "CAUTION" warnings regarding safety and proper use.



Improper handling may result in physical damage, serious personal injury and/or death.



Improper handling may result in physical damage and/or personal injury.

Matters described in Acaution may lead to serious danger depending on the situation. Be sure to observe important matters described herein.

! DANGER

- Transport, installation, plumbing, wiring, operation, maintenance, and inspections should be performed by trained technicians; otherwise, electric shock, injury, fire, or damage to the equipment may result.
- In the case of maintenance with disassembly, please contact the nearest authorized maintenance shop.
- When using the equipment in conjunction with explosion proof motor, a technician with electrical expertise should supervise the transport, installation, plumbing, wiring, operation, maintenance and inspection of the equipment; otherwise, explosion, ignition, electric shock, personal injury, fire or damage to the equipment may result.
- When the unit is to be used in a system for human transport a protecting device for human safety should be installed to prevent chances of accidents resulting in personal injury, death, or damage to the equipment due to running out of control or falling.
- When the unit is to be used for an elevator or lifter, install a safety protecting device on the elevator side to prevent it from falling; otherwise, personal injury, death, or damage to the equipment may result.

!CAUTION

Please install loss prevention device such as oil pan to the machine which is vulnerable to oil especially (machine for food processing and machine for clean room, and so on) in case oil or grease leaks; otherwise, the product may fail because of oil leakage.

Introduction: How to Refer to the Maintenance Manual, Table of Contents

This maintenance manual is common for "gearmotors," and "hollow type input shaft"

The symbols shown below are marked in the upper right or left corner of each page to indicate the classification. Please read the applicable pages.

On Common pages, regarding only specific specification, symbols are applied to indicate the contents about special specification.

Specifications	Common to All	Gearr		Hollow Type Input Shaft	Application Product
	Specifications	Without Brake	With Brake	Input Shart	riodaet
symbol	Common		ОВ		Application Product

Contents

Common

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Application Product: HYPONIC Gearmotor® with Current Limiter	
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1. Receiving Inspection Common

A CAUTION

- Unpack the unit after verifying that it is positioned right side up; otherwise, injury may result.
- Verify that the unit received is the one you ordered. Installing the wrong unit may result in personal injury or equipment damage.
- Do not remove the nameplate.

Verify the items listed below upon receiving the product. If a nonconformity or problem is found, please contact with your nearest agent, distributor, or sales office.

- (1) Does the information on the nameplate conform to what you ordered?
- (2) Was any part broken during transport?
- (3) Are all bolts and nuts tightened firmly?

1-1 Reading the Nameplates

There are two main types of nameplates: type 1 and type 2. Representative examples are shown below. Please observe them by type.

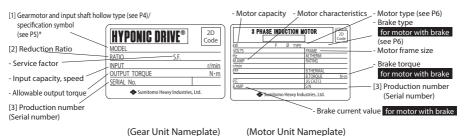
When contacting the company, please provide [1] Gearmotor type or input shaft hollow type/specification symbol, [2] Reduction ratio, and [3] Serial number.

- Nameplate Type 1: Gear Unit and Motor Unit Are Combined.



Figure 1-1 Gearmotor Nameplate (type 1)

- Nameplate Type 2: Separate Nameplates for Gear Unit and Motor Unit.



(dear office name place)

Figure 1-2 Gearmotor and Input Shaft Hollow Type Nameplate (type 2)

Note: The input shaft hollow type has a nameplate only for the gear unit.

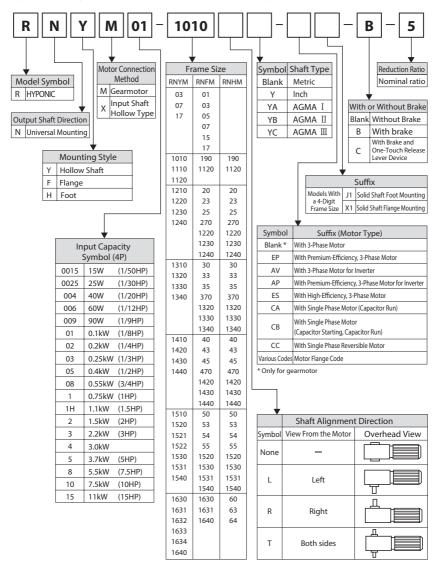
^{*} A specification symbol may not be identified.

1-2 Checking Lubrication Method

All series of HYPONIC Gearmotor adopt grease lubrication and grease is enclosed when shipped from the factory, so the motor is available as it is.

1-3 Gearmotor Type

Symbol meanings are shown below. Please confirm that the type matches the order.



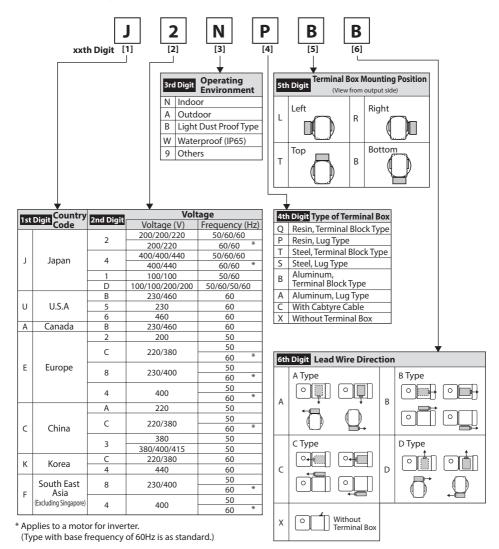
1. Receiving Inspection OI OB





1-4 Gearmotor Specification Symbol

Symbol meanings are shown below. Please confirm that the type matches your order. The specification symbol is on the nameplate in the case it is specified at an order.

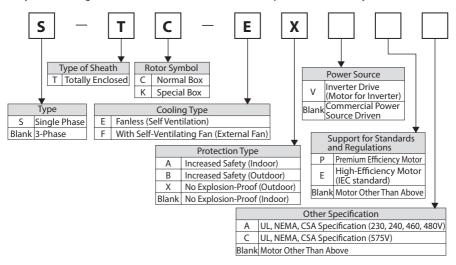


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○ **BI** 1. Receiving Inspection

1-5 Motor Type

Symbol meanings are shown below. Please confirm that the specification matches your order.



1-6 Brake Type

Tables show the relationship between standard brake type, motor type, and capacity range.

Table 1-1 Brake Type (15W - 90W)

Duelle Torre	F Si	Motor Capacity (W)		
Brake Type	Frame Size	3-Phase Motor	Single Phase Motor	
SB-004	01 03 05 07	15 25 40 60	15 25 40	
MB-003	17 1240	40	40	
MB-005	15 17 1240	60 90	60 90	

Table 1-2 Brake Type (0.1kW - 11kW)

	Motor Capacity (kW)					
Brake Type	3-Phase Motor	Premium- Efficiency, 3-Phase Motor	3-Phase Motor for Inverter	Premium- Efficiency, 3-Phase Motor for Inverter	High-Efficiency, 3-Phase Motor	Single Phase Motor
FB-01A1	0.1	-	-	-	-	0.1
FB-02A1	0.2	-	0.1	-	-	0.2
FB-05A1	0.25 0.4	-	0.2	-	0.2	-
FB-1D	0.55	-	0.4	-	0.4	0.4
FB-1E	-	0.75	-	0.75	-	-
FB-1HE	-	1.1	-	-	-	-
FB-2E	-	1.5	-	1.5	-	-
FB-3E	-	2.2	-	2.2	-	-
FB-4E	-	3.0	-	-	-	-
FB-5E	-	3.7	-	3.7	-	-
FB-8E	-	5.5	-	5.5	-	-
FB-10E	-	7.5	-	7.5	-	-
FB-15E	-	11	-	11	-	-

Note: Depending on the specification, brake type may differ from the types shown in Tables 1-1 and 1-2. Check the nameplate.

If this product is not for immediate use, note the following points when storing it.

2-1 Storage Location

Store the product in the clean and dry indoor.

Do not store outdoors. Store in a location that is free of moisture, dust, extreme temperature changes, corrosive gases, etc.

2-2 Storage Time

- The storage time should be within 1 year.
- If the storage time exceeds 1 year, adherence to special rust prevention specifications is required. Please consult with us.
- If for export, adherence to export rust prevention specifications is required. Please consult with us.
- Standard rust prevention specifications
 - External rust prevention Rust prevention oil is applied when shipping from the factory. Check rust conditions every 6 months after shipment. Reapply the rust prevention process, if necessary.

Internal rust prevention Store in the general factory or warehouse which is free of moisture, dust, extreme temperature changes, corrosive gases, etc.

2-3 Using After Storage

- Oil seals are affected by temperature, ultraviolet light and other ambient conditions and can easily degrade. After long storage periods, inspect before operation, and replace any degraded seals with new seals.
- At startup, check that there are no unusual noises, vibrations, temperature rises, or other symptoms. For motor with brakes, check that brakes work properly. If any abnormalities are found, immediately contact the nearest authorized maintenance shop.

7

ADANGER

- Do not step under the unit suspended by a crane or other machines for transport; otherwise, injury, or death may result.

ACAUTION

- Take enough care not to drop the unit.
- When a hanging bolt or hole is provided, be sure to use it. After mounting a unit to a machine, do not hoist the entire machine using the hanging bolt or hole; otherwise, personal injury or damage to the equipment and/ or lifting device may result.
- Before hoisting, refer to the rating plate, crate, outline drawing, catalog, etc. for the weight of the unit. Never hoist a unit that exceeds the rating of the load capacity or other mechanism used to lift it; otherwise, personal injury or damage to the equipment and/or lifting device may result
- Use an appropriate hanging bolt or hole, and make sure that the eye-bolt and/or nut is not loose before hoisting.

! DANGER

- Do not use a standard unit in an explosive atmosphere. Under such conditions, an explosion proof motor should be used; otherwise, explosion, ignition, electric shock, personal injury, fire or damage to the equipment may result.
- In the case of explosion proof motor, use a motor with specifications that are appropriate for a dangerous location (a location where gas or volatile vapor is present); otherwise, explosion, ignition, electric shock, or damage to the equipment may result.

A CAUTION

- Do not use the products for purposes other than those shown on the nameplate or in the manufacturing specifications; otherwise, electric shock, personal injury, or damage to the equipment may result.
- Do not place flammable objects around the gearmotor; otherwise, fire may result.
- Do not place any object that will hinder ventilation around the gearmotor or reducer. Insufficient ventilation can cause excessive heat build-up that may result in burns or fire.
- Do not step on or hang from the products; otherwise, personal injury, or damage to the equipment may result.
- Do not touch the shaft end of the gearmotor or reducer, inside keyways, or the edge of the motor fan with bare hands; otherwise, injury may result.
- When the unit is used in food processing applications, machines for clean room and so on, vulnerable to oil contamination, install an oil pan or other such device to cope with grease leakage due to breakdown or failure; otherwise, grease leakage may damage products.

4-1 Installation Location

Ambient temperature: −10 to +40°C

Ambient humidity: 85%RH or less with no condensation
Altitude: Maximum 1,000 m
Atmosphere: No corrosive or volatile gases, no steam

Dust-free, well-ventilated area.

Installation location: Indoor type: Indoors (area with minimal dust, no contact with water)
Outdoor type: Indoors or outdoors (place where are got wet with common

rainwater but not direct heavy wind and rain)

Waterproof type (Protection class IP65/Dust-tight, water jets protection type):

A structure that is not adversely affected by water jets from any direction.

It cannot be used in water or in environments where strong water jets are splashed (high-pressure cleaning) or cleaned

with chemicals.

Waterproof type (Protection class IP67/Dust-tight, immersion protection type):

A structure that is submerged in water at the specified water depth and time and is not adversely affected even if

water enters.

It cannot be used in an environment where a strong water jets are splashed (high-pressure cleaning) or cleaned with chemicals.

vibration: Maximum 1G

- Mounting in conditions other than the above requires adherence to optional specifications. Please consult with us.
- Drives built to specifications, such as explosion proofing, can be used in the specified mounting environments. However, concerning the connector to the machine used, implement measures based on the mounting environment.
- Mount in a location that enables easy operation, such as inspection and maintenance.
- Mount on a sufficiently rigid base.

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Common 4. Installation

4-2 Mounting Angle

There is no limit on a mounting angle.

There is no limitation on a mounting angle unless it is originally specified the certain angle in manufacturing.

Do not remove the motor's eye-bolt. In case it is removed, insert a bolt or other appropriate material into the screw hole to prevent water or other substances from entering the motor through the screw hole.

4-3 Mounting Bolts (Flange Type, Foot Type)

Use the bolts of the sizes in Table 4-1.

Table 4-1 Mounting Bolt Sizes

Type	Frame Size	Bolt Size
	01, 03	Hexagon socket head bolt M5
	05, 07, 15, 17, 190, 1120	Hexagon socket head bolt M6
	20, 23, 25, 270, 1220, 1230, 1240	Hexagon socket head bolt M8
Flances trues	30, 33, 35, 370, 1320, 1330, 1340	Hexagon socket head bolt M10
Flange type	40, 43, 45, 470	Hexagon socket head bolt M10
	1420, 1430, 1440, 50, 53, 54, 55	Hexagon socket head bolt M12
	1520, 1530, 1531, 1540	Hexagon socket head bolt M16
	1630, 1631, 1640	Hexagon socket head bolt M20
	190, 1120, 20, 23, 25, 270, 1220, 1230, 1240	Finished bolt M8
Foot type	30, 33, 35, 370, 1320, 1330, 1340	Finished bolt M10
	40, 43, 45, 470, 1420, 1430, 1440	Finished bolt M12
	50, 53, 54, 55, 1520, 1530, 1531, 1540	Finished bolt M16
	60, 63, 64	Finished bolt M20

4-4 Keyed Shaft Motor Assembly Issues (Input Shaft Hollow Type)

- [1] Remove oil, dirt, and other contaminants from the motor shaft and inside of the HYPONIC Gearmotor input shaft. (The inner surface of the input shaft is treated with rust prevention oil before shipping.)
- [2] Align the motor shaft key with the input shaft keyway. (Keyway dimensions conform to JIS B 1301-1996 (ISO) "Keys and Their Corresponding Keyways: Parallel keys (Normal Type)").
- [3] Coat the motor shaft with molybdenum disulfide grease to prevent fretting, and the mating face with liquid gasket.
- [4] Depending on the motor combination, a spacer preventing the key from falling out may be in a separate shipment. Before assembly, insert the spacer deeply into the hole in the input shaft. Operation with uninserted spacer could result in the key falling out and damaging the shaft.
- [5] When assembling the motor and HYPONIC Gearmotor, make sure that the centers of both shafts are aligned. Do not force the assembly if the shafts are slanted or misaligned or if the key is only partially engaged.
- [6] Fasten the motor and adapter plate by using the motor mounting bolt. Tighten after confirming that the motor spigot is securely inserted into the adapter plate spigot. Important: If the bolt is tightened when the spigot is not inserted, uneven tightening will result, causing damage to the internal bearing and other components.

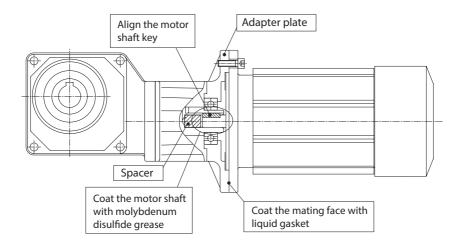


Figure 4-1 Assembly Diagram

ommon 5. Coupling With Other Machines

! CAUTION

- Confirm the rotation direction before coupling the unit with the driven machine. Incorrect rotation direction may cause personal injury or damage to the equipment.
- When operating the product alone (uncoupled), remove the key that is temporarily attached to the output shaft; otherwise the key could fly off, and injury may result.
- Cover rotating parts to prevent direct touch; otherwise, injury may result.
- When coupling the product with another machine, check that the alignment, the belt tension and parallelism of the pulleys are within the specified limit value. When the unit is directly coupled with another machine, check that the direct coupling accuracy is within the specified limit value. When a belt is used for coupling the unit with another machine, check the belt tension. Correctly tighten bolts on the pulley and coupling before operation; otherwise, injury may result because of misalignment.

5-1 Checking Rotational Direction

Tables 5-1 - 5-3 show the direction of output shaft rotation when wiring as on P27 - 45.

(1) Hollow shaft type

When wiring is performed as shown on P27 - 45, the motor shaft rotates to the right as seen from the fan cover side.

In the following diagrams, arrows show the direction of output shaft rotation in this case.

The directional relationship between the input shaft and output shaft rotations is the same with the input shaft hollow type.

Table 5-1 Direction of Output Shaft Rotation (Hollow Shaft Type)

Frame Size	Reduct	ion Ratio
03 07	5, 80, 100, 120, 160, 200, 240	7.5, 10, 12, 15, 20, 25, 30, 40, 50, 60
17	5, 7.5, 10, 12, 80, 100, 120, 150, 200, 240	15, 20, 25, 30, 40, 50, 60
1010 1110	-	5, 7, 10
1120	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1210	-	5, 7, 10
1220	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1230	-	80, 100, 120, 150, 200, 240
1240	300, 360, 480, 600, 720, 900, 1200, 1440	-
1310	-	5, 7, 10
1320	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1330	-	80, 100, 120, 150, 200, 240
1340	300, 360, 480, 600, 720, 900, 1200, 1440	-
1410	-	5, 7, 10
1420	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1430	-	80, 100, 120, 150, 200, 240
1440	300, 360, 480, 600, 720, 900, 1200, 1440	-
1510	-	5, 7, 10
1520	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1521	5, 7, 10, 12, 15, 20, 25	-
1522	5, 7, 10, 12, 15	-
1530	-	80, 100, 120, 150, 200, 240
1531	-	40, 50, 60, 80
1540	300, 360, 480, 600, 720, 900, 1200, 1440	-
1630	-	80, 100, 120
1631	-	150, 200, 240
1632	30	40, 50, 60
1633	20, 25	30, 40
1634	5, 7, 10, 12, 15	20, 25
1640	300, 360, 480, 600, 720, 900, 1200, 1440	-
Rotation direction		

Note: 1. Switch the SW in the connection diagram on P29 and P40 - 41 for reverse rotation of a 15 - 90W single phase power source motor.

- 2. To reverse rotation of a 0.1 0.4kW single phase power source motor, reverse Z1 and Z2 in the connection diagram on P30 and P42 - 45.
- 3. To reverse rotation of a 3-phase power source motor, reverse R and T in the connection diagram on P27 and P31 - 36.

5. Coupling With Other Machines





(2) Flange Type

When wiring as shown on P27 - 45, the motor shaft rotates to the right as seen from the fan cover side. In the following diagrams, arrows show the direction of output shaft rotation in this case.

Table 5-2 Direction of Output Shaft Rotation (Flange Type)

Frame Size		tion Ratio
01 03 05 07	5, 80, 100, 120, 160, 200, 240	7.5, 10, 12, 15, 20, 25, 30, 40, 50, 60
15 17	5, 7.5, 10, 12, 80, 100, 120, 150, 200, 240	15, 20, 25, 30, 40, 50, 60
190	5	7.5, 10, 15, 20, 30, 40, 50, 60
20	10, 15, 20, 25, 30, 40, 50, 60	80, 100, 120
23	10, 15, 20, 25, 30	40, 50, 60
25	-	150, 200, 240
270	5, 7.5, 10, 15, 20	30
30	-	80, 100, 120
33	10, 15, 20, 25, 30	40, 50, 60
35	-	150, 200, 240
370	5, 7.5, 10, 15, 20	30
40	-	80, 100, 120
43	10, 15, 20, 25, 30	40, 50, 60
45	-	150, 200, 240
470	5, 7.5, 10, 15, 20	30
50	-	80, 100, 120
53 54	10, 15, 20, 30	40, 50, 60, 80
55	-	150, 200, 240
1120	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1220	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1230	-	80, 100, 120, 150, 200, 240
1240	300, 360, 480, 600, 720, 900, 1200, 1440	-
1320	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1330	-	80, 100, 120, 150, 200, 240
1340	300, 360, 480, 600, 720, 900, 1200, 1440	-
1420	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1430	-	80, 100, 120, 150, 200, 240
1440	300, 360, 480, 600, 720, 900, 1200, 1440	-
1520	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-
1530	-	80, 100, 120, 150, 200, 240
1531	-	80
1540	300, 360, 480, 600, 720, 900, 1200, 1440	-
1630	-	80, 100, 120
1631	-	150, 200, 240
1640	300, 360, 480, 600, 720, 900, 1200, 1440	-
Rotation direction		
	R type L type	R type L type

Note: 1. Switch the SW in the connection diagram on P29 and P40 - 41 for reverse rotation of a 15 - 90W single phase power source motor.

^{2.} To reverse rotation of a 0.1 - 0.4kW single phase power source motor, reverse Z1 and Z2 in the connection diagram on P30 and P42 - 45.

^{3.} To reverse rotation of a 3-phase power source motor, reverse R and T in the connection diagram on P27 and P31 - 36.



5. Coupling With Other Machines

(3) Foot Type

When wiring as shown on P27 - 45, the motor shaft rotates to the right as seen from the fan cover side. In the following diagrams, arrows show the direction of output shaft rotation in this case.

Table 5-3 Direction of Output Shaft Rotation (Foot Type)

Frame Size	ion of Output Shaft Rotation (Foot Type) Reduction Ratio		
190	7.5, 10, 15, 20, 30, 40, 50, 60	5	
20	10, 15, 20, 25, 30, 40, 50, 60	80, 100, 120	
23	10, 15, 20, 25, 30	40, 50, 60	
25	-	150, 200, 240	
270	5, 7.5, 10, 15, 20	30	
30	-	80, 100, 120	
33	10, 15, 20, 25, 30	40, 50, 60	
35	-	150, 200, 240	
370	5, 7.5, 10, 15, 20	30	
40	-	80, 100, 120	
43	10, 15, 20, 25, 30	40, 50, 60	
45	-	150, 200, 240	
470	5, 7.5, 10, 15, 20	30	
50	-	80, 100, 120	
53 54	10, 15, 20, 30	40, 50, 60, 80	
55	-	150, 200, 240	
60	-	80, 100, 120	
63	10, 15, 20, 30	40, 50	
64	10, 15, 20	30, 40	
1120	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-	
1220	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-	
1230	-	80, 100, 120, 150, 200, 240	
1240	-	300, 360, 480, 600, 720, 900, 1200, 1440	
1320	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-	
1330	-	80, 100, 120, 150, 200, 240	
1340	-	300, 360, 480, 600, 720, 900, 1200, 1440	
1420	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-	
1430	-	80, 100, 120, 150, 200, 240	
1440	-	300, 360, 480, 600, 720, 900, 1200, 1440	
1520	5, 7, 10, 12, 15, 20, 25, 30, 40, 50, 60	-	
1530	-	80, 100, 120, 150, 200, 240	
1531	-	40, 50, 60, 80	
1540	-	300, 360, 480, 600, 720, 900, 1200, 1440	
Rotation	R type L type	R type L type	
direction			
	T type	T type	

Note: 1. To reverse rotation of a single phase power source motor, reverse Z1 and Z2 in the connection diagram on P30 and P42 - 45.

14

To reverse rotation of a 3-phase power source motor, reverse R and T in the connection diagram on P27 and P31 - 36.

5. Coupling With Other Machines





5-2 Mounting Connector

- When mounting connector, do not give an impact or excessive axial load to the shaft. The bearing could be damaged, or the collar could come off.
- Shrinkage-fit or shaft-end screw fit (see Figure 5-1) is recommended.

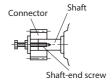


Figure 5-1

(1) When Using a Coupling

The alignment accuracy (A, B, X) in figure 5-2 should be no greater than the number shown in Table 5-4.

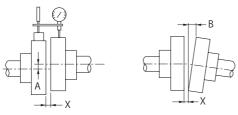


Figure 5-2

Table 5-4 Alignment Precision for Flexible Coupling

Allowable	0.1mm or manufac-
Tolerance A	turer-specified value
Allowable	0.1mm or manufac-
Tolerance B	turer-specified value
Χ	manufacturer-speci-
٨	fied value

(2) When Using Chains, Sprockets, or Gears

- When using a chain, attach so that the chain tension angle is perpendicular to the shaft.
- Refer to the chain catalog or other reference for chain tension.
- Select a sprocket or gear pitch diameter that is at least three times the shaft diameter.
- -The working load point of the sprocket or gear should go from the center of the shaft to this product. (See Figure 5-3)

(3) When Using a V Belt

- Over-tightening the V belt will damage the shaft and bearing. Refer to the V belt catalog or other reference for V belt tension.
- The parallelism, eccentricity β of the two pulleys should be within 20´. (See Figure 5-4)
- When using multiple V belts, use a matched set having the same length.

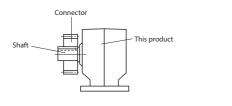


Figure 5-3



Figure 5-4

5-3 Precautions for Mounting the Hollow Shaft Type

(1) Driven Shaft Size

- If the driven shaft dimension is small and there is a space from the hollow shaft, abrasion from fretting tends to occur. The resulting abrasion powder may get pinched in the oil seal, causing the grease to leak.

Furthermore, vibrations due to the space may damage the parts inside the product.

- If the driven shaft length is short, excessive force is applied on the hollow shaft, possibly causing vibration or grease leak.
- If the effective length of driven shaft is short, the key and the keyway may be damaged.

(2) Mounting on the Driven Shaft

- If the hollow shaft end face is hit with a metal hammer or the driven shaft was biting on the hollow shaft when assembled, the hollow shaft may become deformed and the oil seal contact may become uneven, causing the grease to leak.
- If the case or the oil seal is hit, the damaged or deformed case or oil seal may cause the grease to leak.

(3) Fixing on the Driven Shaft

 If the hollow shaft is not fixed, it may vibrate in the thrust direction due to the vibration from the operation or from the machine side, possibly causing the oil seal performance to become uneven and the grease to leak.

The vibration may also damage the parts inside the product.

(4) Torque Arm Retainer

- Fixing the torque arm retainer may prevent the case from following the driven shaft movement, and as a result of excessive force being applied on the hollow shaft, the grease may leak through the oil seal. It may also damage the parts inside the product.

When using the hollow shaft type, be sure to refer to the mounting procedure on P17 - 21.

5. Coupling With Other Machines Common



5-4 Hollow Shaft Type, Torque Arm Mounting/Flange Mounting

(1) Driven Shaft Length

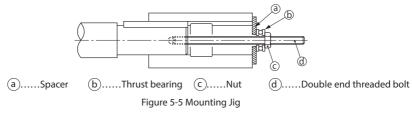
When mounting the driven shaft onto the hollow shaft, make sure that the insertion length is at or above the "recommended driven shaft length."

Refer to the catalog or consult us for more details.

- Torque arm mounted and flange mounted options are available.
- The torque arm mounting method varies by the frame size.

(2) Torque Arm Mounting (Frame Sizes 03, 07, 17, 1010)

- [1] Mounting on the driven shaft
 - Apply the molybdenum disulfide grease to the surface of the driven shaft and the bore of the hollow shaft, and insert the product into the driven shaft.
 - If the fit is tight, lightly hit the end face of the hollow shaft with a wooden hammer to insert the shaft. When doing so, never hit the case or the oil seal directly. If the fit is particularly tight, use a jig such as the one shown in Figure 5-5 for a smoother insertion.



- The hollow shaft is created with a JIS H8 tolerance. If an impact is expected or the overhung load is significant, make the fit of the hollow shaft and the driven shaft tight. (JIS js6 or k6 is recommended for the driven shaft tolerance.)

[2] Fixing onto the driven shaft

- Be sure to fix the product onto the driven shaft.

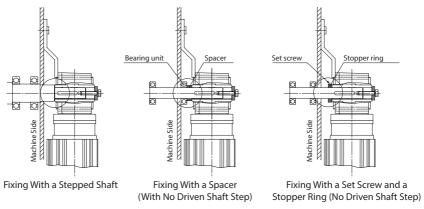
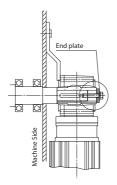
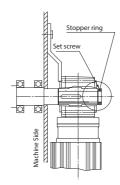


Figure 5-6 Method of Fixing So That the Product Does Not Move to the Machine Side

Common 5. Coupling With Other Machines





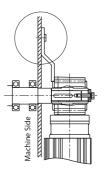
Fixing With an End Plate

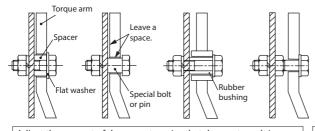
Fixing With a Set Screw and a Stopper Ring

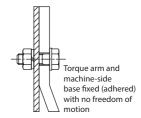
Figure 5-7 Method of Fixing When the Product Does Not Move in the Opposite Direction of the Machine

[3] Torque arm retainer

- Mount the torque arm on the driven machine side of the case. Use a hexagon socket head bolt to mount on the case. (See Table 5-5 for the size.)
- Ensure there is some degree of freedom for the torque arm retainer so that no excessive force is applied between the product and the driven shaft. Never fix the torque arm by using a retainer bolt.
- If frequent start and stop are expected, or for repetitious plugging operations, attach a blanket cylinder between the torque arm and the mounting bolt (or the spacer) to lesson the impact.







Adjust the amount of the space to a size that does not result in excessive force or contact based on the movement of the machine. The retainer bolt, machine or the product may be damaged due to excessive force.

Good Example

Bad Example

Figure 5-8 Retainer Mounting Examples

Table 5-5 Hexagon Socket Head **Bolt Sizes**

DOIL DIECE				
Frame Size	Bolt			
03	M5			
07, 17, 1010	M6			

5. Coupling With Other Machines Common



Ring (No Driven Shaft Step)

(3) Torque Arm Mounting (Frame Sizes 1110 - 1640)

- [1] Mounting on the driven shaft
 - Apply the molybdenum disulfide grease to the surface of the driven shaft and the bore of the hollow shaft, and insert the product into the driven shaft.
 - If the fit is tight, lightly hit the end face of the hollow shaft with a wooden hammer to insert the shaft. When doing so, never hit the case or the oil seal directly. If the fit is particularly tight, use a jig such as the one shown in Figure 5-9 for a smoother insertion.

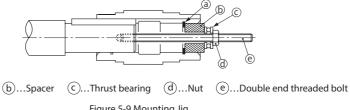


Figure 5-9 Mounting Jig

- The hollow shaft is created with a JIS H8 tolerance. If an impact is expected or the overhung load is significant, make the fit of the hollow shaft and the driven shaft tight. (JIS js6 or k6 is recommended for the driven shaft tolerance.)

[2] Fixing onto the driven shaft

(a)...Snap ring

- Be sure to fix the product onto the driven shaft.

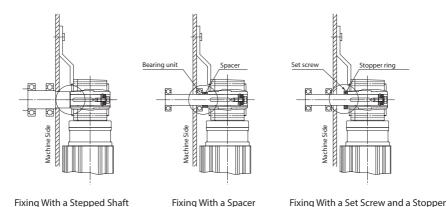


Figure 5-10 Method of Fixing So That the Product Does Not Move to the Machine Side

(With No Driven Shaft Step)

Common 5. Coupling With Other Machines

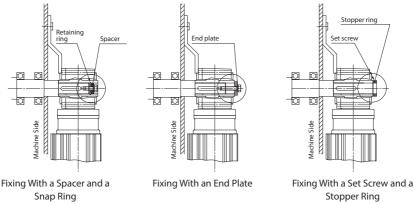
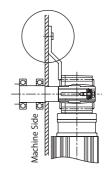
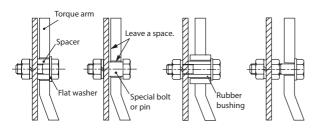


Figure 5-11 Method of Fixing So That the Product Does Not Move in the Opposite Direction of the Machine

[3] Torque arm retainer

- Mount the torque arm on the driven shaft machine side of the case. Use a hexagon socket head bolt to mount on the case. (See Table 5-6 for the size.)
- Ensure there is some degree of freedom for the torque arm retainer so that no excessive force is applied between the product and the driven shaft. Never fix the torque arm by using a retainer bolt.
- If frequent start and stop are expected, or for repetitious plugging operations, attach a blanket cylinder between the torque arm and the mounting bolt (or the spacer) to lesson the impact.





Torque arm and machine-side base fixed (adhered) with no freedom of motion

Adjust the amount of the space to a size that does not result in excessive force or contact based on the movement of the machine. The retainer bolt, machine or the product may be damaged due to excessive force.

Good Example

Bad Example

Figure 5-12 Retainer Mounting Examples

Table 5-6 Hexagon Socket Head Bolt Sizes

Frame Size	Bolt Size
1110, 1120	M6
1210, 1220, 1230, 1240	M8
1310, 1320, 1330, 1340, 1410, 1510	M10
1420, 1430, 1440, 1520, 1521, 1522, 1634	M12
1530, 1531, 1540	M16
1630, 1631, 1632, 1633, 1640	M20

5. Coupling With Other Machines Common



(4) Removing From the Driven Shaft

Be careful not to allow excessive force to apply between the case and the hollow shaft. Use a jig such as the one shown in Figure 5-13 to remove it more smoothly.

The mounting, fixing and removal jig and parts are to be prepared by the customer.

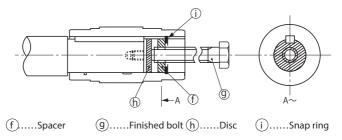


Figure 5-13 Removal Jig

(5) Flange Mounting

- For flange mounting, first mount the product on the machine and then mount the driven shaft on the

Then, assemble the bearing unit onto the driven shaft, and upon confirming that there is no shaft looseness, fix the bearing unit.

- Exercise caution to prevent the case from getting twisted and causing extra force to the driven shaft and the hollow shaft.

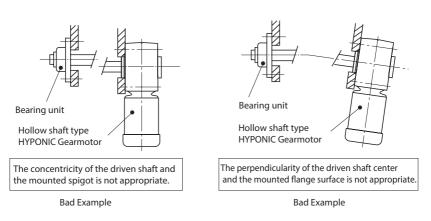


Figure 5-14 Flange Mounted Option



When using other manufacturer's motor, follow the operation manual for that motor.

This manual shows wiring for motors with Japanese standard specifications. Please consult with us for motors with overseas specifications.

A DANGER

- Do not handle the unit when cables are enagized. Be sure to turn off the power when working on the unit; otherwise, electric shock may result.
- Connect a power cable to the unit according to the diagram shown inside the terminal box or in the maintenance manual; otherwise, electric shock or fire may result.
- Do not forcibly bend, pull, or clamp the power cable and lead wires; otherwise, electric shock or fire may result.
- Correctly ground the grounding bolt; otherwise, electric shock may result.
- -The lead-in condition of explosion proof motor shall conform the facility's regulations, electrical codes, and explosion proofing standard, as well as the maintenance manual; otherwise, electric shock, personal injury, explosion, fire or damage to the equipment may result.
- For an explosion proof motor and single phase power source motor , you cannot operate the motor with inverter drive.
- For a 15-90W waterproof type motor, prevent the end of a cab tire cable, rectifier and capacitor from contacting water.

A CAUTION

- When wiring, follow the facility's regulations and electrical codes, in order to prevent burning, electric shock, injury, and fire.
- -The motor is not equipped with a protection device. However, it is compulsory to install an overload protector according to facility electrical codes. It is recommended to install other protective devices (earth leakage breaker, etc.), in addition to an overload protector, in order to prevent burning, electric shock, injury, and fire.
- Do not touch the terminals when measuring insulation resistance; otherwise, electric shock may result.
- When using a star-delta starter, select one with an electromagnetic switch on the power source side (3-contact point type); otherwise, fire may result.
- Voltage PWM inverters that use IGBT generate high-voltage surges at the motor terminals, which may degrade the insulation on the motor windings. Especially such as when the cable is long in the 400V class, a surge voltage over 1300V occurs. Therefore, in this case, install an LCR filter, AC reactor, etc. between the inverter and motor to inhibit the surge voltage.
- For motor with brake , do not energize the brake coil when the motor is stopped. Otherwise coil burnout fire, may result. Also, mistaken wiring could damage the rectifier.
- When measuring the insulation resistance of explosion proof motor, confirm that there is no gas or explosive vapor in the vicinity, in order to prevent explosion or ignition.
- If ambient temperature exceeds 60°C, place the rectifier in a location where the temperature is 60°C or less. In this case, always protect the entire rectifier with a cover. However, standard ambient temperature conditions for units with and without brakes is -10 40°C. (A special specification is required in the case of operating in an environment where ambient temperature exceeds 40°C.)
- Long cables cause large voltage drops. Select cables with appropriate diameter so that the voltage drop will no greater than 2%.
- After wiring outdoor types and explosion proof types , check that terminal box mounting bolts are not loose, and correctly attach the terminal box cover.
- For a single phase motor, do not take a starting capacitor as an operation capacitor when using it; otherwise, the capacitor will be damaged.
- For a single phase motor, do not scratch a plastic film of the starting capacitor, in order to prevent electric shock. otherwise, electric shock may result.
- For a 15 90W waterproof type motor, do not open the cap of a waterproof/dust-proof box (see Figure 6-1); otherwise, waterproof/dust-proof effects will be lost and electric shock, damage, and fire may result.

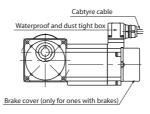


Figure 6-1

 For a 15 - 90W waterproof type motor with brake, the brake rectifier is delivered separately, and should be installed inside the control panel and wired accordingly.

6-1 Removing and Attaching the Resin Terminal Box Cover

3-phase motor: 0.1- 0.4kW, high-efficiency, 3-phase motor: 0.2kW, 3-phase motor for inverter: 0.1 - 0.2kW

(1) Removal

As shown in Figure 6-2, to remove the cover, grab the sides of the terminal box, and pull it toward you.

(2) Attachment

Push the terminal box cover from above the terminal box case until it snaps shut.

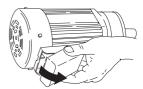


Figure 6-2

6-2 Measuring Insulation Resistance

When measuring insulation resistance, always disconnect the control panel and measure the motor alone.

Measure insulation resistance before wiring. Insulation resistance (R) is changed by a number of factors, including motor output, voltage, type of insulation, winding temperature, moisture, degree of fouling, time used, and amount of time test voltage is applied. However, normally, it must be above the values in Table 6-1.

Table 6-1 Values for Insulation Resistance

Motor Voltage	Megohmmeter Voltage	Insulation Resistance (R)
Low-voltage electric motors	500V	1 MΩ or more
of no more than 600V	3000	1 MILZ OF THORE

Reference: JEC -2100 contains the following equation: $R \geq \frac{\text{Rated Voltage (V)}}{\text{Rated output power (kW)} + 1,000} \qquad (M\Omega)$ $R \geq \frac{\text{Rated Voltage (V)} + (\text{RPM/3})}{\text{Rated output power (kW)} + 2,000} + 0.5 (M\Omega)$

Low insulation resistance is a sign that there is an insulation failure. Do not apply power. Consult an accredited maintenance shop.

6-3 Coordination of System Protection

- Use a wiring breaker for short circuit proofing.
- Use an overload protection device designed to handle currents that exceed the rated current on the nameplate.
- For increased safety motors, use an overload protection device capable of protecting the locked rotor current on the nameplate within the allowable locking time.

6-4 Connecting the Power Cable.

Connect the power cable and motor lead wire by clasping in a pressure connection terminal as shown in Figure 6-3.



Figure 6-3

6-5 Motor Wiring

The pages for motor wiring diagrams are shown.

Table 6-2 Without Brake

Motor Type				Page		
		Capacity (kW)	Number of Lead Wires	Direct Input from Commercial Power Source	Inverter Drive	
	Standard	15W - 0.55	3	P27	P28	
3-Phase Motor	Increased safety	0.1 - 7.5 11	3 6	P27	-	
Premium- Efficiency, 3-Phase Motor	Standard	0.75 - 3.7 5.5 - 11	3 6	P27	P28	
	Increased safety	0.75 - 3.7 5.5 - 11	3 6	P27	-	
3-Phase Motor for Inverter		0.1 - 0.4	3	-	P28	
Premium-Efficiency, 3-Phase Motor for Inverter		0.75 - 3.7 5.5 - 11	3 6	-	P28	
High-Efficiency, 3-Phase Motor		0.2 - 0.4	3	P27	P28	
Single Phase Motor		15W - 90W	3	P29		
		0.1 - 0.4	6	P30	-	
Single Phase Reversible Motor		15W - 90W	3	P29	-	

Note: Diagram above is motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.

○BI 6. Wiring

Table 6-3 With Brake (15 - 90W)

	T Brake (13 3)				Page		
Motor Type	Frame Size	Capacity (W)	Brake Type	Number of Lead Wires	One Direction Rotation	Plugging Rotation	Inverter Drive
3-Phase	01 03 05 07	15 25 40 60	SB-004				
	17 1240	40	MB-003	5	P31	P34	P37
Motor	15 17 1240	60 90	MB-005				
	01 03 05 07	15 25 40	SB-004				
Single			MB-003		P40	P40	
Phase	17 1240	40	(Waterproof)	5			
	17 1240	40	MB-003) 3	•		-
Motor			(Indoor)		P41	P41	
	15 17 1240	60 90	MB-005				

Table 6-4 With Brake (0.1 - 11kW)

Table 6-4 With Brake (0.1 -	T TRVV)	KVV)		Page		
Motor Type	Capacity (kW)	Brake Type	Number of Lead Wires	One Direction Rotation	Plugging Rotation	Inverter Drive
	0.1	FB-01A1	5	P32	P35	P38
3-Phase Motor	0.2	FB-02A1				
3-Filase Motor	0.25 0.4	FB-05A1				
	0.55	FB-1D				
	0.75	FB-1E		P32	P35	P38
	1.1	FB-1HE				
	1.5	FB-2E	5			
Premium-Efficiency,	2.2	FB-3E	,			
3-Phase Motor	3.0	FB-4E]			
3-Filase Motor	3.7	FB-5E				
	5.5	FB-8E		P33	P36	P39
	7.5	FB-10E	8			
	11	FB-15E				
3-Phase Motor for	0.1	FB-02A1	5	-	-	P38
Inverter	0.2	FB-05A1				
	0.4	FB-1D				
	0.75	FB-1E		-	-	P38
	1.5	FB-2E	5			
Premium-Efficiency, 3-Phase Motor for Inverter	2.2	FB-3E				
	3.7	FB-5E				
	5.5	FB-8E	8	-	-	P39
	7.5	FB-10E				
	11	FB-15E				
High-Efficiency,	n-Efficiency, 0.2 FB-05A1	5	P32	P35	P38	
3-Phase Motor	0.4	FB-1D	3	F 32	L 22	F30
	0.1	FB-01A1	8	P42	P44	
Single Phase Motor	0.2	FB-02A1				-
	0.4	FB-1D		P43	P45	

Note: 1. Brake type may differ depending on specification. Check the nameplate.

^{2.} The diagram above is for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.

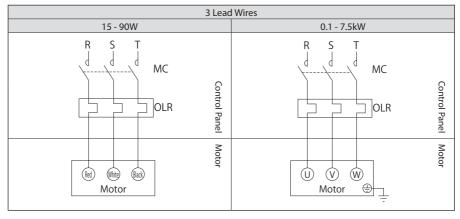
In this section, motor wiring, standard specification for terminals, and symbols of lead wires are shown.

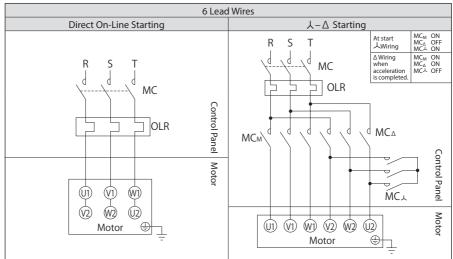
■ Without Brake. 3-Phase Power Source

3-Phase Motor

Premium-Efficiency, 3-Phase Motor

High-Efficiency, 3-Phase Motor





MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

- -This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- Do not open the cap of a waterproof/dust-proof box of a 15 90W waterproof type motor. Otherwise, waterproof/ dust-proof effects will be lost and electric shock, damage, and fire may result.

○ ☐ 6. Wiring

■ Without Brake. Inverter Drive

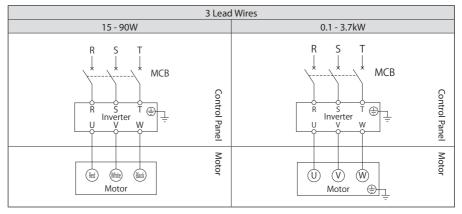
3-Phase Motor

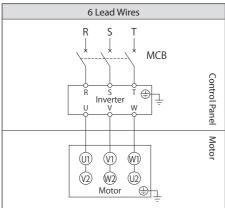
Premium-Efficiency, 3-Phase Motor

3-Phase Motor for Inverter

Premium-Efficiency, 3-Phase Motor for Inverter

High-Efficiency, 3-Phase Motor





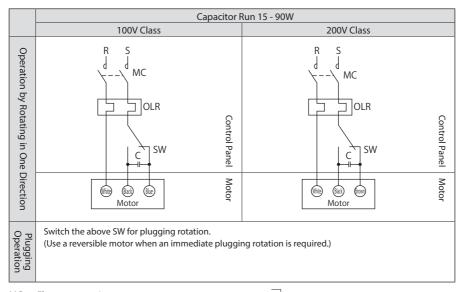
MCB: Breaker for wiring - Customer needs to prepare.

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- -The motor must be insulated to inverter-drive a 400V class 3-phase motor/high-efficiency, 3-phase motor.
- Do not open the cap of a waterproof/dust-proof box of a 15 90W waterproof type motor. Otherwise, waterproof/ dust-proof effects will be lost and electric shock, damage, and fire may result.

■ Without Brake. Single Phase Power Source

Single Phase Motor

Single Phase Reversible Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

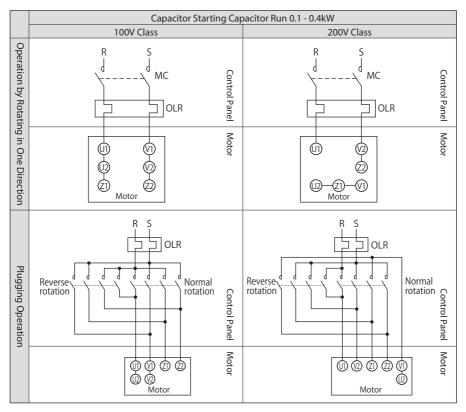
SW: Plugging switch

C: Capacitor (accessory)

- -This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- Use a capacitor bundled with the product (see Table 6-6 on P48) for wiring.
- Do not open the cap of a waterproof/dust-proof box of a waterproof type motor. Otherwise, waterproof/dust-proof effects will be lost and electric shock, damage, and fire may result.
- The capacitor is not waterproof even for a waterproof type motor.

■ Without Brake. Single Phase Power Source

Single Phase Motor



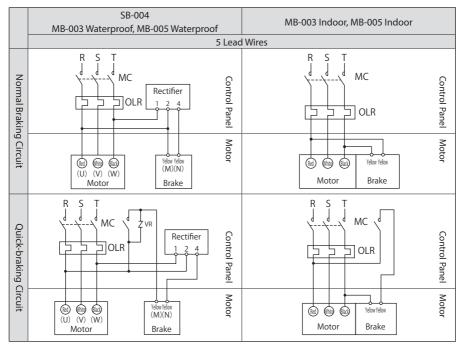
MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay Electromagnetic contactor for normal and reverse rotation

- -This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- Reverse Z1 and Z2 after the motor stopped to rotate the motor reversely in one direction.
- The capacitor is built-in the terminal box.

■ With Brake. 3-Phase Power Source. Operation by Rotating in One Direction.

3-Phase Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

VR: Varistor (for protecting contact points, rectifier, etc.)

- -This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-1 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

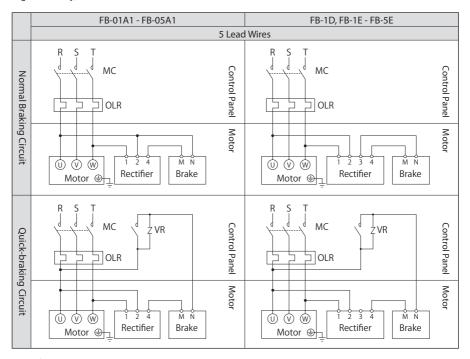
 Table 7-2 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- In the case of quick-braking circuits, interlock brake circuit's electromagnetic contractor with the motor's electromagnetic contractor.
- A rectifier for SB-004, MB-003 waterproof type motor and MB-005 waterproof type motor is placed separately.
 (SB-004 with a terminal box have a rectifier built into the terminal box. The rectifier is not waterproof for a waterproof type motor.)
- A rectifier for MB-003 and 005 indoor motor is built-in the brake unit.
- Symbols of lead wires are as shown in () for the MB-003 and 005 waterproof 400V class motor.
- Do not open the cap of a waterproof/dust-proof box of a waterproof type motor (see P23); otherwise, water-proof/dust-proof effects will be lost and electric shock, damage, and fire may result.

■ With Brake. 3-Phase Power Source. Operation by Rotating in One Direction.

3-Phase Motor

Premium-Efficiency, 3-Phase Motor

High-Efficiency, 3-Phase Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

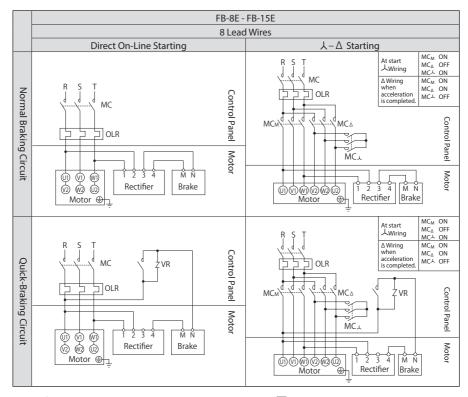
VR: Varistor (for protecting contact points, rectifier, etc.)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- In the case of quick-braking circuits, interlock brake circuit's electromagnetic contractor with the motor's electromagnetic contractor.

■ With Brake. 3-Phase Power Source. Operation By Rotating In One Direction.

Premium-Efficiency, 3-Phase Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

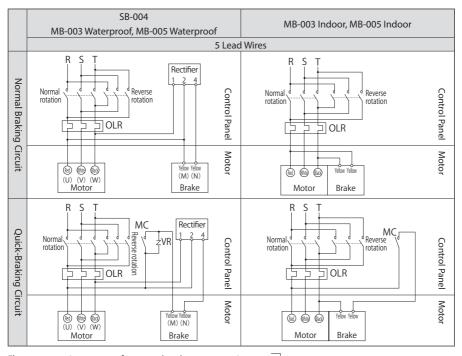
VR: Varistor (for protecting contact points, rectifier, etc.)

- -This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a guick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- In the case of quick-braking circuits, interlock brake circuit's electromagnetic contractor with the motor's electromagnetic contractor.

■ With Brake. 3-Phase Power Source. Plugging Operation

3-Phase Motor



Electromagnetic contactor for normal and reverse rotation

MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

VR: Varistor (for protecting contact points, rectifier, etc.)

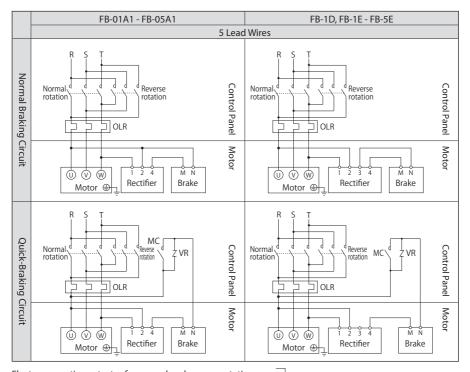
- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-1 on P6.
- Brake action delay time is different between normal and quick-braking circuits.
 Table 7-2 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For plugging operations using a quick-braking circuit, interlock the brake circuit's electromagnetic contactors to the motor's normal and reverse rotation electromagnetic contactors.
- A rectifier for SB-004, MB-003 waterproof and MB-005 waterproof is placed separately. (SB-004 with a terminal box have a rectifier built into the terminal box. The rectifier is not waterproof for a waterproof type motor.)
- A rectifier for MB-003 indoor and MB-005 indoor is built in the brake unit.
- Symbols of lead wires are as shown in () for MB-003 waterproof and MB-005 waterproof 400V class.
- Do not open the cap of the waterproof/dust-proof box (refer to P.23) of a waterproof type motor. Otherwise, waterproof/dust-proof effects will be lost and electric shock, damage and fire may be caused.

■ With Brake. 3-Phase Power Source. Plugging Operation

3-Phase Motor

Premium-Efficiency, 3-Phase Motor

High-Efficiency, 3-Phase Motor



Electromagnetic contactor for normal and reverse rotation

MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

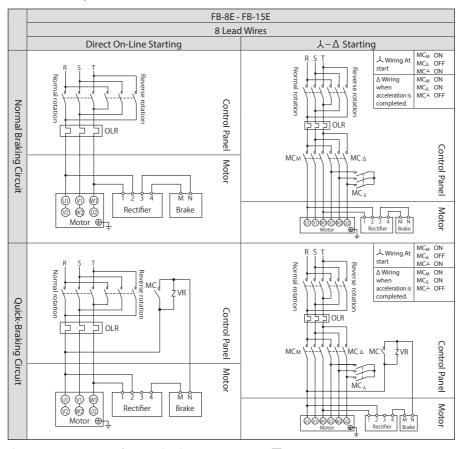
VR: Varistor (for protecting contact points, rectifier, etc.)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a guick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For plugging operations using a quick-braking circuit, interlock the brake circuit's electromagnetic contactors to the motor's normal and reverse rotation electromagnetic contactors.

■ With Brake. 3-Phase Power Source. Plugging Operation

Premium-Efficiency, 3-Phase Motor



Electromagnetic contactor for normal and reverse rotation

MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

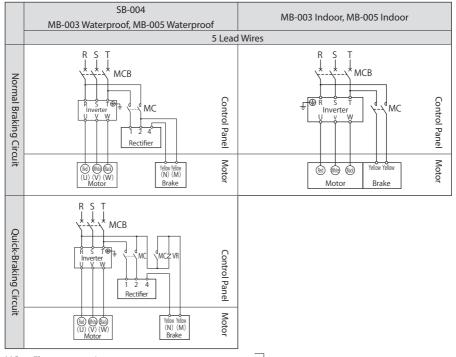
VR: Varistor (for protecting contact points, rectifier, etc.)

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- For brake types, see Table 1-2 on P6.
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 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
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- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For plugging operations using a quick-braking circuit, interlock the brake circuit's electromagnetic contactors to the motor's normal and reverse rotation electromagnetic contactors.

■ With Brake, Inverter Drive

3-Phase Motor



MC: Electromagnetic contactor

MCB: Breaker for wiring

VR: Varistor (for protecting contact points, rectifier, etc.)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-1 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-2 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- Always use the inverter's power source side for the brake power source.
- Match the opening and closing timing of the brake circuit's electromagnetic contactor to the one of the inverter control.
- A rectifier for SB-004, MB-003 waterproof and MB-005 waterproof is placed separately. (SB-004 with a terminal box have a rectifier built into the terminal box. The rectifier is not waterproof for a waterproof type motor.)
- A rectifier for MB-003 indoor and MB-005 indoor is built in the brake unit.
- Symbols of lead wires are as shown in () for MB-003 waterproof and MB-005 waterproof 400V class.
- Do not open the cap of the waterproof/dust-proof box (refer to P.23) of a waterproof type motor. Otherwise, waterproof/dust-proof effects will be lost and electric shock, damage and fire may be caused.

○BI 6. Wiring

■ With Brake. Inverter Drive

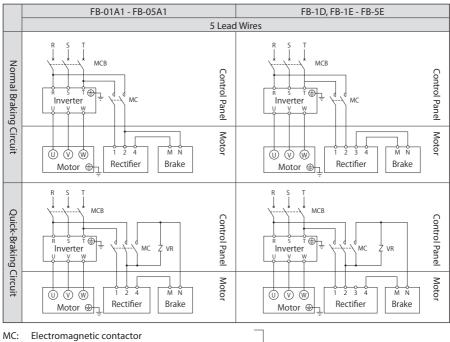
3-Phase Motor

Premium-Efficiency, 3-Phase Motor

3-phase Motor for Inverter

Premium-Efficiency, 3-Phase Motor for Inverter

High-Efficiency, 3-Phase Motor



MCB: Breaker for wiring

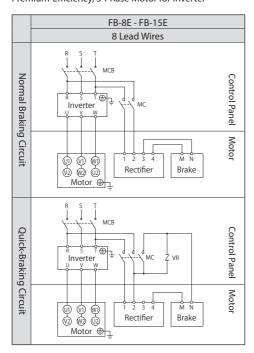
VR: Varistor (for protecting contact points, rectifier, etc.)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- The motor must be insulated to inverter-drive a 400V class 3-phase motor/high-efficiency, 3-phase motor.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- Always use the inverter's power source side for the brake power source.
- Match the timing of opening and closing of the brake circuit's electromagnetic contactor to the one of the inverter control.

■ With Brake. Inverter Drive

Premium-Efficiency, 3-Phase Motor Premium-Efficiency, 3-Phase Motor for Inverter



MC: Electromagnetic contactor

MCB: Breaker for wiring

VR: Varistor (for protecting contact points, rectifier, etc.)

- Customer needs to prepare.

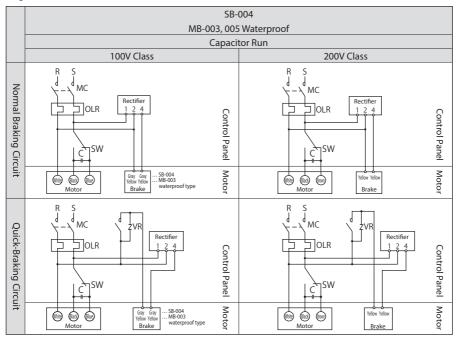
- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.

- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- Always use the inverter's power source side for the brake power source.
- Match the timing of opening and closing of the brake circuit's electromagnetic contactor to the one of the inverter control.

■ With Brake. Single Phase Power Source

Single Phase Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

SW: Plugging switch

VR: Varistor (for protecting contact points, rectifier, etc.)

C: Capacitor (accessory)

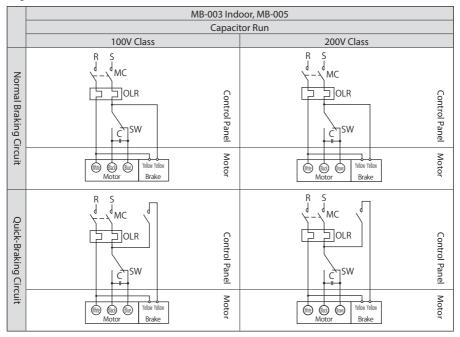
-This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us

- I his diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-1 on P6.
- Use a capacitor bundled with the product (see Table 6-6 on P48) for wiring.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-2 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For quick-braking circuits, interlock the brake circuit's electromagnetic contactor to the motor's electromagnetic contactor.
- Switch the above SW for plugging rotation. (Immediate plugging rotation is unable.)
- Rectifier and capacitor are placed separately. (SB-004 with a terminal box have a rectifier built into the terminal box. The rectifier and the capacitor are not waterproof for a waterproof type motor.)
- Do not open the cap of a waterproof/dust-proof box (see P.23) of a waterproof type motor. Otherwise, waterproof/dust-proof effects will be lost and electric shock, damage, and fire may result.

■ With brake. Single Phase Power Source

Single Phase Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

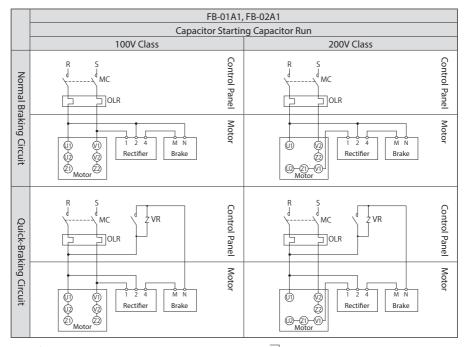
SW: Plugging switchC: Capacitor (accessory)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-1 on P6.
- Use a capacitor bundled with the product for wiring.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-2 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors for quick-braking circuits, see Table 6-5 on P46.
- For quick-braking circuits, interlock the brake circuit's electromagnetic contactor to the motor's electromagnetic contactor.
- Switch the above SW for plugging rotation. (Immediate plugging rotation is unable.)
- A rectifier is built-in the brake unit.

■ With Brake. Single Phase Power Source. Operation by Rotating in One Direction.

Single Phase Motor



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

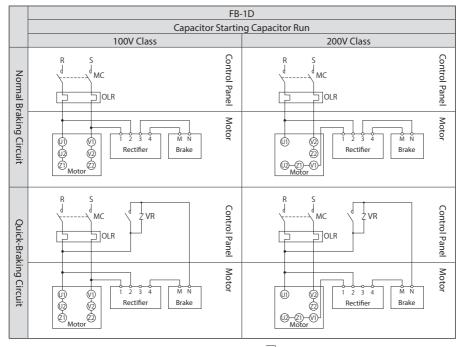
VR: Varistor (for protecting contact points, rectifier, etc.)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For quick-braking circuits, interlock the brake circuit's electromagnetic contactor to the motor's electromagnetic contactor.
- Reverse Z1 and Z2 after the motor stopped to rotate the motor reversely.
- The capacitor is built-in the terminal box.

■ With Brake. Single Phase Power Source. Operation by Rotating in One Direction.

Single Phase Motor



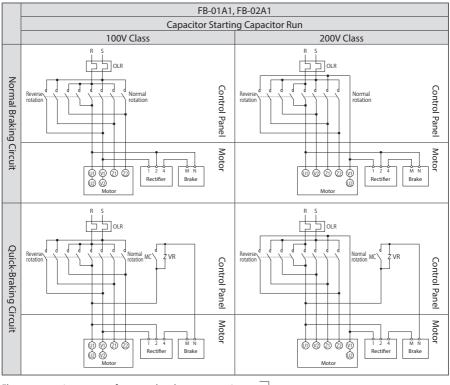
MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay VR: Varistor (for protecting contact points, rectifier, etc.)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.
 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a guick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For quick-braking circuits, interlock the brake circuit's electromagnetic contactor to the motor's electromagnetic contactor.
- Reverse Z1 and Z2 after the motor stopped to rotate the motor reversely.
- The capacitor is built-in the terminal box.

■ With Brake. Single Phase Power Source. Plugging Operation

Single Phase Motor



Electromagnetic contactor for normal and reverse rotation

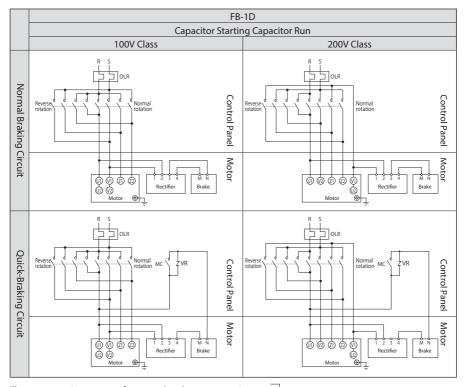
MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay VR: Varistor (protection element)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.
 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
- Use a quick-braking circuit to improve hoisting equipment and stopping precision.
- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For plugging operations using a quick-braking circuit, interlock the brake circuit's electromagnetic contactors to the motor's normal and reverse rotation electromagnetic contactors.
- The capacitor is built-in the terminal box.

■ With Brake. Single Phase Power Source. Plugging Operation

Single Phase Motor



Electromagnetic contactor for normal and reverse rotation

MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

VR: Varistor (protection element)

- This diagram shows cases for motors with standard Japanese domestic specifications. Please consult with us for motors with overseas specifications.
- For brake types, see Table 1-2 on P6.
- Brake action delay time is different between normal and quick-braking circuits.

 Table 7-3 on P51 shows action delay time. Choose the circuit that matches work requirements.
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- Use a quick-braking circuit when a phase-advancing capacitor is mounted.
- For information on electromagnetic contactors and varistors for quick-braking circuits, see Table 6-5 on P46.
- For plugging operations using a quick-braking circuit, interlock the brake circuit's electromagnetic contactors to the motor's normal and reverse rotation electromagnetic contactors.
- The capacitor is built-in the terminal box.

6-6 Points to Note When Using a Quick-Braking Circuit

When using brakes with quick-braking circuits, take note of the following items.

- Connect a varistor (protection element) to protect the quick-braking circuit contact points from surge voltage generated by the brake action.
- Wire the quick-braking circuit contact points to the brake power source secondary side contact points. Contact points might not be protected.
- For information on using an alternating current electromagnetic contactor for contact points for quick-braking circuits, see Table 6-5.

If multiple contact points are required, note the following issues.

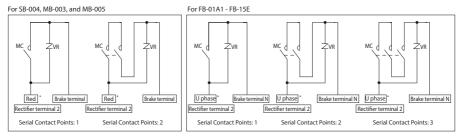
- Connect electromagnetic contactor contact points in serial. (See Figure 6-4.)
- Connect the varistor (VR) as close to the unit as possible. (See Figure 6-4.)

Table 6-5 Type for Parts Recommended When Using a Quick-Braking Circuit (When Using an Alternating Current Electromagnetic Contactor)

			Recommended	Contact	or Type	Recommo		Recommended	Varistor (Fo		ntactor								
AC Volt- age	Brake Type	Compo	y Fuji Electric FA nents & Systems Co., Ltd. Made by Mitsubishi Electric Corporation		Contact Point Capacity (DC-13 class)		Varistor Type	Maxi- mum Al- lowable Circuit Voltage	Varistor Voltage	Power Rating									
	SB-004																		
	MB-003						Mini- mum												
	MB-005						0.4A	TND07V-			0.25W								
	FB-01A1		Serial contact		Serial contact			471KB00AAA0			0.23								
	FB-02A1		points: 1 (0.7A)		points: 1 (1.2A)		Mini- mum												
	FB-05A1			ST-12			0.5A												
	FB-1D	SC-05		31 12			Mini- mum	TND10V-		470V (423 - 517V)	0.4W								
200V	FB-1E	30-03					0.7A	471KB00AAA0			0.400								
220V	FB-1HE					DC110V			AC300V										
	FB-2E		Serial contact		Serial contact		Mini-	TND14V- 471KB00AAA0											
	FB-3E		points: 2 (3.0A)		points: 2 (3.0A)		mum 1.5A												
	FB-4E										0.6W								
	FB-5E		Serial contact	ST-20	Serial contact		Mini-												
	FB-8E		points: 3 (4.0A)	31-20	points: 3 (5.0A)		mum 3.0A												
	FB-10E	SC-5-1	Serial contact	ST-21	Serial contact points: 3		Mini- mum	TND20V- 471KB00AAA0			1.0W								
	FB-15E		points: 3 (10A)		(10.0A)		5.5A	47 IKBUUAAAU											
	MB-003		Serial contact				Mini-		_	_									
	MB-005		points: 1		Serial contact points: 2 (0.5A)								mum	_	-		_		
	FB-01A1		(0.25A)												0.2A				
	FB-02A1		Serial contact											Mini- mum	TND10V- 821KB00AAA0			0.4W	
	FB-05A1		points: 2 (0.4A)				0.3A	02110007070											
	FB-1D			ST-12			Mini-	TND14V-											
	FB-1E	1E SC-05			mum 0.5A	821KB00AAA0			0.6W										
400V	FB-1HE					DC220V													
440V	FB-2E		Serial contact		Serial contact	DCZZOV	Mini-		AC510V	820V									
	FB-3E		points: 3 (2.0A)		points: 3 (2.0A)		mum 1.0A		71.03.01	(738 - 902V)									
	FB-4E								A0		1.0W								
	FB-5E			ST-20	1	Ī	Mini-	TND20V- 821KB00AAA0											
	FB-8E			51-20			mum 1.5A	021100070170											
	FB-10E	_	-	ST-21	Serial contact		Mini- mum												
	FB-15E			3.21	points: 3 (4.0A)		3.0A												

- This recommended contactor type is for Fuji Electric FA Components & Systems Co., Ltd. and Mitsubishi Electric Corporation contactors. Products from other manufacturers are also allowable if they have equivalent capabilities.
- Recommended contactor contact point capacity indicates the DC-13 class rated operating current for the main contact, which is assumed to have durability regarding electronic opening and closing (service life) is approximately 2 million times. The ratings of the main and auxiliary contacts may differ, so please check the catalog or other sources.
- Among the recommended contactors, the Mitsubishi Electric Corporation S-T12 and S-T20 have one auxiliary contact. Please note that these 2 contractors are not usable when two or more auxiliary contact points are required for inverter drive and so on. (Other connectors in Table 6-5 have two auxiliary contact points.)
- This recommended varistor type is for ones made from Nippon Chemi-Con Corporation. Products from other manufacturers are also allowable if they have equivalent capabilities.
- A varistor for a single phase 100V is the same as the one for a single phase 200V.

Figure 6-4 Examples of Contact Point Connections with Quick-Braking Circuits



^{*} For inverter drives, connect to the R phase (power source side). Note: A motor with the indoor type MB brake does not have a rectifier's terminal 2 and a varistor (VR).

6-7 Capacitor Specification of Single Phase Power Source Motor

Table 6-6 Capacitor Run 15 - 90W (Accessory)

	M		Capacitor for Operation							
Voltage (V)	Type	Capacity (W)		Capacity Range (µF)	Withstand Voltage (V)					
			15	5						
			25	7						
	Cinalo phoso	40	Frame size: 05 07	12						
	Single phase	40	Frame size: 17 1240	14						
			60	18						
100			90	25	220					
100	Single phase reversible		15	6	220					
		Single phase	Single phase	25		10				
				Single phase	Single phase	Single phase	Single phase	Single phase	40	Frame size: 05 07
		40	Frame size: 17 1240	16						
			60	22						
			90	32						
				3.5						
	Single phase		60	4.5						
200		90		6.5	440					
	Cinalo aboso	40		4	440					
	Single phase reversible		60	5.5						
	reversible	reversible 90		8						

Table 6-7 Capacitor Starting Capacitor Run 0.1 - 0.4kW (Built in the Terminal Box)

M	otor	Capacitor	for Starting	Capacitor for Operation		
Valtage (V)	Composity (IdM)	Capacity	Withstand	Capacity	Withstand	
Voltage (V)	Capacity (kW)	Range (µF)	Voltage (V)	Range (µF)	Voltage (V)	
	0.1	60		10		
100/200	0.2	100	125	20	230	
	0.4	200		40		

7. Operation Common

DANGER

- Do not approach or touch rotating parts (output shaft, etc.) during operation; otherwise, loose clothing may become caught in these rotating parts and injury may result.
- When the power supply is interrupted, be sure to turn off the power switch. Unexpected resumption of power may cause electric shock, personal injury, or damage to the equipment.
- Do not operate the unit with the terminal box cover removed. Return the terminal box cover to the original position after maintenance, otherwise, electric shock may result.
- Do not operate the machine while the brake is released by the manual brake release bolt; otherwise, falling, going out of control, or damage to the equipment may result.
- Do not use a single phase power source motor for applications which provide more load than maximum torque of the motor. otherwise, reverse overdrive may result.
- To reverse a single phase power source motor other than a reversible motor, be sure to stop the motor then reverse it; otherwise, overdrive may result with the rotation direction unchanged.

A CAUTION

- Do not put fingers or foreign objects into the opening of the gearmotor or reducer; otherwise, electric shock, injury, fire, or damage to the equipment may result.
- -The gearmotor or reducer becomes very hot during operation. Be careful not to touch with hands or body. Otherwise, burns may result.
- If any abnormality occurs during operation, stop operation immediately; otherwise, electric shock, personal injury, or fire may result.
- Do not operate the unit in excess of the load rating; otherwise, personal injury, or damage to the equipment may result.
- Do not touch the current-carrying part of a capacitor for starting a single phase motor until it is fully discharged; otherwise, electric shock may result.

Common 7. Operation

7-1 Items to Check Before Operation

After installation and wiring are completed, check the following items before operating.

- Is the wiring correct?
- Is the unit properly coupled with the driven machine?
- Are mounting bolts tightened firmly?
- Is the direction of rotation as required?

After confirming these items, operate without a load and gradually apply a load. Check the items shown in Table 7-1.

7-2 Items to Check During Operation

Table 7-1 Items to Check During Operation

Does abnormal sound or vibration generate?	- Is the housing deformed because the installation surface is not flat? - Is insufficient rigidity of the installation base generating resonance? - Is the shaft center aligned with the driven machine? - Is the vibration of the driven machine transmitted to the gearmotor or reducer?
Is the surface temperature abnormally high?	- Does the voltage rise or drop substantially? - Is the ambient temperature too high? - Does the current flowing to the gearmotor exceed the rated current shown on the nameplate?

If any abnormalities are found, immediately stop operation and contact the nearest authorized maintenance shop.

7-3 Brake Torque and Activation Delay Time

The table below shows standard specification brake types, their brake torque, and their relationship to brake activation delay time.

Table 7-2 SB Brakes and MB Brakes

		Motor Ca	pacity (W)		Brake /	Activation Delay T	ime (s)
Brake Type	Frame Size	3-Phase Motor	Single Phase Motor	Brake Torque (Dynamic Friction Torque) (N·m)	Circuit	Normal Braking Circuit for Inverter (Separate Turn- Off Circuit)	Quick-Braking Circuit
SB-004	01 03 05 07	15 25 40 60	15 25 40	0.4	0.1 - 0.2	0.08 - 0.12	0.005 - 0.015
MB-003	17 1240	40	40	0.3	0.07.012	0.02.006	0.02 0.06
MB-005	15 17 1240	60 90	60 90	0.5	0.07 - 0.12	0.03 - 0.06	0.03 - 0.06

Table 7-3 With Brake

Table 7-3	WILLIDIAN									
			Motor Cap	acity (kW)				Brake Ac	tivation Dela	y Time (s)
Brake Type	3-Phase Motor	Premium- Efficiency, 3-Phase Motor	3-phase Motor for Inverter	Premium- Efficiency, 3-Phase Motor for Inverter	High- Efficiency, 3-Phase Motor	Single Phase Motor	Brake Torque (Dynamic Friction Torque) (N·m)	Normal Braking Circuit (Simul- taneous Turn-Off Circuit)	Normal Braking Circuit for Inverter (Separate Turn-Off Circuit)	Quick- Braking Circuit
FB-01A1	0.1	-	-	-	-	0.1	1.0	0.15-	0.00 0.12	0.015 - 0.02
FB-02A1	0.2	-	0.1	-	-	0.2	2.0	0.2	0.08 - 0.12	0.015 - 0.02
FB-05A1	0.25 0.4	-	0.2	-	0.2	-	4.0	0.1- 0.15	0.03 - 0.07	0.01 - 0.015
FB-1D	-		-		-	0.4	4.0	0.2-	0.1-	0.01 - 0.02
FB-ID	0.55	-	0.4	-	0.4	-	7.5	0.3	0.15	0.01 - 0.02
FB-1E	-	0.75	-	0.75	-	-	7.5	0.25 - 0.45	0.15 - 0.25	
FB-1HE	-	1.1	-	-	-	-	11	0.45 - 0.65	0.25 - 0.35	0.01 - 0.03
FB-2E	-	1.5	-	1.5	-	-	15	0.35 - 0.55	0.15 - 0.25	
FB-3E	-	2.2	-	2.2	-	-	22	0.75 - 0.95	0.4- 0.5	
FB-4E	-	3.0	-	-	-	-	30	0.65 - 0.85	0.3- 0.4	
FB-5E	-	3.7	-	3.7	-	-	40	1.1 - 1.3	0.4 - 0.5	0.02 - 0.04
FB-8E	-	5.5	-	5.5	-	-	55	1.0 - 1.2	0.3 - 0.4	
FB-10E	-	7.5	-	7.5	-	-	80	1.8 - 2.0	0.6 - 0.7	
FB-15E	-	11	-	11	-	-	110	1.6 - 1.8	0.5 - 0.6	

Note: 1. Brake type may differ depending on specification. Check the nameplate.

- 2. Brake torque will change according to operating environment, operating conditions, the condition of the friction surface, etc. In particular, brake torque may not be at the prescribed level for initial operation, and after a long period of inactivity. In such a case turn the brake on and off under as light load as possible to contact the brake's friction surfaces.
- Brake activation delay time will change according to the brake's wiring circuit. Select the optimum circuit for the application.

Common 8. Daily Inspection and Maintenance

⚠ DANGER

- Do not handle the unit when cables are energized. Be sure to turn off the power when working on the unit; otherwise, electric shock may result.
- Do not approach or touch any rotating parts (output shaft, etc.) during maintenance or the inspection with operating the unit; loose clothing may become caught in these rotating parts and cause serious injury or death.
- For explosion proof motor, customers must not disassemble or modify; otherwise, explosion, ignition, electric shock, or damage to the equipment may result.
- For explosion proof motor, the lead-in condition shall conform to the facility's regulations, electrical codes, and explosion proofing standard, as well as the maintenance manual; Additionally, do not open the terminal box cover while operating. otherwise, explosion, ignition, electric shock, or damage to the equipment may result.
- Do not operate the machine while the brake is released by the manual brake release bolt; otherwise, falling, going out of control, or damage to the equipment may result.

A CAUTION

- Do not put fingers or foreign objects into the opening of the gearmotor or reducer; otherwise, electric shock, injury, fire, or damage to the equipment may result.
- The gearmotor or reducer becomes very hot during operation. Do not touch the product with bare hands. Otherwise, burns may result.
- Do not touch the terminals when measuring insulation resistance; otherwise, electric shock may result.
- Do not operate the unit without a safety cover (removed during inspection) in place to shield rotating parts; otherwise, loose clothing may become caught in these rotating parts and injury may result.
- In the case that any abnormality is observed, promptly identify and correct, according to instructions in this maintenance manual. Do not operate until the cause for the abnormality is understood, and the abnormality is corrected.
- Do not operate damaged gearmotors or reducers; otherwise, injury, fire, or damage to the equipment may result.
- We cannot assume any responsibility for damage or injury resulting from an unauthorized modification by a customer, as it is outside the scope of the warranty.
- Dispose gearmotor or reducer lubricant as general industrial waste.
- For explosion proof motor, when measuring the insulation resistance, confirm that there is no gas or explosive vapor in the vicinity in order to prevent explosion or ignition.
- Changing brake linings requires experience. Consult with the nearest authorized maintenance
- Brake torque will change depending on operation environment and conditions, the condition of the friction surface, and other factors. In particular, brake torque may not be at the prescribed level for initial operation, and after a long period of inactivity. In such a case turn the brake on and off under as light load as possible to contact the brake's friction surfaces.



8-1. Daily Inspection

Make certain to carry out daily inspections in accordance with Table 8-1. Neglecting inspections is a source of trouble.

Table 8-1. Daily Inspection

Inspection Item	Inspection Detail
Current O D B	Is the current no greater than the rated value shown on the nameplate?
Noise	Are there unusual noises, or are there extreme changes in the noises?
Vibration	Is there abnormally large vibration? Are there extreme changes?
Surface temperature	Is surface temperature unusually high? Is there a sudden rise? / Temperature rises during operation will differ according to model and type. However, in case the difference between the gear unit surface temperature and the environment temperature is approximately 40°C, there is no particular trouble if fluctuation is slight.
Grease leaks	Is grease leaking from the gear unit? Are the oil seal sliding surfaces corroded?
Mounting bolts	Are the mounting bolts loose?
Chain, V-belt	Are the chain or V-belt loose?

- For a motor with the capacity of 90W or less, the current value of the motor may stay high temporarily due to increased viscosity of grease for the gear unit and motor bearing grease during cold winter. There are no concerns of burnout of a motor even if the current may exceed the rated current value for 5 to 15 minutes in a no load operation.
 - Considerations may be needed for the current value setting of an overload protection device, including an electronic thermal relay and selection of an inverter capacity range. Contact us for details.
- If any problems are found in a daily inspection, follow "9. Troubleshooting" (on P76 and 77) to take appropriate actions. If these actions do not correct the issue, immediately contact the nearest authorized maintenance shop.

8-2 Main Unit Maintenance

- Because long-life grease is used for gear, it can run for a long time without replenishment, maintenance with disassembly after approximately 20,000 hours or 3 to 5 years will increase lifetime.
- Contact the nearest authorized maintenance shop regarding maintenance with disassembly.
- Oil seals have a lifetime. During long use, natural degradation and frictional wear will reduce effectiveness. Reducer operating conditions and ambient environment will cause lifetime to widely vary. Given normal operation, (uniform load, running 10 hours per day, normal temperature) as a guideline, it is recommended to change them every 1 to 3 years. If the sliding surfaces of oil seals or V-rings show signs of wear or corrosion, replace them with new ones. Sliding surfaces are made of carbon steel, so rain water, condensation and other factors could cause rust to form and spread. Because this could lead to oil seal damage, take regular rust prevention measures. About replacing oil seal and V-ring, please consult with nearest authorized maintenance shop.
- If the unit stops and starts frequently, mounting bolts (or nuts) may come loose. Periodically check for looseness as it is a source of miss-alignment, oil leakages, and load unbalance.

8-3 Brake Maintenance and Inspection

⚠ DANGER

- Do not handle the unit when cables are energized. Be sure to turn off the power when working on the unit; otherwise, electric shock may result.
- When using the unit for lifting, do not release the brake while a load is suspended; otherwise it could fall, causing an accident.
- Do not operate the machine while the brake is released by the manual brake release bolt; otherwise, falling, going out of control, or damage to the equipment may result.
- Before operation, turn power on and off to check brake action; otherwise falling or running out of control could occur.
- Do not bring water or oils in contact with the brake. Brake torque degradation could cause falling or running out of control.

A CAUTION

- After gap inspection and adjustment, do not operate with the fan cover removed. otherwise, loose clothing may become caught in these rotating parts and injury may result.
- Changing brake linings requires experience. Consult with the nearest authorized maintenance shop.

Given normal operation conditions, brake mechanical lifetime is quite long at 2 million times. These conditions include the moment of inertia for the load being no greater than the moment of inertia for the brakemotor. However, please periodically inspect the brake gap (G). The brake lining wears after long hours of running time, making it impossible for the brake to release. When operating times exceed 2 million, wear and damage to mechanical parts may cause dropping or overdrive problems.

8-4 Brake Construction and Gap Inspection and Adjustment

- The brake is spring activated (power-off type).
- The brake lining wears after long hours of operating the brake, making it impossible for the brake to release. Therefore please periodically inspect the brake gap (G).
- If on inspection, the gap is close to the limit value, adjust the gap.
- In FB-1E 4E a shock absorber is inserted between the stationary core and the armature plate to reduce the noise that results from the braking action.

When inspecting, be careful that the gap gauge, other measuring tool or anything else does not damage the shock absorber or cause it to fall out.

There is danger that if the shock absorber is damaged or falls out, brake noise will increase and the brake will not function properly.

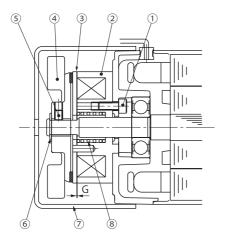
Table 8-2 Pages Containing Information on Brake Construction and Gap Inspection and Adjustment

table of 2 rages containing information on brance construction and sup inspection and ragastinent						
Brake Type	Indoor	Outdoor/Waterproof				
SB-004	P55	P64				
MB-003, MB-005	P56	P65				
FB-01A1, FB-02A1 - FB-05A1	P57	P66				
FB-1D	P58	P67				
FB-1E	P59	P68				
FB-1HE, FB-2E	P60	P69				
FB-3E, FB-4E	P61	P70				
FB-5E, FB-8E	P62	P71				
FB-10E, FB-15E	P63	P72				

Note: Please refer to P73 for the way to remove and install One-Touch Release lever (optional).



■ SB-004 (Indoor Type)



Part Number	Part Name			
1	Brake mounting bolt			
2	Stationary core			
3	Armature plate			
4	Lining with fan			
5	Set screw			
6	Snap ring			
7	Cover			
8	Torque spring			

Figure 8-1

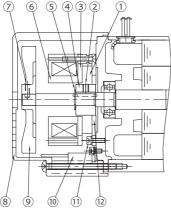
- Gap Inspection

- (1) Remove the cover [7].
- (2) Insert a gap gauge between the stationary core [2] and the armature plate [3] and measure the gap. Measure in 3 locations around the circumference.
- (3) Adjustment is required if the gap value is close to the limit.

Gap Value G (mm)					
Required value	Limit value				
(original value)	Lillill value				
0.15 - 0.25	0.4				

- (1) Remove the cover [7].
- (2) Loosen the set screw [5]. (Anti-loose locking is provided.)
- (3) Insert a gap gauge between the stationary core [2] and the armature plate [3] to adjust to a specified
- (4) Apply a locking agent to the set screw [5] to fix the lining with fan [4].
- (5) Attach the cover [7].

■ MB-003, 005 (Indoor Type)



		
╞ ┼		Fan
	9	(mounted for single p
		60 and 90W only)
	10	Rectifier
	11	Brake mounting bolt
(12)	12	Fixed plate

Part

Number

3

6

7

8

Figure 8-2

- Gap Inspection

- (1) Remove cover [8].
- (2) Insert a gap gauge between the stationary core [6] and the armature plate [3], and measure the gap. Measure in 3 locations around the circumference.

Gap Value G (mm)				
Required value	Limit value			
(original value)	Littill Value			
0.05 - 0.25	0.35			

Part Name

Shaft-retaining E-ring Stationary core

for single phase

Brake lining Boss set screw Armature plate

Fan set screw

Boss

Cover

(3) The brake lining must be replaced if the gap value is close to the limit. (You cannot adjust the gap.)



■ FB-01A1, 02A1, 05A1 (Indoor Type)

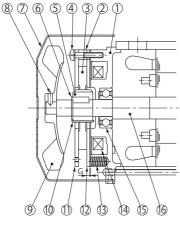


Figure 8-3

Part	Part Name
Number	
1	Stationary core
2	Spacer
3	Brake lining
4	Attachment bolt
5	Boss
6	Shaft-retaining C-ring
7	Cover
8	Fan set screw
9	Fan
10	Leaf spring
11	Fixed plate
12	Armature plate
13	Spring
14	Electromagnetic coil
15	Bearing
16	Motor shaft

Note: FB-01A1 of a 3-phase motor 0.1kW does not have [8] and [9].

- Gap Inspection

- (1) Remove the cover [7].
- (2) Insert a gap gauge between the stationary core [1] and the armature plate [12], and measure the gap. Measure in 3 locations around the circumference.
- (3) Adjustment is required if the gap value is close to the limit.

Gap Value G (mm)	
Required value	Limit value
(original value)	Limit value
0.2 - 0.35	0.5

- Gap Adjustment

- (1) Remove the cover [7].
- (2) Loosen the fan set screw [8] and remove the fan [9].
- (3) Slightly loosen the attachment bolts [4] and rotate the fixed plate [11] counterclockwise, as far as it will go. Then tighten the attachment bolts [4]. After tightening, measure the gap (G) and check to see if the gap value is between the required value and the limit. (This operation will reduce the gap by
- (4) Turn the power on and off to check brake action.
- (5) Attach the fan [9] and cover [7]. Use a fan set screw [8] coated with Three Bond TB2365 (Sumitomo part number EW444WW-01), and tighten with a torque of 0.3 - 0.5 N·m.

Note: If the optional brake release bolt is installed, disassemble after removing the release bolt.

■ FB-1D (Indoor Type)

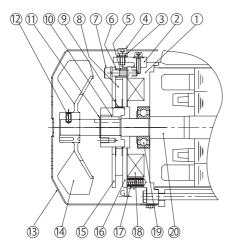


Figure	8-4
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Part	Part Name
Number	
1	Stationary core
2	Brake release
3	Manual release protection
3	spacer
4	Brake release bolt
5	Spacer
6	Gap adjusting shims
7	Attachment bolt
8	Brake lining
9	Leaf spring
10	Boss
11	Shaft-retaining C-ring
12	Fan set screw
13	Cover
14	Fan
15	Fixed plate
16	Armature plate
17	Spring
18	Electromagnetic coil
19	Bearing
20	Motor shaft

Gap Value G (mm)

Limit value

0.6

Required value

(original value)

0.3 - 0.4

- Gap Inspection

- (1) Remove the brake release bolt [4] and the manual release prevention spacer [3].
- (2) Remove the cover [13].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [16] and measure the gap. Measure in 3 locations around the circumference.
- (4) Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.2 - 0.25 mm. Adjustment cannot be made at a lower value.)

- (1) Remove the brake release bolt [4] and the manual release prevention spacer [3].
- (2) Remove the cover [13].
- (3) Remove the fan set screw [12] and remove the fan [14].
- (4) Loosen the attachment bolts [7] and remove the spacers [5], gap adjustment shims [6], attachment bolts [7] and fixed plate [15] as a set. When removing the attachment bolts [7], make certain not to take off the gap adjustment shims [6].
- (5) The gap adjustment shims [6] have a thickness of 0.2 0.25 mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [5], gap adjustment shims [6], attachment bolts [7] and the fixed plate [15] as a set.
- (6) Check the gap G, and readjust the shims if there is a large difference between the gap and the required value.
- (7) Turn the power on and off to check brake action.
- (8) Attach the fan [14], fan set screw [12] and cover [13]. Use a fan set screw [12] coated with Three Bond TB2365 (Sumitomo part number EW445WW-01), and tighten with a torque of 0.85 - 1.05 N⋅m. Finally, attach the brake release bolt [4] and the manual release prevention spacer [3].



FB-1E (Indoor Type)

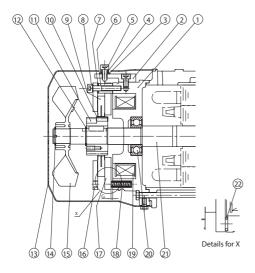


Figure 8-5

Part	Do at Nove o	
Number	Part Name	
1	Stationary core	
2	Brake release	
3	Seal washer	
4	Manual release prevention	
4	spacer	
5	Brake release bolt	
6	Spacer	
7	Gap adjusting shims	
8	Attachment bolt	
9	Brake lining	
10	Leaf spring	
11	Boss	
12	Shaft-retaining C-ring	
13	Cover	
14	Shaft-retaining C-ring	
15	Fan	
16	Fixed plate	
17	Armature plate	
18	Spring	
19	Electromagnetic coil	
20	Ball bearings	
21	Motor shaft	
22	Shock absorber	

Gap Value G (mm)

Limit value

0.6

Required value

(original value)

0.25 - 0.35

- Gap Inspection

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [13].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [17] and measure the gap. Measure in 3 locations around the circumference.
- (4) Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.2 - 0.25 mm. Adjustment cannot be made at a lower value.)

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [13].
- (3) Remove the shaft-retaining C-ring [14], and remove the fan [15].
- (4) Loosen the attachment bolts [8] and remove the spacers [6], gap adjustment shims [7], attachment bolts [8] and fixed plate [16] as a set. When removing the attachment bolts [8], make certain not to take off the gap adjustment shims [7] or the shock absorber [22].
- (5) The gap adjustment shims [7] have a thickness of 0.2 0.25 mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [6], gap adjustment shims [7], attachment bolts [8] and the fixed plate [16] as a set.
- (6) Check the gap G, and readjust the shims if there is a large difference between the gap and the required value.
- (7) Turn the power on and off to check brake action.
- (8) Attach the fan [15], shaft-retaining C-ring [14] and cover [13].
- (9) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].

■ FB-1HE, FB-2E (Indoor Type)

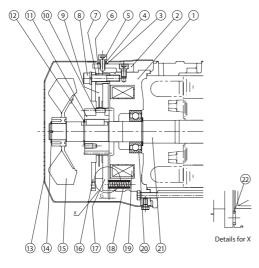


Figure 8-6

Part		
	Part Name	
Number		
1	Stationary core	
2	Brake release	
3	Seal washer	
4	Manual release	
	prevention spacer	
5	Brake release bolt	
6	Spacer	
7	Gap adjusting shims	
8	Attachment bolt	
9	Brake lining	
10	Leaf spring	
11	Boss	
12	Shaft-retaining C-ring	
13	Cover	
14	Shaft-retaining C-ring	
15	Fan	
16	Fixed plate	
17	Armature plate	
18	Spring	
19	Electromagnetic coil	
20	Ball bearings	
21	Motor shaft	
22	Shock absorber	

Gap Value G (mm)

Limit value

0.75

Required value

(original value)

0.25 - 0.35

- Gap Inspection

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [13].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [17] and measure the gap. Measure in 3 locations around the circumference.
- (4) Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.35 - 0.45mm. Adjustment cannot be made at a lower value.)

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [13].
- (3) Remove the shaft-retaining C-ring [14], and remove the fan [15].
- (4) Loosen the attachment bolts [8] and remove the spacers [6], gap adjustment shims [7], attachment bolts [8] and fixed plate [16] as a set. When removing the attachment bolts [8], make certain not to take off the gap adjustment shims [7] or the shock absorber [22].
- (5) The gap adjustment shims [7] have a thickness of 0.35 0.45mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [6], gap adjustment shims [7], attachment bolts [8] and the fixed plate [16] as a set.
- (6) Check the gap G, and readjust the shims if there is a large difference between the gap and the required value.
- (7) Turn the power on and off to check brake action.
- (8) Attach the fan [15], shaft-retaining C-ring [14], and cover [13].
- (9) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].



■ FB-3E, FB-4E (Indoor Type)

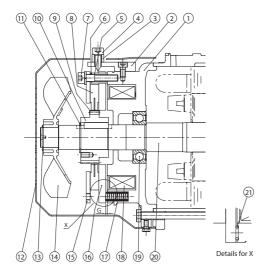


Figure 8-7

Part		
	Part Name	
Number		
1	Stationary core	
2	Brake release	
3	Manual release prevention	
3	spacer	
4	Brake release bolt	
5	Spacer	
6	Gap adjusting shims	
7	Attachment bolt	
8	Brake lining	
9	Leaf spring	
10	Boss	
11	Shaft-retaining C-ring	
12	Cover	
13	Shaft-retaining C-ring	
14	Fan	
15	Fixed plate	
16	Armature plate	
17	Spring	
18	Electromagnetic coil	
19	Ball bearings	
20	Motor shaft	
21	Shock absorber	

Gap Value G (mm)

Limit value

0.85

Required value

(original value)

0.25 - 0.35

- Gap Inspection

- (1) Remove the brake release bolt [4] and the manual release prevention spacer [3].
- (2) Remove the cover [12].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [16] and measure the gap. Measure in 3 locations around the circumference.
- (4) Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.45 - 0.55mm. Adjustment cannot be made at a lower value.)

- (1) Remove the brake release bolt [4] and the manual release prevention spacer [3].
- (2) Remove the cover [12].
- (3) Remove the shaft-retaining C-ring [13] and the fan [14].
- (4) Loosen the attachment bolts [7] and remove the spacers [5], gap adjustment shims [6], attachment bolts [7] and fixed plate [15] as a set. When removing the attachment bolts [7], make certain not to take off the gap adjustment shims [6] or the shock absorber [21].
- (5) The gap adjustment shims [6] have a thickness of 0.45 0.55 mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [5], gap adjustment shims [6], attachment bolts [7] and fixed plate [15] as a set.
- (6) Check the gap G, and readjust the shims if there is a large difference between the gap and the required value.
- (7) Turn the power on and off to check brake action.
- (8) Attach the fan [14], shaft-retaining C-ring [13] and cover [12].
- (9) Finally, attach the brake release bolt [4] and the manual release prevention spacer [3].

■ FB-5E, FB-8E (Indoor Type)

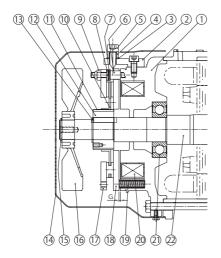


Figure 8-8

Part	Part Name
Number	
1	Stationary core
2	Brake release
3	Seal washer
4	Manual release
	prevention spacer
5	Brake release bolt
6	Stud bolt
7	Adjusting washer
8	Spring washer
9	Gap adjusting nut
10	Brake lining
11	Leaf spring
12	Boss
13	Shaft-retaining C-ring
14	Cover
15	Shaft-retaining C-ring
16	Fan
17	Fixed plate
18	Armature plate
19	Spring
20	Electromagnetic coil
21	Ball bearings
22	Motor shaft

- Gap Inspection

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [14].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [18] and measure the gap. Measure in 3 locations around the circumference.
- (4) Adjustment is required if the gap value is close to the limit.

Required value (original value)	Limit value
0.35 - 0.45	1.0

Gap Value G (mm)

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [14].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [18], rotating to the right the gap adjusting nuts [9] that are attached to ends of the stud bolts [6]. If large adjustments to the gap are not possible, decrease the number of adjusting washers [7]. There are 3 gap adjusting nuts [9]. Adjust these in turn so that 3 positions on the circumference are uniformly at the required gap.
- (4) Turn the power on and off to check brake action.
- (5) Attach the cover [14].
- (6) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].



FB-10E, FB-15E (Indoor Type)

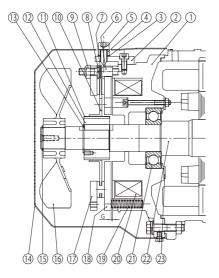


Figure 8-9

Part	Part Name	
number		
1	Stationary core	
2	Brake release	
3	Seal washer	
4	Manual release	
	prevention spacer	
5	Brake release bolt	
6	Stud bolt	
7	Adjusting washer	
8	Spring washer	
9	Gap adjusting nut	
10	Brake lining	
11	Leaf spring	
12	Boss	
13	Shaft-retaining C-ring	
14	Cover	
15	Shaft-retaining C-ring	
16	Fan	
17	Fixed plate	
18	Armature plate	
19	Spring	
20	Electromagnetic coil	
21	Ball bearings	
22	Motor shaft	
23	Bearing cover	

Gap Value G (mm)

Limit value

1.2

Required value

(original value)

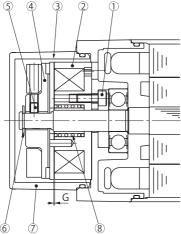
- Gap Inspection

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [14].
- 0.35 0.45 (3) Insert a gap gauge between the stationary core [1] and the armature plate [18], measuring the gap. Measure in 3 locations around the circumference.
- (4) Adjustment is required if the gap value is close to the limit.

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [14].
- (3) Insert a gap gauge between the stationary core [1] and the armature plate [18], rotating to the right the gap adjusting nuts [9] that are attached to ends of the stud bolts [6]. If large adjustments to the gap are not possible, decrease the number of adjusting washers [7]. There are 3 adjusting nuts [9]. Adjust these in turn so that 3 positions on the circumference are uniformly at the required gap.
- (4) Turn the power on and off to check brake action.
- (5) Attach the cover [14].
- (6) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].



■ SB-004 (Waterproof)



(8)
Figure	8-10

Part	Part Name
Number	raitiNaille
1	Brake mounting bolt
2	Stationary core
3	Armature plate
4	Lining with fan
5	Set screw
6	Snap ring
7	Cover
8	Torque spring

- Gap Inspection

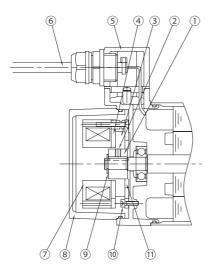
- (1) Remove the cover [7].
- (2) Insert a gap gauge between the stationary core [2] and the armature plate [3], measuring the gap. Measure in 3 locations around the circumference.
- (3) Adjustment is required if the gap value is close to the limit.

Gap Value G (mm)			
Required value	Limit value		
(original value)	Littiit value		
0.15 - 0.25	0.4		

- (1) Remove the cover [7].
- (2) Loosen the set screw [5]. (Anti-loose locking is provided.)
- (3) Insert a gap gauge between the stationary core [2] and the armature plate [3] to adjust to a specified gap.
- (4) Apply a locking agent to the set screw [5] to fix the lining with fan [4].
- (5) Attach the cover [7]. (Make sure that O-rings are not damaged. If damaged, replace them with new ones.)



■ MB-003, 005 (Waterproof)



IV	lumber	
	1	Boss
	2	Boss set screw
	3	Brake lining
	4	Armature plate
	5	waterproof/dust-proof box
	6	cab tire cable
	7	Stationary core
	8	Cover
	9	Shaft-retaining E-ring
	10	Brake mounting bolt
	11	Fixed plate

Part Name

Part

Figure 8-11

- Gap Inspection

- (1) Remove the cover [8].
- (2) Insert a gap gauge between the stationary core [7] and the armature plate [4], measuring the gap. Measure in 3 locations around the circumference.

Gap Value G (mm)			
Required value (original value)	Limit value		
0.05 - 0.25	0.35		

(3) The brake lining must be replaced if the gap value is close to the limit. (You cannot adjust the gap.)

FB-01A1, 02A1, 05A1 (Outdoor Type)

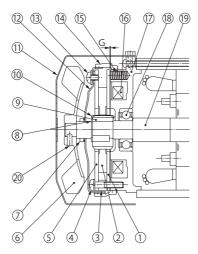


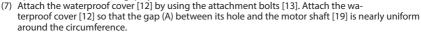
Figure 8-12

- Gap Inspection

- (1) Remove the cover ([11].
- (2) Loosen the fan set screw [20] and remove the fan [6].
- (3) Remove the waterproof seal [14].
- (4) Insert a gap gauge between the stationary core [17] and the armature plate [1], measuring the gap. Measure in 3 locations around the circumference.
- (5) Adjustment is required if the gap value is close to the limit.

- Gap Adjustment

- (1) Remove the cover [11].
- (2) Loosen the fan set screw [20] and remove the fan [6].
- (3) Remove the waterproof seal [14].
- (4) Pull off the V-ring [7].
- (5) Remove the waterproof cover attachment bolts [13], and remove the waterproof cover [12].
- (6) Slightly loosen the attachment bolts [4] and rotate the fixed plate [5] counter clockwise, until it will go. Then tighten the attachment bolts [4]. After tightening, measure the gap (G) and check to see if the gap value is between the required value and the limit. (This operation will reduce the gap by 0.3 mm.)



(8) Clean the surface of the waterproof seal [14] to remove impurities.

- (9) As shown in the construction drawings, install the waterproof seal [14] between the stationary core [17] and the waterproof cover [12]. Insert the waterproof seal [14] with its arrow mark pointing toward the load side. (Align the hole in the waterproof seal [14] for the release bolt with the position of the release bolt.) Attach the waterproof seal [14] so that its protrusion fits snugly around the entire circumference of the groove for the stationary core [17]. Otherwise water could leak in.
- (10) Turn the power on and off to check brake action.
- (11) Attach the V-ring [7]. Wipe off the lip and surface near the lip of the V-ring [7], lightly coat the lip surface with grease and attach. Observe the attaching dimension (B = 4.5mm).
- (12) Attach the fan [7] and cover [11]. Use a fan set screw [20] coated with Three Bond TB2365 (Sumitomo part number EW444WW-01), and tighten to a torque of 0.3 - 0.5 N·m.

Note: If the optional brake release bolt is installed, disassemble after removing the release bolt.

Part	Part Name	
Number	Part Name	
1	Armature plate	
2	Brake lining	
3	Spacer	
4	Attachment bolt	
5	Fixed plate	
6	Fan	
7	V-ring	
8	Shaft retaining C-ring	
9	Boss	
10	Leaf spring	
11	Cover	
12	Waterproof cover	
13	Waterproof cover	
13	attachment bolts	
14	Waterproof seal	
15	Spring	
16	Electromagnetic coil	
17	Stationary core	
18	Bearing	
19	Motor shaft	
20	Fan set screw	

Note: FB-01A1 of a 3-phase motor 0.1kW does not have [6], [7] and [20].

Gap Valu	e G (mm)
Required value	Limit value
(original value)	Limit value
0.2 - 0.35	0.5









■ FB-1D (Outdoor Type)

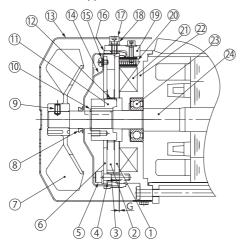


Figure 8-13

- Gap Inspection

- Remove the brake release bolt [17] and the manual release prevention spacer [18].
- (2) Remove the cover [13].
- (3) Loosen the fan set screw [9] and remove the fan [7].
- (4) Remove the brake release [19], (2 locations)
- (5) Remove the waterproof seal [16].
- (6) Insert a gap gauge between the stationary core [22] and the armature plate [1], and measure the gap. Measure in 3 locations around the circumference.
- (7) Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.2 - 0.25 mm. Adjustment cannot be made at a lower value.)

Part	Part Name
Number	Part Name
1	Armature plate
2	Brake lining
3	Spacer
4	Gap adjusting shims
5	Attachment bolt
6	Fixed plate
7	Fan
8	V-ring
9	Fan set screw
10	Shaft retaining C-ring
11	Boss
12	Leaf spring
13	Cover
14	Waterproof cover
15	Waterproof cover
13	attachment bolts
16	Waterproof seal
17	Brake release bolt
18	Manual release protection
10	spacer
19	Brake release
20	Spring
21	Electromagnetic coil
22	Stationary core
23	Bearing
24	Motor shaft

Gap Value G (mm)				
Required value (original value)	Limit value			
0.3 - 0.4	0.6			

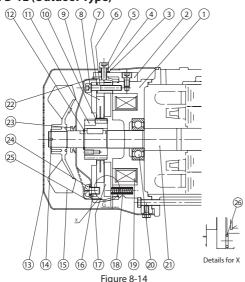
- (1) Remove the brake release bolt [17] and the manual release prevention spacer [18].
- (2) Remove the cover [13].
- (3) Loosen the fan set screw [9] and remove the fan [7].
- (4) Pull off the V-ring [8].
- (5) Remove the brake release [19], (2 locations)
- (6) Remove the waterproof seal [16].
- (7) Remove the waterproof cover attachment bolts [15], and remove the waterproof cover [14].
- (8) Loosen the attachment bolts [5] and remove the spacers [3], gap adjusting shims [4], attachment bolts [5], fixed plate[6] as a set. When removing the attachment bolts [5], make certain not to take off the gap adjust-



- (10) Check the gap G, and readjust the shims if there is a large difference between it and the required value.
- (11) Attach the waterproof cover [14] by using the attachment bolts [15]. Attach the waterproof cover [14] so that the gap (A) between its hole and the motor shaft [24] is nearly uniform.
- (12) Clean the surface of the waterproof seal [16] to remove impurities.
- (13) As shown in the construction drawings, install the waterproof seal [16] between the stationary core [22] and the waterproof cover [14]. Then attach the brake release [19]. Insert the waterproof seal [16] with its arrow mark pointing toward the load side. Align the hole in the waterproof seal [16] for the release bolt with the position of release bolt [17]. Attach the waterproof seal [16] so that its protrusion fits snugly around the entire circumference of the groove for the stationary core [22]. Otherwise water could leak in.
- (14) Turn the power on and off to check brake action.
- (15) Attach the V-ring [8]. Wipe off the lip and surface near the lip of V-ring [8], lightly coat the lip surface with grease, and attach. Observe the attaching dimension (B = 4.5mm).
- (16) Attach the fan [7] and cover [13]. Use a fan set screw [9] coated with Three Bond TB2365 (Sumitomo part number EW445WW-01), and tighten with a torque of 0.85 - 1.05 N m. Finally, attach the brake release bolt [17] and the manual release prevention spacer [18].



■ FB-1E (Outdoor Type)

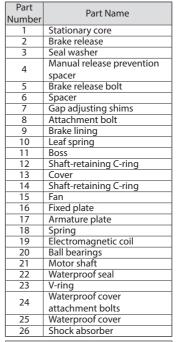


- Gap Inspection

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [13].
- (3) Remove the shaft-retaining C-ring [14], and remove the fan [15].
- (4) Remove the brake release [2] (2 locations) and remove the waterproof
- (5) Insert a gap gauge between the stationary core [1] and the armature plate [17] and measure the gap. Measure in 3 locations around the
- (6) Adjustment is required if the gap value is close to the limit. (Gáp adjustment shim thickness is approximately 0.2 - 0.25 mm. Adjustment cannot be made at a lower value.)

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- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2) Remove the cover [13].
- (3) Remove the shaft-retaining C-ring [14], and remove the fan [15].
- (4) Pull off the V-ring [23].
- (5) Remove the brake release [2] (2 locations) and remove the waterproof seal [22].
- (6) Remove the waterproof cover attachment bolts [24], and remove the waterproof cover [25].
- (7) Loosen the attachment bolts [8] and remove the spacers [6], gap adjustment shims [7], attachment bolts [8] and fixed plate [16] as a set. When removing the attachment bolts [8], make certain not to take off the gap adjustment shims [7] and the shock absorber [26].
- The gap adjustment shims [7] have a thickness of 0.2 0.25 mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [6], gap adjustment shims [7], attachment bolts [8] and the fixed plate [16] as a set.
- (9) Check the gap G, and readjust the shims if there is a large difference between it and the required value.
- (10) Attach the waterproof cover [25] by using the waterproof cover attachment bolts [24]. At this time align the cutout area on the side of the waterproof cover [25] with the brake release bolt [5]. Attach the waterproof cover [25] so that the gap (A) between its hole and the motor shaft [21] is nearly uniform.
- (11) Clean the surface of the waterproof seal [22] to remove impurities.
- (12) As shown in the construction drawings, install the waterproof seal [22] between the stationary core [1] and the waterproof cover [25]. Then attach the brake release [2]. Insert the waterproof seal [22] with its arrow mark pointing toward the load side. Align the hole in the waterproof seal [22] for the brake release bolt with the position of the release bolt [5]. Attach the waterproof seal [22] so that its protrusion fits snugly around the entire circumference of the groove for the stationary core [1]. (Be careful that the waterproof seal [22] does not meander. Otherwise water could leak in.)
- (13) Turn the power on and off to check brake action.
- (14) Attach the V-ring [23]. Wipe off the lip and surface near the lip of the V-ring [23], lightly coat the lip surface with grease, and attach. Observe the attaching dimension (B = 6mm).
- (15) Attach the fan [15], shaft-retaining C-ring [14] and cover [13].
- (16) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].



Gap Value G (mm)			
Required value	Limit value		
(original value)	Liffiit value		
0.25 - 0.35	0.6		



■ FB-1HE, FB-2E (Outdoor Type)

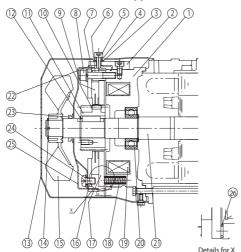


Figure 8-15

- Gap Inspection

- (1) Remove the brake release bolt [5] and the manual release prevention spacer [4].
- Remove the cover [13].
- Remove the shaft-retaining C-ring [14], and remove the fan [15].
- Remove the brake release [2] (2 locations) and remove the waterproof seal [22].
- Insert a gap gauge between the stationary core [1] and the armature plate [17] and measure the gap. Measure in 3 locations around the
- Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.35 - 0.45mm. Adjustment cannot be made at a lower value.)

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- Remove the brake release bolt [5] and the manual release prevention spacer [4].
- Remove the cover [13].
- Remove the shaft-retaining C-ring [14], and remove the fan [15].
- Pull off the V-ring [23].
- Remove the brake release [2] (2 locations) and remove the waterproof seal [22].
- Remove the waterproof cover attachment bolts [24], and remove the waterproof cover [25].
- Loosen the attachment bolts [8] and remove the spacers [6], gap adjustment shims [7], attachment bolts [8] and fixed plate [16] as a set. When removing the attachment bolts [8], make certain not to take off the gap adjustment shims [7] or the shock absorber [26].
- The gap adjustment shims [7] have a thickness of 0.35 0.45mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [6], gap adjustment shims [7], attachment bolts [8] and the fixed plate [16] as a set.
- Check the gap G, and readjust the shims if there is a large difference between it and the required value.
- (10) Attach the waterproof cover [25] by using the waterproof cover attachment bolts [24]. At this time align the cutout area on the side of the waterproof cover [25] with the brake release bolt [5]. Attach the waterproof cover [25] so that the gap (A) between its hole and the motor shaft [21] is nearly uniform.
- (11) Clean the surface of the waterproof seal [22] to remove impurities.
- (12) As shown in the construction drawings, install the waterproof seal [22] between the stationary core [1] and the waterproof cover [25]. Then attach the brake release [2]. Insert the waterproof seal [22] with its arrow mark pointing toward the load side. Align the hole in the waterproof seal [22] for the brake release bolt with the position of the release bolt [5]. Attach the waterproof seal [22] so that its protrusion fits snugly around the entire circumference of the groove for the stationary core [1]. (Be careful that the waterproof seal [22] does not meander. Otherwise water could leak in.)
- (13) Turn the power on and off to check brake action.
- (14) Attach the V-ring [23]. Wipe off the lip and surface near the lip of the V-ring [23], lightly coat the lip surface with grease, and attach. Observe the attaching dimension (B = 6 mm).
- (15) Attach the fan [15], shaft-retaining C-ring [14] and cover [13].
- (16) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].



Gap Value G (mm)			
Required value (original value)	Limit value		
0.25 - 0.35	0.75		

FB-3E, FB-4E (Outdoor Type)

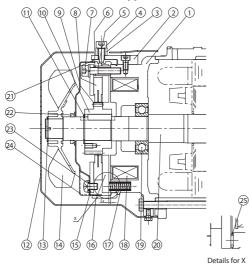


Figure 8-16

- Gap Inspection

- Remove the brake release bolt [4] and the manual release prevention spacer [5].
- Remove the cover [12].
- Remove the shaft-retaining C-ring [13] and the fan [14].
- Remove the brake release [2] (2 locations) and remove the waterproof seal [21]
- Insert a gap gauge between the stationary core [1] and the armature plate [16] and measure the gap. Measure in 3 locations around the
- Adjustment is required if the gap value is close to the limit. (Gap adjustment shim thickness is approximately 0.45 - 0.55mm. Adjustment cannot be made at a lower value.)

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- Remove the brake release bolt [4] and the manual release prevention spacer [5].
- Remove the cover [12].
- Remove the shaft-retaining C-ring [13] and the fan [14].
- Pull off the V-ring [22].
- Remove the brake release [2] (2 locations) and remove the waterproof seal [21].
- Remove the waterproof cover attachment bolts [23], and remove the waterproof cover [24].
- Loosen the attachment bolts [7] and remove the spacers [5], gap adjustment shims [6], attachment bolts [7] and fixed plate [15] as a set. When removing the attachment bolts [7], make certain not to take off the gap adjustment shims [6] or the shock absorber [25].
- The gap adjustment shims [6] have a thickness of 0.45 0.55 mm. Reduce the number of shims according to the wear conditions, then reassemble the spacers [5], gap adjustment shims [6], attachment bolts [7] and fixed plate [15] as a set.
- Check the gap G, and readjust the shims if there is a large difference between it and the required value.
- (10) Attach the waterproof cover [24] by using the waterproof cover attachment bolts [23]. At this time align the cutout area on the side of the waterproof cover [24] with the brake release bolt [4]. Attach the waterproof cover [24] so that the gap (A) between its hole and the motor shaft [20] is nearly uniform.
- (11) Clean the surface of the waterproof seal [21] to remove impurities.
- (12) As shown in the construction drawings, install the waterproof seal [21] between the stationary core [1] and the waterproof cover [24]. Then attach the brake release [2]. Align the hole in the waterproof seal [21] for the brake release bolt with the position of the release bolt [4]. Attach the waterproof seal [21] so that its protrusion fits snugly around the entire circumference of the groove for the stationary core [1]. (Be careful that the waterproof seal [21] does not meander. Otherwise water could leak in.)
- (13) Turn the power on and off to check brake action.
- (14) Attach the V-ring [22]. Wipe off the lip and surface near the lip of the V-ring [22], lightly coat the lip surface with grease, and attach. Observe the attaching dimension (B = 6mm).
- (15) Attach the fan [14], shaft-retaining C-ring [13] and cover [12].
- (16) Finally, attach the brake release bolt [4] and the manual release prevention spacer [3].

Part	Part Name	
Number		
1	Stationary core	
2	Brake release	
3	Manual release prevention	
	spacer	
4	Brake release bolt	
5	Spacer	
6	Gap adjusting shims	
7	Attachment bolt	
8	Brake lining	
9	Leaf spring	
10	Boss	
11	Shaft-retaining C-ring	
12	Cover	
13	Shaft-retaining C-ring	
14	Fan	
15	Fixed plate	
16	Armature plate	
17	Spring	
18	Electromagnetic coil	
19	Ball bearings	
20	Motor shaft	
21	Waterproof seal	
22	V-ring	
23	Waterproof cover	
	attachment bolts	
24	Waterproof cover	
25	Shock absorber	
	6 1/1 6/ 1	

Gap Value G (mm)		
Required value (original value)	Limit value	
0.25 - 0.35	0.85	

8. Daily Inspection and Maintenance



■ FB-5E, FB-8E (Outdoor Type)

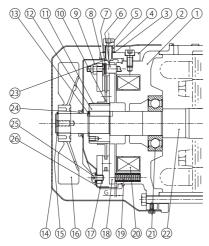


Figure 8-17

- Gap Inspection

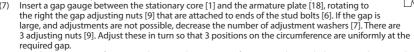
- Remove the brake release bolt [5] and the manual release prevention spacer [4].
- Remove the cover [14].
- Remove the shaft-retaining C-ring [15] and the fan [16].
- Remove the brake release [2] (2 locations) and remove the waterproof seal [23].
- Insert a gap gauge between the stationary core [1] and the armature plate [18] and measure the gap. Measure in 3 locations around the circumference.
- Adjustment is required if the gap value is close to the limit.

Part Number	Part Name
1	Stationary core
2	Brake release
3	Seal washer
4	Manual release prevention
4	spacer
5	Brake release bolt
6	Stud bolt
7	Adjusting washer
8	Spring washer
9	Gap adjusting nut
10	Brake lining
11	Leaf spring
12	Boss
13	Shaft-retaining C-ring
14	Cover
15	Shaft-retaining C-ring
16	Fan
17	Fixed plate
18	Armature plate
19	Spring
20	Electromagnetic coil
21	Ball bearings
22	Motor shaft
23	Waterproof seal
24	V-ring
25	Waterproof cover
	attachment bolts
26	Waterproof cover

Gap Value G (mm)				
Required value (original value)	Limit value			
0.35 - 0.45	1.0			

- Gap Adjustment

- Remove the brake release bolt [5] and the manual release prevention spacer [4].
- Remove the cover [14].
- Remove the shaft-retaining C-ring [15] and the fan [16]. (3)
- Pull off the V-ring [24].
- (5) Remove the brake release [2] (2 locations) and remove the waterproof seal [23].
- Remove the waterproof cover attachment bolts [25], and remove the waterproof cover [26].



- Attach the waterproof cover [26] by using the waterproof cover attachment bolts [25]. At this time align the cutout area on the side of the waterproof cover [26] with the brake release bolt [5]. Attach the waterproof cover [26] so that the gap (A) between its hole and the motor shaft [22] is nearly uniform.
- Clean the surface of the waterproof seal [23] to remove impurities.
- (10) As shown in the construction drawings, install the waterproof seal [23] between the stationary core [1] and the waterproof cover [26]. Then attach the brake release [2]. Align the hole in the waterproof seal [23] for the brake release bolt with the position of the release bolt [5]. Next, attach along the machined surfaces around the stationary core [1]. Be careful that the waterproof seal [23] does not meander. Otherwise water could leak in.)
- (11) Turn the power on and off to check brake action.
- (12) Attach the V-ring [24]. Wipe off the lip and surface near the lip of the V-ring [24], lightly coat the lip surface with grease, and attach. Observe the attaching dimension (B = 6mm).
- (13) Attach the fan [16], shaft-retaining C-ring [15] and cover [14].
- (14) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].



○ BI 8. Daily Inspection and Maintenance

■ FB-10E, FB-15E (Outdoor Type)

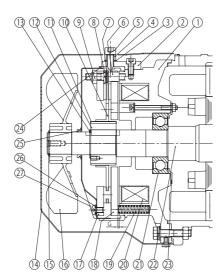


Figure 8-18

- Gap Inspection

- Remove the brake release bolt [5] and the manual release prevention spacer [4].
- Remove the cover [14].
- Remove the shaft-retaining C-ring [15] and the fan [16].
- Remove the brake release [2] (2 locations) and remove the waterproof seal [24].
- Insert a gap gauge between the stationary core [1] and the armature plate [18] and measure the gap. Measure in 3 locations around the circumference.
- Adjustment is required if the gap value is close to the limit.

Part	Part Name
Number	rait Name
1	Stationary core
2	Brake release
3	Seal washer
4	Manual release
	prevention spacer
5	Brake release bolt
6	Stud bolt
7	Adjusting washer
8	Spring washer
9	Gap adjusting nut
10	Brake lining
11	Leaf spring
12	Boss
13	Shaft-retaining C-ring
14	Cover
15	Shaft-retaining C-ring
16	Fan
17	Fixed plate
18	Armature plate
19	Spring
20	Electromagnetic coil
21	Ball bearings
22	Motor shaft
23	Bearing cover
24	Waterproof seal
25	V-ring
26	Waterproof cover
	attachment bolts
27	Waterproof cover

Gap Value G (mm)			
Required value	Limit value		
(original value)	Lillill value		
0.35 - 0.45	1.2		



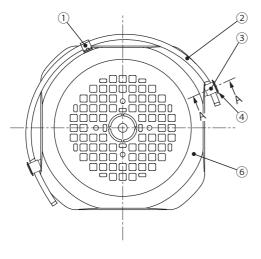
- Gap Adjustment

- Remove the brake release bolt [5] and the manual release prevention spacer [4].
- (2)Remove the cover [14].
- (3) Remove the shaft-retaining C-ring [15] and the fan [16].
- (4) Pull off the V-ring [25].
- (5) Remove the brake release [2] (2 locations) and remove the waterproof seal [24].
- Remove the waterproof cover attachment bolts [26], and remove the waterproof cover [27].
- Insert a gap gauge between the stationary core [1] and the armature plate [18], rotating to the right the gap adjusting nuts [9] that are attached to ends of the stud bolts [6]. If the gap is large, and adjustments are not possible, decrease the number of adjustment washers [7]. There are 3 adjusting nuts [9]. Adjust these in turn so that 3 positions on the circumference are uniformly at the required gap.
- Attach the waterproof cover [27] by using the waterproof cover attachment bolts [26]. At this time align the cutout area on the side of the waterproof cover [27] with position of the brake release bolt [5]. Attach the waterproof cover [27] so that the gap (A) between its hole and the motor shaft [22] is nearly uniform.
- Clean the surface of the waterproof seal [24] to remove impurities.
- As shown in the construction diagram, install the waterproof seal [24] between the stationary core [1] and the waterproof cover [27]. Then attach the brake release [2]. Align the hole in the waterproof seal [24] for the brake release bolt with the position of the release bolt [5]. Next, attach the waterproof seal along the machined surfaces around the stationary core [1]. Be careful that the waterproof seal [24] does not meander. Otherwise water could leak in.)
- Turn the power on and off to check brake action.
- (12) Attach the V-ring [24]. Wipe off the lip and surface near the lip of the V-ring [25], lightly coat the lip surface with grease, and attach. Observe the attaching dimension (B = 6mm).
- Attach the fan [16], shaft-retaining C-ring [15] and cover [14].
- (14) Finally, attach the brake release bolt [5] and the manual release prevention spacer [4].

8. Daily Inspection and Maintenance B B



8-5 Removing and Installing One-Touch Release Lever (Optional)



Part Number	Part Name
1	Holder
2	Release lever
3	Release pin
4	Retaining ring
5	Brake release
6	Fan cover

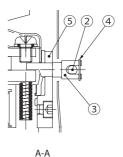


Figure 8-19

- Removing One-Touch Release Lever

- (1) Removing retaining ring [4] (E-retaining ring or shaft retaining C-ring) in 2 locations.
- (2) Remove release lever [2] from holder [1].
- (3) Expand release lever [2] to the outside from each side of the lever in turn, removing it from release pin [3]. (Do not expand the release lever overly).
- (4) Remove release pin [3].
- (5) Remove fan cover [6].

- Installing One-Touch Release Lever

- (1) Attach fan cover [6].
- (2) Insert release pin [3] into brake release [5] with preventing pin to drop.
- (3) Attach release lever [2] to U-hole of release pin [3] by extending release lever [2] to the outside from each side of the lever in turn.
- (4) Attach retaining ring [4].
- (5) Check that brake is released by pushing release lever [2].
- (6) Fix release lever [2] to holder [1].

8. Daily Inspection and Maintenance

8-6 Changing the Brake Lining

If the following conditions occur, ask the nearest authorized maintenance shop to exchange the brake linings with new ones.

(1) SB-004, FB-1D, FB-1E - FB-15E

When the thickness of brake lining reaches the use limit thickness in Table 8-3

(2) MB-003 - MB-005

When the gap reaches the limit (see P56, P65)

(3) FB-01A1 - FB-05A1

When the brake gap still reaches the limit after the gap adjustment (see P57, P66)

Table 8-3 Brake Lining Dimensions

Brake Type	Brake Lining	Original Thickness	Usable Thickness Limit
21. 27.	Dimension Drawing	₀ (mm)	₀ (mm)
SB-004	to	5.0	4.6
MB-003, MB-005 FB-01A1, FB-02A1 - FB-05A1	, to	7.0	-
FB-1D			6.0
FB-1E		8.8	7.8
FB-1HE, FB-2E	, , ,	9.0	8.0
FB-3E, FB-4E		10.4	8.4
FB-5E, FB-8E	to	10	6.0
FB-10E, FB-15E	ЦЦ	11	7.0

- Brake torque may not be at the prescribed level during initial operation. In such a case turn the brake on and off under as light load as possible to contact the brake's friction surfaces.
- When changing the brake lining, change the boss and leaf springs (for FB-5E- FB-15E, include the gap adjusting nuts) as a set.
- After 2 million or more cycles of operation, or after 10 years or more have passed since shipment from the factory, inspect to check whether continued operation is possible, even if the lining is more than the usable thickness limit.
- Check the following items concerning the condition of each mechanical part.
 - Is the lining material split or chipped?
 - Is there any peeling or gap between the lining material and the disc?
 - Does the brake lining spline unit exhibit any cracking, chipping, or stepped wear?
 - Is there any stepped wear on the surfaces around the stud bolts or armature plate?
- Change the brake lining, even if it has not reached the usable thickness limit in following cases. [1] 10 or more years have elapsed since the manufacturing date [2] the brake is used outdoors or in a highhumidity environment, [3] it is stored or rested for a long period of time.

8-7 Changing the V-Ring and Waterproof Seal (Outdoor Type)

V-rings and waterproof seals degrade over the years, losing their waterproofing abilities. As a guideline, contact the nearest authorized maintenance shop every 3 years. If the sliding surfaces of oil seals or Vrings show signs of wear or corrosion, replace them with new ones. Sliding surfaces are made of carbon steel, so rain water, condensation and other factors could cause rust to form and spread. Because this could lead to oil seal damage, take regular rust prevention measures.

8. Daily Inspection and Maintenance



8-8 Manually Releasing the Brake

To manually release the brake without turning on the brake, operate the brake release mechanism as shown below.

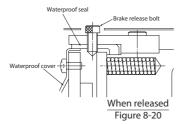
FB brake (FB-01A1 - FB-05A1 are optional)

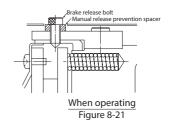
- (1) First remove the brake release bolts from the 2 opposing angles and remove the release prevention spacers. Reinsert the bolts and rotate it with a hexagonal wrench to release the brake. Be careful not to over rotate the brake release bolts. (Rotate the brake release bolts while checking to see if the brake is released. (See Figures 8-20, 8-21)
- (2) After releasing the brake, to return it to its original condition, for safety, return the manual release

prevention spacers that were removed in (1) to their original positions. (See Figure 8-21)

(3) This table shows brake release bolt sizes.

Brake Type	Bolt Size
FB-01A1 - FB-05A1, FB-1D	M5
FB-1E - FB-2E	M6
FB-3E, FB-4E	M8
FB-5E - FB-15E	M10





Note: Indoor types do not come with waterproof seals or waterproof covers.

■ One-Touch Release Lever Type (Optional)

- All you need to do to release the brake is push the release lever over. (See Figure 8-22)
- (1) To release the brake, pull the release lever out of the holder, and push it toward the load or anti-load side. (Some specifications do not allow pushing the release lever toward the load side.)

 Be careful not to push the lever too far. Pushing the lever too far could damage the brake. (Push the release lever while checking to see if the brake is released.)
- (2) When operating the motor, make certain to return the lever to its original position and set it inside the holder. Start operation after confirming that the brake operates properly.

Note: The brake is released while the lever is tilted by a hand, and it works when the lever is released the hold.

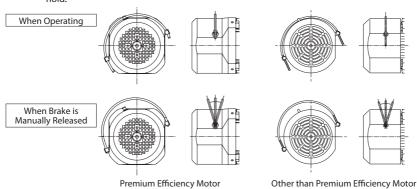


Figure 8-22

Common 9. Troubleshooting

If any abnormal condition occurs, refer to Table 9-1, 9-2 and promptly take appropriate measures. If these actions do not correct the issue, immediately contact the nearest authorized maintenance shop.

Table 9-1 Troubleshooting

		Problem	Cause	Correction	
			Power failure	Contact the electric power company.	
			Defective electric circuit	Check the circuit.	
			Blown fuse	Replace the fuse.	
			Protective device is engaged	Fix the problem and recover.	
			Load locking	Check the load and safety device.	
			Poor switch contact	Adjust the contact unit.	
			Motor stator coil disconnect	Consult with authorized maintenance shop.	
			Bearing damage	Consult with authorized maintenance shop.	
		or will not operate o load	Defective governor switch (0.1 - 0.4kW single phase motor)	Consult with authorized maintenance shop.	
			Damaged capacitor (single phase motor)	Consult with authorized maintenance shop.	
			3-phase is functioning as single- phase	Check the power supply with a voltmeter. Check the motor, transformer coil, contactor, fuse, etc. and repair or replace them.	
			Friction surface of brake is corroded	Request brake cleaning from an authorized maintenance shop.	
-			Incorrect brake gap adjustment	Re-adjust brake gap. (Se P55 - 72.)	
load	d but	or rotates without a the slow speed shaft t rotate.	Damage to gear unit due to overloading of gears, etc.	Consult with authorized maintenance shop.	
		The switch overheats	Insufficient switch capacity	Replace with specified fuse.	
			Overload	Decrease the load to the specified value.	
		Fuse tripping	Insufficient fuse capacity	Replace with specified fuse.	
The	8		Overload	Decrease the load to the specified value.	
The slow speed shaft turns with no load	When a load is applied		Defective governor switch (0.1 - 0.4kW single phase motor)	Consult with authorized maintenance shop.	
spe	load	The area of will	Voltage drop	Contact the electric power company.	
ed s	is.	The speed will not increase	Overload	Decrease the load to the specified value.	
shaft t	applie	and the motor is overheating.	Lowered capacitor capacity range (single phase motor)	Consult with authorized maintenance shop.	
urn	۵		Short-circuited motor stator coil	Consult with authorized maintenance shop.	
₹.			The key is not inserted	Insert key.	
±,		It stops.	Bearing burnout	Consult with authorized maintenance shop.	
10			Poor adjustment of protection device	Adjust the protection device.	
oad		motor runs in the erse direction.	Wiring error	Change the connection.	
	Euc	o trippina	The lead wire is short circuited.	Consult with authorized maintenance shop.	
	ruse	e tripping	Poor contact between motor and starter	Make good connection.	
			Overload	Decrease the load to the specified value.	
			Voltage drop or rise	Contact the electric power company.	
			Defective governor switch (0.1 - 0.4kW single phase motor)	Consult with authorized maintenance shop.	
Exc	essive	e temperature rise	Lowered capacity range of a capacitor for operation (single phase motor)	Consult with authorized maintenance shop.	
			The ambient temperature is high	Improve the ventilation method.	
			Damaged bearing	Consult with authorized maintenance shop.	
			Abnormal wear of reducer parts due to overload. etc.	Consult with authorized maintenance shop.	

9. Troubleshooting Common

Table 9-2 Troubleshooting

Table	e 9-2 Troubleshooting Problem	Cause	Correction	
	Oil and fat blot or drip from			
Grease leaks	the seal section of input / output shaft.	Grease applied to the oil seal seeps out at first.	Wipe off around the oil seal, and observe.	
	Leakage of grease from input/ output shaft section	Damaged oil seal or damaged shaft (or collar)	Consult with authorized maintenance shop.	
aks	Leakage of grease from the contact surfaces of casing, etc.	Loose fastener bolts	Tighten fastener bolts correctly.	
	Leakage of grease into motor	Oil seal damage	Consult with authorized maintenance shop.	
		Dust and foreign matter in bearings, or damaged bearings		
		Reducer parts grinding foreign matter	Consult with authorized maintenance shop.	
		Reducer parts are damaged	Consult with authorized maintenance shop.	
	ormal sound	Warping of casing due to uneven installation surface	Make the installation base flat or make adjustment by using liners, etc.	
Exce	essive vibration	Resonance due to insufficient rigidity of the installation base	Reinforce the installation base to increase rigidity.	
		Nonalignment of the center of axle with driven machine	Align the center of axle.	
		Transmission of vibration from the driven machine	Individually operate the product to check the source of the sound.	
		Foreign objects have entered	Consult with authorized maintenance shop.	
		Bearing damage	Consult with authorized maintenance shop.	
		Improper brake gap adjustment	Adjust the brake gap. (See P55 - 72.)	
A I	and a standard	Brake lining wear	Request brake lining replacement from an authorized maintenance shop.	
Abn	ormal motor sounds	Brake unit electromagnetic coil burnout	Consult with authorized maintenance shop.	
		Rectifier damage	Consult with authorized maintenance shop.	
		A leaf spring in the brake boss unit has come off or is damaged	Consult with authorized maintenance shop.	
		Defective governor switch (0.1 - 0.4kW single phase motor)	Consult with authorized maintenance shop.	
	Does not activate	Forgot to restore the brake release bolt to its original position	Restore the release bolt.	
	Does not activate	Improper adjustment after disassembly	Request authorized maintenance shop to re-adjust.	
Bral		Not using the quick-braking circuit	Change to quick-braking circuit. (See P31 - 45.)	
e is ir		Foreign objects in brake lining unit, oil adhesion	Request cleaning from authorized maintenance shop.	
Brake is ineffective	Slips (Braking takes a long time)	Brake lining wear	Adjust the brake gap. Request brake lining replacement from an authorized maintenance shop.	
e e	(Statuting takes a foring time)	Brake gap not uniform	Adjust the brake gap.	
		Overload	Decrease the load to the specified value.	
		Brake release bolt not sufficiently restored	Restore the release bolt.	
	Overcurrent shut-off	Sudden speed changes	Increase the time for speed changes.	
₹		Extreme load fluctuation	Decrease load fluctuation.	
Inverter Tripping	Overcurrent due to ground fault	Ground fault on output side	Take measures to prevent ground fault.	
	Direct current overcurrent	Short on output side	Take measures to prevent short. Inspect wiring.	
pping	Regenerative overvoltage shut-off	Sudden speed reduction	Increase the time for speed reduction. Decrease brake frequency.	
_	Thermal operation	Overload Decrease the load to the spe value.		

10. Construction Drawings

10-1 Construction Drawings (90W or Less)

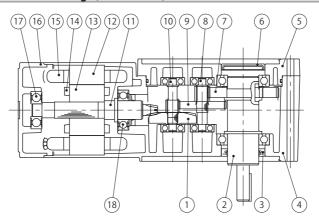


Figure 10-1 RNFM Type (E.g.: RNFM0025-03L-240)

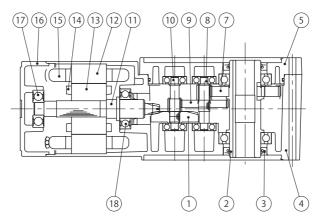


Figure 10-2 RNFM Type (E.g.: RNYM0025-03-240)

Table 10-1 Gearmotor, Principal Parts

Part Number	Part Name	Part Number	Part Name	Part Number	Part Name
1	HYPOID gear	7	Gear	13	Rotor core
2	Output shaft	8	Pinion shaft	14	Rotor conductor
3	Oil seal	9	Gear	15	Stationary coil
4	Casing	10	Pinion shaft	16	Anti-load side cover
5	Cover	11	HYPOID pinion shaft	17	Bearing
6	Seal cap	12	Stationary core	18	Bearing



10-2 Construction Drawings (0.1kW or More)

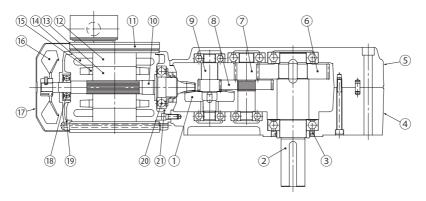


Figure 10-3 RNFM Type (E.g.: RNFM08-50R-120)

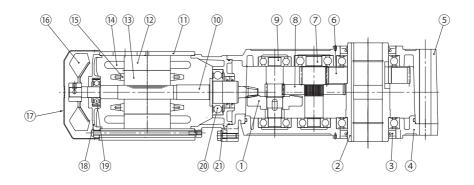


Figure 10-4 RNFM Type (E.g.: RNYM08-1530-120)

Table 10-2 Gearmotor, Principal Parts

Part Number	Part Name	Part Number	Part Name	Part Number	Part Name
1	HYPOID gear	8	Gear	15	Rotor conductor
2	Output shaft	9	Pinion shaft	16	Fan
3	Oil seal	10	HYPOID pinion shaft	17	Fan cover
4	Case (1)	11	Motor frame	18	Anti-load side cover
5	Case (2)	12	Stationary core	19	Bearing
6	Gear	13	Rotor core	20	Bearing
7	Pinion shaft	14	Stationary coil	21	Motor flange bracket

MEMO



Application Product

HYPONIC Gearmotor® HYPONIC Gearmotor® with Current Limiter

This manual covers the current limiter (current-sensing overload detection device) unit. For information on handling the reducer unit and the motor unit see P1-79.

Contents

11. Specification/Installation	82
12. Wiring	83
13. Setting	84
14. Operation	85





↑ CAUTION

- Do not use in a place where it will be directly exposed to cutting fluid when used to drive a chip conveyor.
- Do not use in an enclosed environment. The ambient temperature may exceed the allowable range, which may adversely affect electrical components.

11-1 Specification

Table 11-1 Current Limiter (Current-sensing Overload Detection Device) Specification

Applicable motor capacity		Three-phase motor 0.1kW	Three-phase motor 0.2kW	
Devices Courses		Commercial power supply 200V 50/60Hz, 220V 60Hz		
Power Source		(inverter operation not possible)		
0 1 15:	Default Setting *1	0.6A±0.05A	1.1A±0.09A	
Overload Detection Current	Setting Range *2	0.3~0.7A	0.6~1.4A	
Current	Current Accuracy *1	±0.05A to the setting scale	±0.09A to the setting scale	
Start-up Non-detection Time		2s (fixed, tolerance 2.0 to 2.5s)		
Overload Detection Time		0.3s (fixed, tolerance 0.2 to 0.3s)		
	Shut-off Method Motor current (2-phase shut-off of U-	Motor current self-shut-off		
C-5		(2-phase shut-off of U-phase and W-phase)		
Safeguard	Activation	0.3~0.7A ±0.05A to the setting scale 2s (fixed, tole) 0.3s (fixed, tole) Motor curre (2-phase shut-off of Self-maintain Power is turned on again a	s shut-off status	
	Reset	Power is turned on again after power off (1 s or longer)		
Overload Detection Signal Output Terminal (3-terminal Block)	Туре	Dry 1c contact, overload activation		
	Minimum applicable load *3	DC5V 10mA		
	Rated load	AC250V 3A, DC30V 3A		

^{* &}lt;sup>1</sup> Please check with the actual device since current value errors may occur in relation to the setting scale due to fluctuations in power supply voltage, etc.

11-2 Installation Location

Ambient temperature: 0~40°C

Ambient humidity: 45 to 85%RH with no condensation

Altitude: Maximum 1000m

Atmosphere: No corrosive or volatile gases, no steam

Dust-free, well-ventilated area.

Installation location: Indoors (area with minimal dust, no contact with water), not in an enclosed environ-

ment.

Vibration: Maximum 4.9m/s²

- Installation conditions are different from those of the HYPONIC Gearmotor without current limiter.

- Mount in a location that enables easy operation, such as inspection and maintenance.

- Mount on a sufficiently rigid base.

^{* &}lt;sup>2</sup>The current setting range is the guaranteed range that can be set and does not indicate the upper or lower limit of the current value setting volume.

^{* &}lt;sup>3</sup> When the relay output from the overload detection signal output terminal is input directly to a programmable logic controller (PLC), the relay output should be set to a value of 0.5 to 1.0V. When the relay output is input directly to a programmable logic controller (PLC), the use of a relay for low current is recommended to prevent contact failure of the relay contact.

HYPONIC Gearmotor with Current Limiter



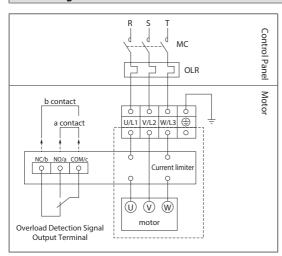
⚠ DANGER

Make sure to securely install terminal box screws and rubber plugs for unused cable entry holes so
that they do not loosen. When used to drive a chip conveyor, cutting fluid may become mist and
enter the terminal box, adversely affecting electrical components.

CAUTION

- Do not open the cover of the terminal box during operation. Doing so may cause an electric shock.
- Do not operate the terminal box with the cover removed. After operation, install the cover of the terminal box back to its original position; otherwise, electric shock may result.
- Do not leave unnecessary screws in the terminal box; otherwise, a short circuit may result.
- Since the current limiter alone may not protect the mating machine, an overload protection device or thermal relay should be installed.
- When removing the cause of the overload, be sure to shut-off the power supply. After the overload
 detection function of the current limiter is activated, the motor will remain stopped, but it may
 automatically resume immediately due to a malfunction caused by momentary power failure or
 noise. The motor may restart, which may result in injury.
- Never drive the inverter. The current limiter will be damaged by voltage including harmonics.
- When connecting to the power supply that contains harmonics or much noise, implement noise countermeasures for the power supply.

12-1 Wiring



MC: Electromagnetic contactor

OLR: Overload protection device or electronic thermal relay

Customer to prepare.

- part is pre-wired at the factory.
- The overload detection signal output terminal is a relay output (dry contact) when the current limiter is activated.

Use for warning indication, etc.

HYPONIC Gearmotor with Current Limiter

A CAUTION

- Do not operate the current setting volume during operation; otherwise, electric shock may result.
- The overload detection current value should be set below the current value at output torque.
 If the value is set higher than the current value at output torque, the overload detection cannot be performed and the gear may be damaged or the motor may burn out.
- When adjusting, do not push the current value setting volume too hard; otherwise, the current value setting dial may be damaged.
- Please check with the actual device to avoid errors in the current value relative to the setting scale due to fluctuations in power supply voltage and other factors.
- When connecting to a power source that contains a lot of harmonics or noise, implement noise suppression measures for the power source.

13-1 Setting

Table 13-1 Factory-set Current Value

Motor Capacity	Factory-set Current Value		
0.1kW	0.6A		
0.2kW	1.1A		

- The factory default setting is the current value shown in Table 13-1 as a provisional value. Be sure to reset it to the rated current value of the power supply to be used or lower.
- For torque-limited models, set the current value to less than the current value at output torque.
- The current value setting dial can be adjusted using a precision flat-blade screwdriver.
- When the overload detection function of the current limiter is activated, the ALARM LED lights up.

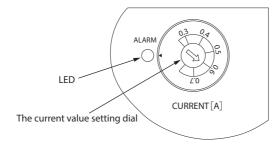


Figure 13-1 The current value setting dial (Ex: 0.1kW)



14-1 Current limiter activation and reset

(1) At Starting

Immediately after starting (during the no detection time at starting), the current limiter is not activated by the starting current of the motor. Overload detection is not performed.

(2) Overload Occurrence

If a current value exceeding the overload detection current setting is detected for more than the overload detection time, a protection function is activated and the motor stops.

When the protection function is activated, the motor current is interrupted and remains stopped even if power is supplied between U and W of the current limiter.

(3) Removing the cause of overload

When removing the cause of overload, be sure to shut off the power supply (turn off MC).

After the overload detection function of the current limiter is activated, the motor will remain stopped: however, a malfunction due to momentary power failure or noise may cause the motor to automatic return immediately.

(4) Reset

After removing the cause of the overload, the motor restarts when the power is turned back on (MC is turned ON).

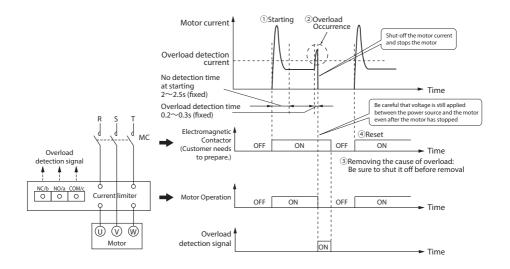


Figure 14-1 Current Limiter Operation Status

The scope of our warranty for our products is limited to the range of our manufacture. Warranty (period and contents)

Warranty Period	The warranty period for the Products shall be earlier, 18 months after the shipment of the Products from the seller's works factory, or 12 months after starting operation, whichever is first.				
Description	If the product failed within the warranty period, during which despite a proper mounting, connection and maintenance & administration are followed according to the maintenance manual, and the product is properly run based on the specification on the catalog or under conditions agreed separately, we will repair or provide an alternative product at our discretion for free of charge, except the exclusions below. However, as far as the product is connected with customers' other devices, we will not indemnify those expenses on dismounting from/mounting on the devices, etc. and other associated construction expenses, transportation expenses and opportunity loss and operation loss the customers suffered from, and other indirect damages.				
Exclusion from the Warranty	 The following items will be excluded from the warranty: A breakdown resulting from defects in the mounting of the product and connection with other devices, etc. A breakdown resulting from insufficient maintenance & administration and improper handling of the product, including a case that the product is not stored according to our defined storage manual. A breakdown resulting from operation which does not fall within our specification and other operation conditions and use status we hardly can know or a failure caused by the use of lubricant which we do not recommended. A breakdown resulting from defects in or special specification of devices, etc. connected by customers. A breakdown resulting from disassembly, parts replacement, and modification conducted by the customer (excluding disassembly for inspection and adjustment of the brake gap, for manual release of the brake, and for other purposes guided in the maintenance manual). A breakdown resulting from defects in parts supplied or specified by customers. A breakdown caused by inevitable force including earthquake, fire, flood disaster, salt damage, gas damage, and lightning strike, etc. Natural wear and tear, abrasion, and deterioration of such relevant consumable parts as a bearing and oil seal, etc. under normal usage. A breakdown caused for reasons not attributable to each of the above item. 				

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Specifications, dimensions, and other items are subject to change without prior notice.



Sumitomo Heavy Industries, Ltd.